



MOSEK Optimization Server

*Release 8.1.0.73*

MOSEK ApS

2019



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## INTRODUCTION

The **MOSEK** Optimization Suite 8.1.0.73 is a powerful software package capable of solving large-scale optimization problems of the following kind:

- linear,
- conic quadratic (also known as second-order cone),
- convex quadratic,
- semidefinite,
- and general convex.

Integer constrained variables are supported for all problem classes except for semidefinite and general convex problems. In order to obtain an overview of features in the **MOSEK** Optimization Suite consult the [product introduction](#) guide.

The most widespread class of optimization problems is *linear optimization problems*, where all relations are linear. The tremendous success of both applications and theory of linear optimization can be ascribed to the following factors:

- The required data are simple, i.e. just matrices and vectors.
- Convexity is guaranteed since the problem is convex by construction.
- Linear functions are trivially differentiable.
- There exist very efficient algorithms and software for solving linear problems.
- Duality properties for linear optimization are nice and simple.

Even if the linear optimization model is only an approximation to the true problem at hand, the advantages of linear optimization may outweigh the disadvantages. In some cases, however, the problem formulation is inherently nonlinear and a linear approximation is either intractable or inadequate. *Conic optimization* has proved to be a very expressive and powerful way to introduce nonlinearities, while preserving all the nice properties of linear optimization listed above.

The fundamental expression in linear optimization is a linear expression of the form

$$Ax - b \in \mathcal{K}$$

where  $\mathcal{K} = \{y : y \geq 0\}$ , i.e.,

$$\begin{aligned} Ax - b &= y, \\ y &\in \mathcal{K}. \end{aligned}$$

In conic optimization a wider class of convex sets  $\mathcal{K}$  is allowed, for example in 3 dimensions  $\mathcal{K}$  may correspond to an ice cream cone. The conic optimizer in **MOSEK** supports three structurally different types of cones  $\mathcal{K}$ , which allows a surprisingly large number of nonlinear relations to be modelled (as described in the [MOSEK modeling cookbook](#)), while preserving the nice algorithmic and theoretical properties of linear optimization.

## 1.1 Why the Optimization Server?

The **MOSEK** OptServer is a simple solver service. It can receive tasks over HTTP or HTTPS and return solutions, log and other information. It can be used either in

- *completely open mode*, where no authentication is required,
- *closed mode*, where authentication is required, or
- *semi-open mode*, where authentication is required for administrative tasks, but optimizer tasks can be submitted anonymously.

The OptServer provides an API for submitting tasks and retrieving information. It makes it easy to offload heavy computations to a remote machine. This is useful for running **MOSEK** on a wider range of devices.

## CONTACT INFORMATION

|                 |  |  |
|-----------------|--|--|
| Phone           | +45 7174 9373  |  |
| Website         | <a href="http://mosek.com">mosek.com</a>                 |  |
| Email           |  |  |
|                 | <a href="mailto:sales@mosek.com">sales@mosek.com</a>     | Sales, pricing, and licensing                |
|                 | <a href="mailto:support@mosek.com">support@mosek.com</a> | Technical support, questions and bug reports |
|                 | <a href="mailto:info@mosek.com">info@mosek.com</a>       | Everything else.                             |
| Mailing Address |  |  |
|                 | MOSEK ApS  |  |
|                 | Fruebjergvej 3   |  |
|                 | Symbion Science Park, Box 16                             |  |
|                 | 2100 Copenhagen O  |  |
|                 | Denmark  |  |

You can get in touch with **MOSEK** using popular social media as well:

|                     |   |
|---------------------|---|
| <b>Blogger</b>      | <a href="http://blog.mosek.com/">http://blog.mosek.com/</a>   |
| <b>Google Group</b> | <a href="https://groups.google.com/forum/#!forum/mosek">https://groups.google.com/forum/#!forum/mosek</a> |
| <b>Twitter</b>      | <a href="https://twitter.com/mosektw">https://twitter.com/mosektw</a>                                     |
| <b>Google+</b>      | <a href="https://plus.google.com/+Mosek/posts">https://plus.google.com/+Mosek/posts</a>                   |
| <b>Linkedin</b>     | <a href="https://www.linkedin.com/company/mosek-aps">https://www.linkedin.com/company/mosek-aps</a>       |

In particular **Twitter** is used for news, updates and release announcements.



## LICENSE AGREEMENT

Before using the **MOSEK** software, please read the license agreement available in the distribution at <MSKHOME>/mosek/8/mosek-eula.pdf or on the **MOSEK** website <https://mosek.com/products/license-agreement>.

**MOSEK** uses some third-party open-source libraries. Their license details follows.

### *zlib*

**MOSEK** includes the *zlib* library obtained from the *zlib* website. The license agreement for *zlib* is shown in Listing 3.1.

Listing 3.1: *zlib* license.

```
zlib.h -- interface of the 'zlib' general purpose compression library
version 1.2.7, May 2nd, 2012

Copyright (C) 1995-2012 Jean-loup Gailly and Mark Adler

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   claim that you wrote the original software. If you use this software
   in a product, an acknowledgment in the product documentation would be
   appreciated but is not required.
2. Altered source versions must be plainly marked as such, and must not be
   misrepresented as being the original software.
3. This notice may not be removed or altered from any source distribution.

Jean-loup Gailly          Mark Adler
jloup@gzip.org            madler@alumni.caltech.edu
```

### *fplib*

**MOSEK** includes the floating point formatting library developed by David M. Gay obtained from the *netlib* website. The license agreement for *fplib* is shown in Listing 3.2.

Listing 3.2: *fplib* license.

```
/*
*****
*
*/
```

```
* The author of this software is David M. Gay.
*
* Copyright (c) 1991, 2000, 2001 by Lucent Technologies.
*
* Permission to use, copy, modify, and distribute this software for any
* purpose without fee is hereby granted, provided that this entire notice
* is included in all copies of any software which is or includes a copy
* or modification of this software and in all copies of the supporting
* documentation for such software.
*
* THIS SOFTWARE IS BEING PROVIDED "AS IS", WITHOUT ANY EXPRESS OR IMPLIED
* WARRANTY.  IN PARTICULAR, NEITHER THE AUTHOR NOR LUCENT MAKES ANY
* REPRESENTATION OR WARRANTY OF ANY KIND CONCERNING THE MERCHANTABILITY
* OF THIS SOFTWARE OR ITS FITNESS FOR ANY PARTICULAR PURPOSE.
*
*****/
```

## INSTALLATION

### 4.1 What's in the box

The **MOSEK** OptServer is shipped as part of the **MOSEK** Optimization Suite. It is located in the folder *MSKHOME/mosek/8/opt-server*, where *MSKHOME* is the folder **MOSEK** has been installed in.

The OptServer files are organized in the following folders:

- **bin** – It contains the executables. i.e.
  - *MosekServer*, see [Sec. 4.4](#).
  - *install\_MosekServer*, see [Sec. 4.1](#).
- **var** – It contains the working directories and the GUI elements:
- **etc** – It contains default configuration file and security key.

### 4.2 Requirements

OptServer only requires Python 3+ to run the configuration script. It has been tested only on Linux 64 bit.

### 4.3 Installation

To install the OptServer you need to execute the *install\_MosekServer* located in the *MSKDIR/opt-server/* folder. A set of options can be provided to customize the installation:

```
--inplace
    Set up the server to run directly in the unpacked distro directory

--user
    Install in ~/.local

--global
    Install in /usr

--prefix DIR
    Install in DIR

--certdir DIR
    This directory contains valid cert.pem and key.pem for HTTPS. If DIR='', then HTTPS is disabled.

--password PWD
    Password for initial user admin

--port PORT
    Configure server to listen to port PORT
```

`--disable-gui`  
Disable GUI and API

`--enable-get`  
Enable fetching submitted data/problem files

`--enable-anonymous`  
Enable submitting without credentials

If the installation succeeds, you can then run the OptServer as described in [Sec. 4.4](#).

## 4.4 Running the Server

The OptServer can be started by running the executable `MosekServer` from the `OPT_SERVER_HOME/bin` folder, for instance

```
$ $OPT_SERVER_HOME/bin/MosekServer
```

With no command line the server runs using the configurations setup during the installation process, see [Sec. 4.1](#). To override the configuration set in the installation, several options can be passed to the server.

---

**Note:** Options can be prefixed by a single or a double dash, i.e. either `-` or `--`.

---

Some examples follow.

### Switching debug mode on

If the server is not working as expected, it may be useful to turn on debugging:

```
MosekServer -debug=true
```

### Change the port

Changing the port is a pretty standard step.

```
MosekServer --port=30080
```

## 4.5 OptServer Options

The complete list of options follow.

`-base={/var/Mosek/server}`  
Base directory

`-certdir=/etc/Mosek/server/cert`  
Enable SSL, `cert.pem` and `key.pem` in this directory

`-cmd=$basedir/script/solve.py $workdir $task`  
Solver command

`-config=/etc/Mosek/server.conf`  
Specify configuration file (JSON)

`-debug=false`  
Turn on debugging info (turned off by default). This is a boolean option.

`-enable-anonymous-submit=false`  
Enable anonymous submitting (turned off by default).

`-enable-get-problem=false`  
Enable fetching submitted tasks (turned off by default).

`-enable-user-api=false`  
Enable extended programming API

`-enable-user-gui=false`  
Enable user interface (turned off by default).

`-hostname=hostname`  
Server host name

`-logfile=filename`  
Log file name

`-login-expiry=86400`  
Login expiry time in seconds

`-port=30080`  
Port to listen to

`-staticdir=extern`  
Directory with files served under `/static/`



## OVERVIEW

In this section an overview of the basic concepts about the OptServer is given.

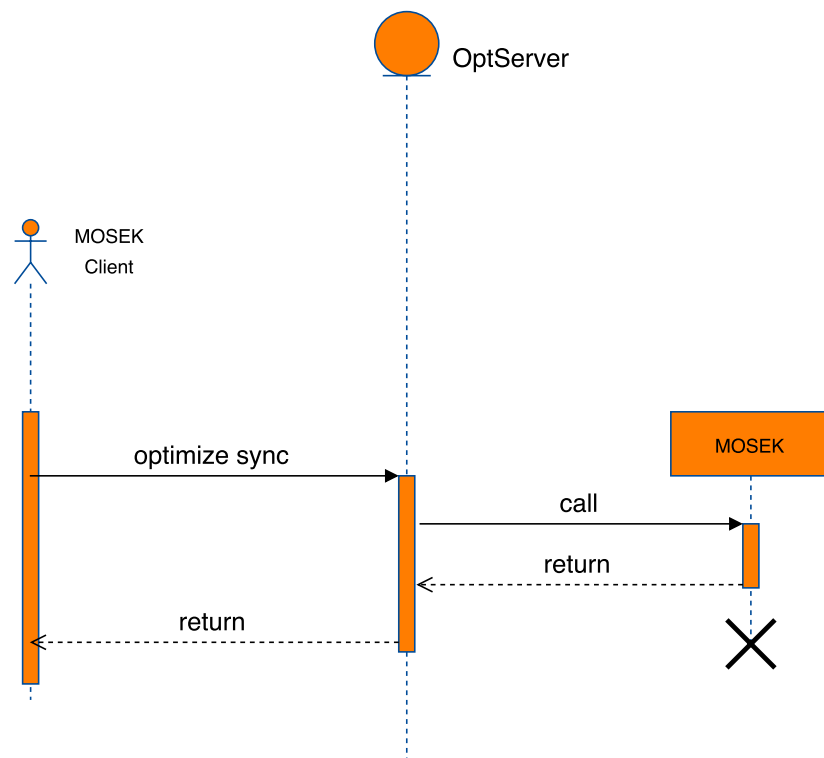
- *Synchronous Job submission*
- *Asynchronous Job submission*

### 5.1 Synchronous Optimization

The easiest way to submit optimization problem to the OptServer is in *synchronous mode*:

1. A submission request is sent over the OptServer and the problem is transferred.
2. The submitter is put on hold.
3. The OptServer runs the optimizer and wait for the results.
4. When the optimizer terminates the OptServer collects the outcome and passes over the client.
5. The client receives the solution and get back control.

The process can be represented as in Fig. 5.1.



The workflow is simple and effective for problems that does not take long to solve, or at least in all settings in which the client can wait for the job to complete.

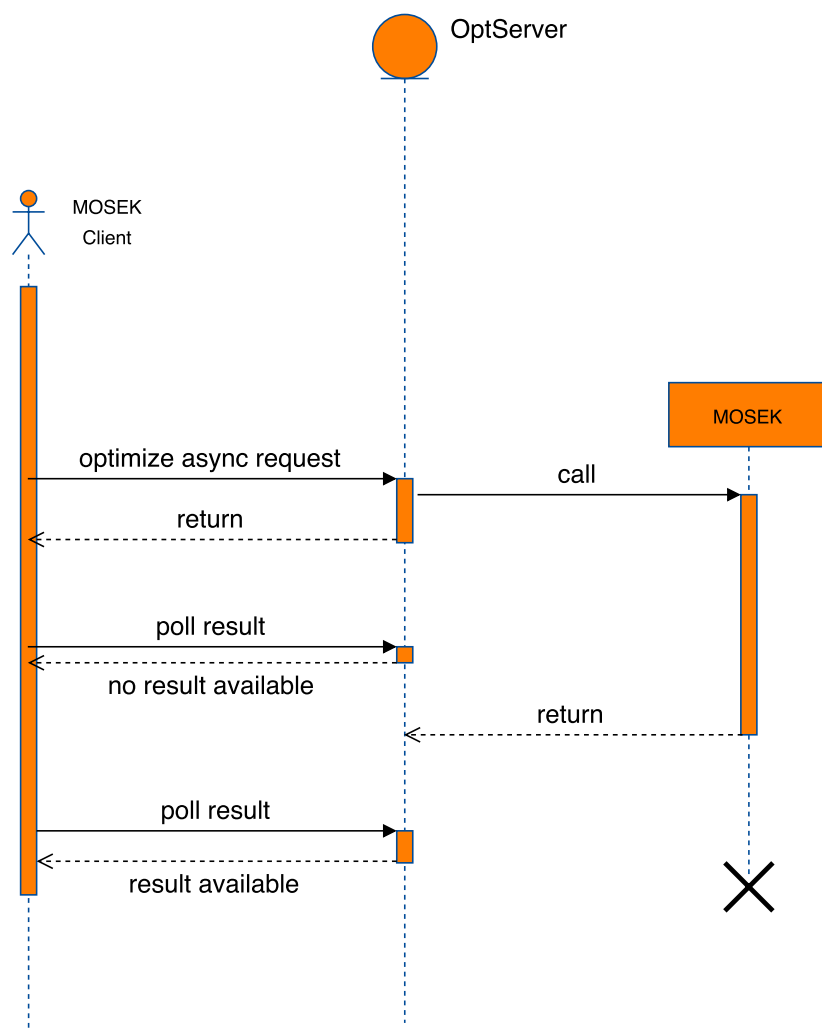
**Warning:** If the connection between the client and the OptServer is lost, the job result can only be recovered by manually accessing the job workspace on the server.

## 5.2 Asynchronous Optimization

The OptServer accepts jobs in *asynchronous mode*, i.e. once the job request is accepted, the client get control back and the server proceed with the optimization. The client can query the OptServer for the status of the job and in case retrieve the solution, if any. The steps can be summarized as:

1. A submission request is sent over the OptServer and the problem is transferred.
2. The submitter regain control and can continue its execution flow.
3. The client can query the OptServer at any time about the job status and solution availability.
4. The OptServer runs the optimizer and wait for the results.
5. When the optimizer terminates the OptServer collects the outcome.

The process can be represented as in Fig. 5.2.



*Asynchronous mode* is particularly suitable when

- a job is expected to run for long time,
- one must submit a set of small jobs that can run in parallel or
- the submitter is a short-lived process, such as a *docker instance*.

|   |
|---|
| <p><b>Warning:</b> The OptServer does not implement any queing strategy, so a job is executed as it is submitted.</p> |
|---|



## GUIDELINES

### 6.1 Known Limitations

The main limitation in the use of the **MOSEK** Optimization Server 8.1.0.73 are reported in this section.

#### Platforms

Currently the **MOSEK** OptServer has been only tested on Linux 64bit machines.

#### Compatibility

Job submission using **MOSEK** API is only available starting from **MOSEK** 8.

Submitting jobs directly using HTTP commands is possible as long as the file format is accepted. However, it must be noticed that the compatibility does not depend on the OptServer but on the underlying **MOSEK** solver available on server machine.

### 6.2 Resources and performance

OptServer is a very lightweight server and requires very limited resources both in terms of memory and CPU.

#### CPU/Memory

The use of CPU/memory resources by OptServer should be negligible.

#### Network

Most of the network load is due to the transfer of the optimization problem from the client to the server. That happens in a single burst. Therefore

- For long running jobs the transfer time is typically negligible,
- For easy to solve problems the transfer time may be more significant.

---

**Hint:** The same problem can result in file of different sizes depending on the chosen format.

---

However, OptServer has not been designed for time critical production environment.

## Disk usage

Each job is stored on disk along with log and solutions. The reasons are:

1. avoid to keep jobs in memory while the solver is running,
2. in case of crash, information can be recovered from the disk,
3. solution and result can be recovered asynchronously reading from disk.

Therefore a suitable amount of free space must be available.

The folder used to store jobs information is under the *basedir* folder, that can be set in the configuration file.

---

**Note:** OptServer does not delete data for completed jobs. Users of cloud services should take some care in case they pay storage fees.

---

## TUTORIALS

This section contains tutorials that illustrate how communicate with the **MOSEK** OptServer in order to

- offload optimization problem from the client to the server and
- retrieve the solution and the solver log.

The tutorials are implemented using the Python 3 programming language. The reason for this choice is that Python provides an easy-to-use HTTP client and allows for a simple and compact code.

- *Submission and solution in synchronous mode*
- *Submission and solution in asynchronous mode*
- *Submission and solution using Condor*

### 7.1 Synchronous Problem Submission

This tutorial shows how to

- submit a job to the OptServer,
- remotely run **MOSEK** and wait for the optimization to terminate and
- retrieve the solution and log.

The optimization problem is assumed to be stored in a file using one of the available *file formats*.

The connection is managed using the `http` Python module, and it is assumed to be established successfully: as a result, an object `con` is available to manage the connection.

First of all, the problem is submitted to the OptServer by a *submit* command

Listing 7.1: How to submit a job to the OptServer.

```
con.request("POST", '/submit', dataf)
resp = con.getresponse()
```

If no errors have occurred, a request for running the optimizer can be sent

Listing 7.2: How to run an optimization job with OptServer.

```
con.request("GET", "/solve?token="+token)
resp = con.getresponse()
```

At this point the request will return when the optimization terminates. If no errors have happened, the results are already available

Listing 7.3: How to get the results.

```
res = resp.getheader('X-Mosek-Res-Code',None)
trm = resp.getheader('X-Mosek-Trm-Code',None)

print("\tMOSEK response: %s" % res)
print("\t\ttrm resp: %s" % trm)
if resp.status == http.client.OK:
    print("Solution:")
    print(resp.read().decode('ascii',errors='ignore'))
```

The log is readily available as well

Listing 7.4: How to retrieve the log for a job on OptServer.

```
con.request("GET", "/log?token="+token)
resp = con.getresponse()
```

The whole example is in [Listing 7.5](#).

Listing 7.5: How to submit a job and solve the problem synchronously.

```
import http.client
import sys

def check_status(resp):

    print("\tHTTPResponse: %s / %s" % (resp.status,resp.reason))
    for k,v in resp.getheaders():
        print("\t%s: %s" % (k,v))

    if resp.status not in [http.client.OK, http.client.NO_CONTENT]:
        print("An error occurred!")
        sys.exit(1)

if __name__ == '__main__':
    host = sys.argv[1]
    port = int(sys.argv[2])
    probfile = sys.argv[3]

    con = http.client.HTTPConnection(host,port)
    try:
        with open(probfile,'rb') as dataf:
            ## Submit job
            print("POST /submit")

            con.request("POST", '/submit', dataf)
            resp = con.getresponse()
            check_status(resp)

            token = resp.read().decode('ascii')

            ## Solve and wait for solution
            print("GET /solve")
            con.request("GET", "/solve?token="+token)
            resp = con.getresponse()
            check_status(resp)
            res = resp.getheader('X-Mosek-Res-Code',None)
            trm = resp.getheader('X-Mosek-Trm-Code',None)
```

```

print("\tMOSEK response: %s" % res)
print("\t\t\t\t\ttrm resp: %s" % trm)
if resp.status == http.client.OK:
    print("Solution:")
    print(resp.read().decode('ascii',errors='ignore'))
print("GET /log")

con.request("GET", "/log?token="+token)
resp = con.getresponse()

check_status(resp)

if resp.status == http.client.OK:
    print(resp.read().decode('utf-8',errors='ignore'))
finally:
    con.close()

```

## 7.2 Asynchronous Problem Submission

This tutorial shows how to

- submit a job to the OptServer,
- start the optimization job running **MOSEK** on server side,
- closing the connection to the server and
- connect again and retrieve the solution and log.

The optimization problem is assumed to be stored in a file using one of the available *file formats*. The connection is managed using `http` Python module, and it is assumed to be established successfully.

First of all, the problem is submitted to the OptServer by a `POST` operation

Listing 7.6: How to submit a job to the OptServer.

```

con.request("POST", '/submit', dataf)
resp = con.getresponse()

```

Note that this operation is identical to the *synchronous case*.

If no errors have occurred, a request for running the optimizer can be sent

Listing 7.7: How to run an optimization job with OptServer.

```

con.request("GET", "/solve-background?token="+token)
resp = con.getresponse()

```

The program regains control immediately. The connection is then closed and reopened, to make sure client and server are working asynchronously.

If no errors have happened, the results can be retrieved

Listing 7.8: How to get the results.

```

con.request("GET", "/solution?token="+token)
resp = con.getresponse()

check_status(resp)

res = resp.getheader('X-Mosek-Res-Code',None)
trm = resp.getheader('X-Mosek-Trm-Code',None)

```

```
print("\tMOSEK response: %s" % res)
print("\t\t\ttrm resp: %s" % trm)
if resp.status == http.client.OK:
    print("Solution:")
    print(resp.read().decode('ascii',errors='ignore'))
```

The log is readily available as well

Listing 7.9: How to retrieve the log for a job on OptServer.

```
con.request("GET", "/log?token="+token)
resp = con.getresponse()

if resp.status == http.client.OK:
    print(resp.read().decode('utf-8',errors='ignore'))
```

The whole example is in Listing 7.10.

Listing 7.10: How to submit a job and solve the problem asynchronously.

```
import http.client
import sys

def check_status(resp):

    print("\tHTTPResponse: %s / %s" % (resp.status,resp.reason))
    for k,v in resp.getheaders():
        print("\t%s: %s" % (k,v))

    if resp.status not in [http.client.OK, http.client.NO_CONTENT]:
        print("An error occurred!")
        sys.exit(1)

if __name__ == '__main__':
    host = sys.argv[1]
    port = int(sys.argv[2])

    probfile = sys.argv[3]

    token=[]
    con = http.client.HTTPConnection(host,port)
    try:
        with open(probfile,'rb') as dataf:
            ## Submit job
            print("POST /submit")
            con.request("POST", '/submit', dataf)
            resp = con.getresponse()
            check_status(resp)

            token = resp.read().decode('ascii')

            ## Start solving end close connection
            print("GET /solve-background")
            con.request("GET", "/solve-background?token="+token)
            resp = con.getresponse()
            check_status(resp)

    finally:
        con.close()
        print("connection closed")

    con = http.client.HTTPConnection(host,port)
```

```

print("connection open")

try:
    print("GET /solution")
    con.request("GET", "/solution?token="+token)
    resp = con.getresponse()

    check_status(resp)

    res = resp.getheader('X-Mosek-Res-Code', None)
    trm = resp.getheader('X-Mosek-Trm-Code', None)

    print("\tMOSEK response: %s" % res)
    print("\t      trm resp: %s" % trm)
    if resp.status == http.client.OK:
        print("Solution:")
        print(resp.read().decode('ascii', errors='ignore'))

    print("GET /log")
    con.request("GET", "/log?token="+token)
    resp = con.getresponse()

    if resp.status == http.client.OK:
        print(resp.read().decode('utf-8', errors='ignore'))
finally:
    con.close()

```

## 7.3 Problem Submission via Condor

*HTCondor*, formerly known as *Condor* is

“a specialized workload management system for compute-intensive jobs.”

This tutorial shows how to submit optimization problem to a *HTCondor* server via *OptServer*.

The idea is very simple: since *OptServer* executes **MOSEK** using a simple Python script (`solve.py`), we can instruct *OptServer* to use a different script that will interface with *HTCondor*. To this extent we use the script as in [Listing 7.11](#).

Listing 7.11: An example of script to off-load a job from *OptServer* to a *HTCondor* server.

```

1 import sys
2 import os, os.path
3 import subprocess
4
5 if __name__ == '__main__':
6     workdir = sys.argv[1]
7     probfile = sys.argv[2]
8     pidfile = os.path.join(workdir, "PID")
9
10    with open(pidfile, 'wt', encoding='ascii') as f:
11        f.write(str(os.getpid))
12
13    r = 1
14    try:
15        r = subprocess.call(['condor_run',
16                             os.path.abspath(os.path.join(os.path.dirname(__file__), "solve.py")),
17                             workdir,
18                             probfile,
19                             '-noPID'])
20    finally:

```

```
21     try:
22         os.remove(pidfile)
23     except:
24         pass
25
26 sys.exit(r)
```

The script operates as follows:

- lines 10-11: the job PID is stored in a text file called `PID` in the working directory;
- lines 14-24 : a *HTCondor* process is created, responsible to run the `solve.py` script.

To tell OptServer to use the script in [Listing 7.11](#) instead of the default `solve.py`, the `cmd` option (see [Sec. 9](#)) in the configuration file `server.conf` must be modified accordingly. In this case the script is available in the `script` directory of the OptServer distribution. Therefore the configuration file can be simply modified changing the `cmd` option to

```
"cmd"      : "${CONFIGDIR}/script/tocondor.py ${TASK}",
```

## SECURITY

OptServer uses on HTTPS by default, for which a self-signed demo certificate is provided in `security/cert`. The user can point OptServer to another certificate setting the `certdir` option (see [Sec. 9](#)).

### 8.1 User role management

Users can be *registered* or *anonymous*. A registered user can be either

- *administrator* or
- *submitter* or
- *anonymous*.

Users can be added, removed or their status changed from the web interface (see [Sec. 10](#)).

#### Administrator

An administrator can submit jobs and perform all administrative tasks.

It is also possible to grant temporary *administrator* access. Any *administrator* can log in the web interface and grant a access token to a user, from the *tokens* page. Each temporary token is specified in terms of how long it lasts.

#### Submitter

This users can both submit jobs and access the web interface to

- collect information about their own jobs,
- modify their own information but
- they can not perfomr administrative task.

#### Anonymous

Anonymous users are not allowed by default, unless the `enable-anonymous-submit` is specified. Anonymous users can only submit jobs.



## CONFIGURATION

The configuration of the OptServer is stored in a single flat JSON file. Following keys are recognized:

**address** `<string>`  
Host and port, in the format `HOST:PORT`. If `HOST` is left blank then `localhost` is used

**basedir** `<string>`  
Work directory.

**certdir** `<string>`  
Directory containing `key.pem` and `cert.pem`.

**externdir** `<string>`  
Directory containing passive files (css, javascript, images etc.) that is required by the web pages

**enable-login** `<true|false>`  
Enable login and management.

**enable-management** `<true|false>`  
Enable management, even when login is disabled. Forced to `true` if `enable-login` is `true`

**enable-anonymous-submit** `<true|false>`  
Allow submitting tasks without authentication.

**login-expiry** `<integer>`  
Expiry of login session in seconds.

**password-salt** `<string>`  
Name of the file used for password salting.

**cmd** `<string>`  
The command executed to solve problems.

The `cmd` key allows for variable substitution using `${...}`. Following variables are recognized:

- *BASEDIR*
- *CONFIGDIR*
- *TASK* Name of the problem file.
- *WORKDIR* Name of the working directory for the task.

If a key is not specified, then its default value, if any, is used.

The default configuration is stored in the `server.conf` file and reported in [Listing 9.1](#).

Listing 9.1: The OptServer default configuration.

```
{
  "address"      : ":30080",
  "basedir"      : "run",
  "externdir"    : "../management/extern",
  "logfile"      : "run/server.log",
  "pidfile"      : "run/PID",
  "cmd"          : "${CONFIGDIR}/script/solve.py ${TASK}",
}
```

```
"enable-login" : true,  
"certdir"      : "security/cert",  
"password-salt" : "./run/salt"  
}
```

## WEB GUI INTERFACE

The **MOSEK** OptServer provides a minimalistic web interface that allows to

- monitor and terminate jobs and
- grant or revoke access tokens,

The web interface can be activated setting the options `enable-management` or `enable-login` (see [Sec. 9](#)). By default is not active.

### 10.1 Login page

When the user opens the web interface a login page is shown. The user must input its user name and in order to be authenticated. See [Sec. 8](#) for further details.

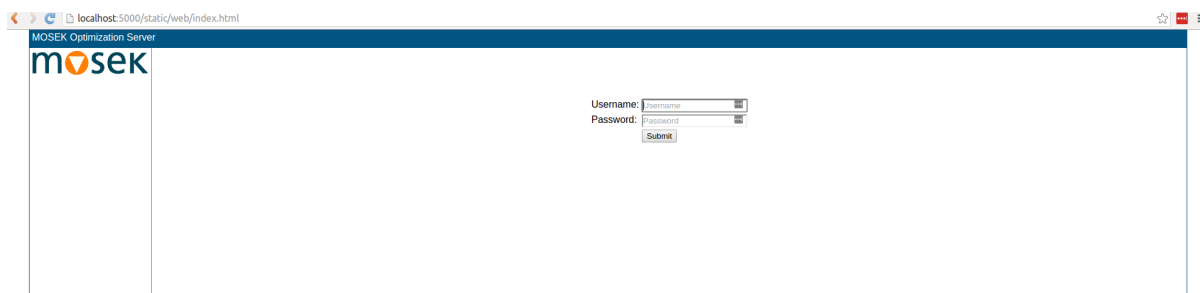


Fig. 10.1: A screenshot of the login page.

---

**Note:** The OptServer does not keep trace of login attempts.

---

If the login is successful the user is presented with a minimal login page.

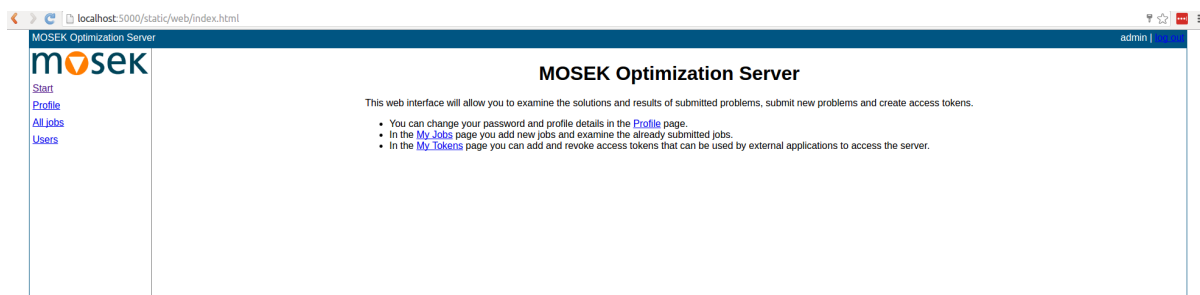


Fig. 10.2: A screenshot of the main page.

## 10.2 Job list page

Selecting the **All Jobs** or **My Jobs** link from the left sidebar for administrators and submitters respectively, the job list page is visualized. It provides information about jobs and for submitters the possibility to post a new job.

An example of how the page looks like is in Fig. 10.3.

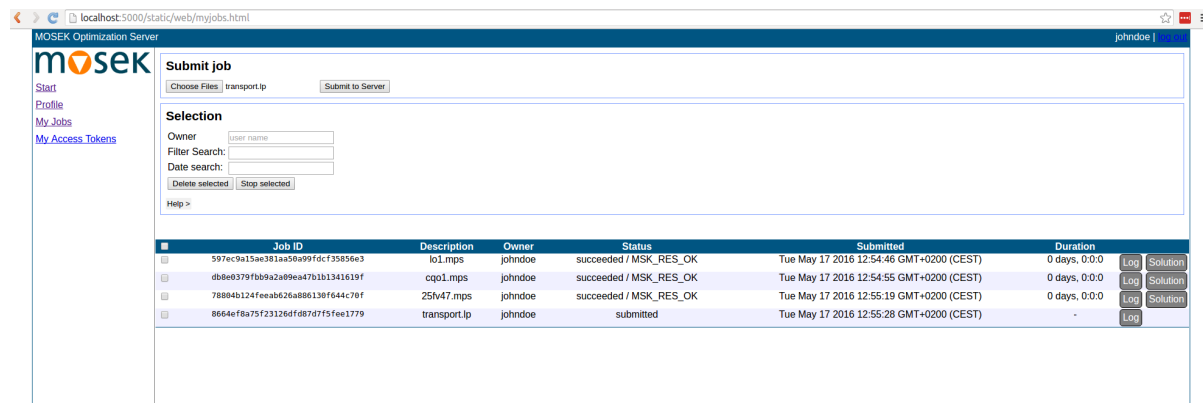


Fig. 10.3: A screenshot of the job list page.

### 10.2.1 The Job List

The list contains all jobs that have been submitted by the user if it is a submitter, or all users for administrators. For each job the following information is available

- **Job ID:** a unique job id,
- **Description:** the submitted file name,
- **Owner:** the user that submitted the job (left blank if anonymous),
- **Status:** whether the job is running, complete with success or something went wrong,
- **Submitted:** when the job has been submitted,
- **Duration:** the overall duration of the job.

For each job two buttons are available that will provide additional information directly from the solver execution:

- **Log:** shows the solver log for that job,
- **Solution:** the solution for the job.

---

**Note:** **Log** and **Solution** are displayed in a new window.

---

### 10.2.2 Job List Filter

To navigate among the submitted jobs OptServer provides a simple search tool that combines criteria from two fields:

- **Filter Search :** Entries in the text search box are matched against values in the columns “Job ID”, “Description”, “Owner” and “Status”. If the string is a substring in any of those fields the row is a match.

- *Date Search* : The entry should either be a single data or a date range (“start .. end”). A date is written as

```
December 21 2012 12:45:00
2012-12-21 12:45:00
```

and the various parts can be left out, i.e. the following are valid

```
Dec 21 2012 meaning Dec 21 2012 00:00:00
2012 meaning Jan 1 2012 00:00:00
```

Ranges are specified with the .., and either end can be left blank to indicate no bound, e.g.

```
Dec 21 2012 .. meaning Dec 21 2012 00:00:00 until now
.. -2012 meaning anything before Jan 1 2012 00:00:00
2011..2012 meaning anything btween Jan 1 2011 and Jan 1 2012
```

Some examples follow

### All jobs submitted in May 2016

In the *Date Search* field enter

```
May .. 2016
```

### All jobs submitted by users with name john

In the *Filter Text* field input

```
john
```

### All failed jobs

In the *Filter Text* field input

```
failed
```

## 10.2.3 Job submission

If the user is a *submitter* it can directly submit a job in asynchronous mode using the GUI.

## 10.2.4 Job Status

The possible job statuses are listed in [Table 10.1](#).

Table 10.1: Status keys.

| Status key       | Description   |
|------------------|---|
| <i>submitted</i> | The job has just been submitted, waiting to run.      |
| <i>running</i>   | The job is currently running.                         |
| <i>failed</i>    | The solver did not terminated correctly.              |
| <i>done</i>      | The solver terminated correctly with a response code. |

Details follow.

### Status *submitted*

The *submitted* status indicates that the job has been received and stored. It is in the process to be executed.

---

**Note:** OptServer does not provide any queuing system. Therefore a job is never waiting for execution.

---

### Status *running*

A job is *running* when the solver has been started but not yet terminated.

### Status *failed*

The *failed* status indicates that something wrong has happened. Two scenarios apply:

1. The running script returned an error before the solver could start.
2. The solver did start, but it terminated unexpectedly and providing no error code. This is the situation for instance in which a serious bug leads to a *segmentation fault*. The *log* may provide useful information on the reason the crash happened.

---

**Tip:** Please consider making a bug report whenever a job fails.

---

### Status *done*

Whenever the job terminates in a nice and controlled way it is flagged as *done*. This *does not* imply the optimization has been successful, but only that the solver has terminated its execution and returned a response code. To distinguish among the different scenarios OptServer also provides the solver response code, which clearly informs the user how and why the solver stopped.

For example

- *MSK\_RES\_OK* indicates the solver terminated successfully,
- *MSK\_RES\_ERR\_LICENSE\_EXPIRED* indicates the **MOSEK** license has expired,
- *MSK\_RES\_TRM\_MAX\_TIME* indicates the solver terminated because the maximum allowed time has reached.

The log contains more detailed information.

## 10.3 User Page

In this page OptServer lists its users, organized in a sortable table that reports

- the username
- the full name,
- the email and
- the roles.

To get more information about the roles see [Sec. 8](#).

In this page administrators can:

- list the OptServer users,
- delete/create users and
- update user information.

An example of how the page looks like is in Fig. 10.4.

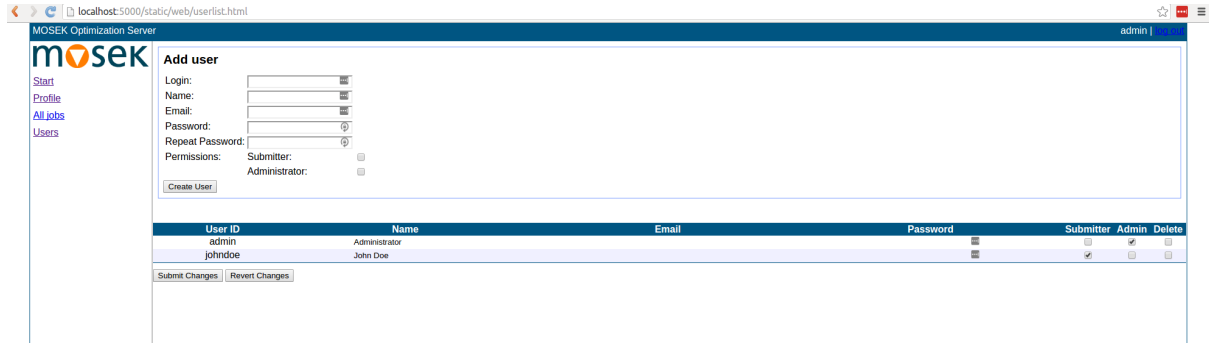


Fig. 10.4: A screenshot of the user page.

### Add New User

A new user can be add using the form on top of the page. Compulsory fields are

- **Login**,
- **Password**.

A user is by default neither an administrator nor a submitter.

### Modify an Existing User

Administrators can modify the user information by editing the relevant fields directly in the user list: just click with mouse pointer and edit!

### Delete an Existing User

An existing user can be delete only by an administrator. This operation will not completely wipe out the user from the OptServer:

- the job submitted by the user will still be listed,
- all temporary files stored (problems and their log and solutions) will not be deleted.

**Warning:** If a new user with the same login name is created, it will take over all data from the deleted user!



## OPTSERVER REFERENCE

### 11.1 OptServer protocol

The server protocol is HTTP plus a couple of extension headers. Commands that the client can use:

`POST /api/submit`

*Post a problem to the server.*

On response OK, a token identifying the problem is returned in the response body, and the token cookie is set to the token string. If logins are disabled or anonymous submits are allowed, no authentication is required. Otherwise, one of following is required:

- An access token, passed in the query part as `access-token=...`, or
- a valid session, passed in the session cookie (i.e. a user that is logged in can submit).

`GET /api/solve`

*Start solving and wait for the solver to finish.*

The token is passed either as a query string `token=<tokenstr>`, or in the token cookie. The Accept header identifies the accepted solution formats. Currently recognized formats are:

|                                       |  |
|---------------------------------------|--|
| <code>application/x-mosek-task</code> | Request solution in <code>.task</code> format. |
| <code>application/x-mosek-json</code> | Request solution in JSON format.               |
| <code>text/plain</code>               | Request a plain ASCII formatted solution       |

`GET /api/solve-background`

*Start solving the identified task in background, return immediately.*

It returns OK is the solver started successfully. The token is passed either as a query string `token=<tokenstr>`, or in the token cookie.

`GET /api/log`

*Return the log.*

The token is passed either as a query string `token=<tokenstr>`, or in the token cookie. If the query string contains the parameter `offset=XXXX`, the log file will be returned from offset `XXXX`.

GET /api/solution

*Return the solution*

It returns the solution if available, or NO\_CONTENT if the task exists but no solution is available. The token is passed either as a query string `token=<tokenstr>`, or in the token cookie.

HEAD /api/break

*Attempt to terminate the solver.*

The token is passed either as a query string `token=<tokenstr>`, or in the token cookie.

## 11.2 Parameters grouped by topic

### Analysis

- `MSK_DPAR_ANA_SOL_INFEAS_TOL`
- `MSK_IPAR_ANA_SOL_BASIS`
- `MSK_IPAR_ANA_SOL_PRINT_VIOLATED`
- `MSK_IPAR_LOG_ANA_PRO`

### Basis identification

- `MSK_DPAR_SIM_LU_TOL_REL_PIV`
- `MSK_IPAR_BI_CLEAN_OPTIMIZER`
- `MSK_IPAR_BI_IGNORE_MAX_ITER`
- `MSK_IPAR_BI_IGNORE_NUM_ERROR`
- `MSK_IPAR_BI_MAX_ITERATIONS`
- `MSK_IPAR_INTPNT_BASIS`
- `MSK_IPAR_LOG_BI`
- `MSK_IPAR_LOG_BI_FREQ`

### Conic interior-point method

- `MSK_DPAR_INTPNT_CO_TOL_DFEAS`
- `MSK_DPAR_INTPNT_CO_TOL_INFEAS`
- `MSK_DPAR_INTPNT_CO_TOL_MU_RED`
- `MSK_DPAR_INTPNT_CO_TOL_NEAR_REL`
- `MSK_DPAR_INTPNT_CO_TOL_PFEAS`
- `MSK_DPAR_INTPNT_CO_TOL_REL_GAP`

## Data check

- *MSK\_DPAR\_DATA\_SYM\_MAT\_TOL*
- *MSK\_DPAR\_DATA\_SYM\_MAT\_TOL\_HUGE*
- *MSK\_DPAR\_DATA\_SYM\_MAT\_TOL\_LARGE*
- *MSK\_DPAR\_DATA\_TOL\_AIJ*
- *MSK\_DPAR\_DATA\_TOL\_AIJ\_HUGE*
- *MSK\_DPAR\_DATA\_TOL\_AIJ\_LARGE*
- *MSK\_DPAR\_DATA\_TOL\_BOUND\_INF*
- *MSK\_DPAR\_DATA\_TOL\_BOUND\_WRN*
- *MSK\_DPAR\_DATA\_TOL\_C\_HUGE*
- *MSK\_DPAR\_DATA\_TOL\_CJ\_LARGE*
- *MSK\_DPAR\_DATA\_TOL\_QIJ*
- *MSK\_DPAR\_DATA\_TOL\_X*
- *MSK\_DPAR\_SEMIDEFINITE\_TOL\_APPROX*
- *MSK\_IPAR\_CHECK\_CONVEXITY*
- *MSK\_IPAR\_LOG\_CHECK\_CONVEXITY*

## Data input/output

- *MSK\_IPAR\_INFEAS\_REPORT\_AUTO*
- *MSK\_IPAR\_LOG\_FILE*
- *MSK\_IPAR\_OPF\_MAX\_TERMS\_PER\_LINE*
- *MSK\_IPAR\_OPF\_WRITE\_HEADER*
- *MSK\_IPAR\_OPF\_WRITE\_HINTS*
- *MSK\_IPAR\_OPF\_WRITE\_PARAMETERS*
- *MSK\_IPAR\_OPF\_WRITE\_PROBLEM*
- *MSK\_IPAR\_OPF\_WRITE\_SOL\_BAS*
- *MSK\_IPAR\_OPF\_WRITE\_SOL\_ITG*
- *MSK\_IPAR\_OPF\_WRITE\_SOL\_ITR*
- *MSK\_IPAR\_OPF\_WRITE\_SOLUTIONS*
- *MSK\_IPAR\_PARAM\_READ\_CASE\_NAME*
- *MSK\_IPAR\_PARAM\_READ\_IGN\_ERROR*
- *MSK\_IPAR\_READ\_DATA\_COMPRESSED*
- *MSK\_IPAR\_READ\_DATA\_FORMAT*
- *MSK\_IPAR\_READ\_DEBUG*
- *MSK\_IPAR\_READ\_KEEP\_FREE\_CON*
- *MSK\_IPAR\_READ\_LP\_DROP\_NEW\_VARS\_IN\_BOU*
- *MSK\_IPAR\_READ\_LP\_QUOTED\_NAMES*
- *MSK\_IPAR\_READ\_MPS\_FORMAT*

- *MSK\_IPAR\_READ\_MPS\_WIDTH*
- *MSK\_IPAR\_READ\_TASK\_IGNORE\_PARAM*
- *MSK\_IPAR\_SOL\_READ\_NAME\_WIDTH*
- *MSK\_IPAR\_SOL\_READ\_WIDTH*
- *MSK\_IPAR\_WRITE\_BAS\_CONSTRAINTS*
- *MSK\_IPAR\_WRITE\_BAS\_HEAD*
- *MSK\_IPAR\_WRITE\_BAS\_VARIABLES*
- *MSK\_IPAR\_WRITE\_DATA\_COMPRESSED*
- *MSK\_IPAR\_WRITE\_DATA\_FORMAT*
- *MSK\_IPAR\_WRITE\_DATA\_PARAM*
- *MSK\_IPAR\_WRITE\_FREE\_CON*
- *MSK\_IPAR\_WRITE\_GENERIC\_NAMES*
- *MSK\_IPAR\_WRITE\_GENERIC\_NAMES\_IO*
- *MSK\_IPAR\_WRITE\_IGNORE\_INCOMPATIBLE\_ITEMS*
- *MSK\_IPAR\_WRITE\_INT\_CONSTRAINTS*
- *MSK\_IPAR\_WRITE\_INT\_HEAD*
- *MSK\_IPAR\_WRITE\_INT\_VARIABLES*
- *MSK\_IPAR\_WRITE\_LP\_FULL\_OBJ*
- *MSK\_IPAR\_WRITE\_LP\_LINE\_WIDTH*
- *MSK\_IPAR\_WRITE\_LP\_QUOTED\_NAMES*
- *MSK\_IPAR\_WRITE\_LP\_STRICT\_FORMAT*
- *MSK\_IPAR\_WRITE\_LP\_TERMS\_PER\_LINE*
- *MSK\_IPAR\_WRITE\_MPS\_FORMAT*
- *MSK\_IPAR\_WRITE\_MPS\_INT*
- *MSK\_IPAR\_WRITE\_PRECISION*
- *MSK\_IPAR\_WRITE\_SOL\_BARVARIABLES*
- *MSK\_IPAR\_WRITE\_SOL\_CONSTRAINTS*
- *MSK\_IPAR\_WRITE\_SOL\_HEAD*
- *MSK\_IPAR\_WRITE\_SOL\_IGNORE\_INVALID\_NAMES*
- *MSK\_IPAR\_WRITE\_SOL\_VARIABLES*
- *MSK\_IPAR\_WRITE\_TASK\_INC\_SOL*
- *MSK\_IPAR\_WRITE\_XML\_MODE*
- *MSK\_SPAR\_BAS\_SOL\_FILE\_NAME*
- *MSK\_SPAR\_DATA\_FILE\_NAME*
- *MSK\_SPAR\_DEBUG\_FILE\_NAME*
- *MSK\_SPAR\_INT\_SOL\_FILE\_NAME*
- *MSK\_SPAR\_ITR\_SOL\_FILE\_NAME*
- *MSK\_SPAR\_MIO\_DEBUG\_STRING*
- *MSK\_SPAR\_PARAM\_COMMENT\_SIGN*

- *MSK\_SPAR\_PARAM\_READ\_FILE\_NAME*
- *MSK\_SPAR\_PARAM\_WRITE\_FILE\_NAME*
- *MSK\_SPAR\_READ\_MPS\_BOU\_NAME*
- *MSK\_SPAR\_READ\_MPS\_OBJ\_NAME*
- *MSK\_SPAR\_READ\_MPS\_RAN\_NAME*
- *MSK\_SPAR\_READ\_MPS\_RHS\_NAME*
- *MSK\_SPAR\_SENSITIVITY\_FILE\_NAME*
- *MSK\_SPAR\_SENSITIVITY\_RES\_FILE\_NAME*
- *MSK\_SPAR\_SOL\_FILTER\_XC\_LOW*
- *MSK\_SPAR\_SOL\_FILTER\_XC\_UPR*
- *MSK\_SPAR\_SOL\_FILTER\_XX\_LOW*
- *MSK\_SPAR\_SOL\_FILTER\_XX\_UPR*
- *MSK\_SPAR\_STAT\_FILE\_NAME*
- *MSK\_SPAR\_STAT\_KEY*
- *MSK\_SPAR\_STAT\_NAME*
- *MSK\_SPAR\_WRITE\_LP\_GEN\_VAR\_NAME*

### Debugging

- *MSK\_IPAR\_AUTO\_SORT\_A\_BEFORE\_OPT*

### Dual simplex

- *MSK\_IPAR\_SIM\_DUAL\_CRASH*
- *MSK\_IPAR\_SIM\_DUAL\_RESTRICT\_SELECTION*
- *MSK\_IPAR\_SIM\_DUAL\_SELECTION*

### Infeasibility report

- *MSK\_IPAR\_INFEAS\_GENERIC\_NAMES*
- *MSK\_IPAR\_INFEAS\_REPORT\_LEVEL*
- *MSK\_IPAR\_LOG\_INFEAS\_ANA*

### Interior-point method

- *MSK\_DPAR\_CHECK\_CONVEXITY\_REL\_TOL*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_DFEAS*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_INFEAS*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_MU\_RED*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_NEAR\_REL*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_PFEAS*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_REL\_GAP*

- *MSK\_DPAR\_INTPNT\_NL\_MERIT\_BAL*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_DFEAS*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_MU\_RED*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_NEAR\_REL*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_PFEAS*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_REL\_GAP*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_REL\_STEP*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_DFEAS*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_INFEAS*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_MU\_RED*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_NEAR\_REL*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_PFEAS*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_REL\_GAP*
- *MSK\_DPAR\_INTPNT\_TOL\_DFEAS*
- *MSK\_DPAR\_INTPNT\_TOL\_DSAFE*
- *MSK\_DPAR\_INTPNT\_TOL\_INFEAS*
- *MSK\_DPAR\_INTPNT\_TOL\_MU\_RED*
- *MSK\_DPAR\_INTPNT\_TOL\_PATH*
- *MSK\_DPAR\_INTPNT\_TOL\_PFEAS*
- *MSK\_DPAR\_INTPNT\_TOL\_PSAFE*
- *MSK\_DPAR\_INTPNT\_TOL\_REL\_GAP*
- *MSK\_DPAR\_INTPNT\_TOL\_REL\_STEP*
- *MSK\_DPAR\_INTPNT\_TOL\_STEP\_SIZE*
- *MSK\_DPAR\_QCQO\_REFORMULATE\_REL\_DROP\_TOL*
- *MSK\_IPAR\_BI\_IGNORE\_MAX\_ITER*
- *MSK\_IPAR\_BI\_IGNORE\_NUM\_ERROR*
- *MSK\_IPAR\_INTPNT\_BASIS*
- *MSK\_IPAR\_INTPNT\_DIFF\_STEP*
- *MSK\_IPAR\_INTPNT\_HOTSTART*
- *MSK\_IPAR\_INTPNT\_MAX\_ITERATIONS*
- *MSK\_IPAR\_INTPNT\_MAX\_NUM\_COR*
- *MSK\_IPAR\_INTPNT\_MAX\_NUM\_REFINEMENT\_STEPS*
- *MSK\_IPAR\_INTPNT\_OFF\_COL\_TRH*
- *MSK\_IPAR\_INTPNT\_ORDER\_METHOD*
- *MSK\_IPAR\_INTPNT\_REGULARIZATION\_USE*
- *MSK\_IPAR\_INTPNT\_SCALING*
- *MSK\_IPAR\_INTPNT\_SOLVE\_FORM*
- *MSK\_IPAR\_INTPNT\_STARTING\_POINT*
- *MSK\_IPAR\_LOG\_INTPNT*

## License manager

- *MSK\_IPAR\_CACHE\_LICENSE*
- *MSK\_IPAR\_LICENSE\_DEBUG*
- *MSK\_IPAR\_LICENSE\_PAUSE\_TIME*
- *MSK\_IPAR\_LICENSE\_SUPPRESS\_EXPIRE\_WRNS*
- *MSK\_IPAR\_LICENSE\_TRH\_EXPIRY\_WRN*
- *MSK\_IPAR\_LICENSE\_WAIT*

## Logging

- *MSK\_IPAR\_LOG*
- *MSK\_IPAR\_LOG\_ANA\_PRO*
- *MSK\_IPAR\_LOG\_BI*
- *MSK\_IPAR\_LOG\_BI\_FREQ*
- *MSK\_IPAR\_LOG\_CUT\_SECOND\_OPT*
- *MSK\_IPAR\_LOG\_EXPAND*
- *MSK\_IPAR\_LOG\_FEAS\_REPAIR*
- *MSK\_IPAR\_LOG\_FILE*
- *MSK\_IPAR\_LOG\_INFEAS\_ANA*
- *MSK\_IPAR\_LOG\_INTPNT*
- *MSK\_IPAR\_LOG\_MIO*
- *MSK\_IPAR\_LOG\_MIO\_FREQ*
- *MSK\_IPAR\_LOG\_ORDER*
- *MSK\_IPAR\_LOG\_PRESOLVE*
- *MSK\_IPAR\_LOG\_RESPONSE*
- *MSK\_IPAR\_LOG\_SENSITIVITY*
- *MSK\_IPAR\_LOG\_SENSITIVITY\_OPT*
- *MSK\_IPAR\_LOG\_SIM*
- *MSK\_IPAR\_LOG\_SIM\_FREQ*
- *MSK\_IPAR\_LOG\_STORAGE*

## Mixed-integer optimization

- *MSK\_DPAR\_MIO\_DISABLE\_TERM\_TIME*
- *MSK\_DPAR\_MIO\_MAX\_TIME*
- *MSK\_DPAR\_MIO\_NEAR\_TOL\_ABS\_GAP*
- *MSK\_DPAR\_MIO\_NEAR\_TOL\_REL\_GAP*
- *MSK\_DPAR\_MIO\_REL\_GAP\_CONST*
- *MSK\_DPAR\_MIO\_TOL\_ABS\_GAP*
- *MSK\_DPAR\_MIO\_TOL\_ABS\_RELAX\_INT*

- *MSK\_DPAR\_MIO\_TOL\_FEAS*
- *MSK\_DPAR\_MIO\_TOL\_REL\_DUAL\_BOUND\_IMPROVEMENT*
- *MSK\_DPAR\_MIO\_TOL\_REL\_GAP*
- *MSK\_IPAR\_LOG\_MIO*
- *MSK\_IPAR\_LOG\_MIO\_FREQ*
- *MSK\_IPAR\_MIO\_BRANCH\_DIR*
- *MSK\_IPAR\_MIO\_CONSTRUCT\_SOL*
- *MSK\_IPAR\_MIO\_CUT\_CLIQUE*
- *MSK\_IPAR\_MIO\_CUT\_CMIR*
- *MSK\_IPAR\_MIO\_CUT\_GMI*
- *MSK\_IPAR\_MIO\_CUT\_IMPLIED\_BOUND*
- *MSK\_IPAR\_MIO\_CUT\_KNAPSACK\_COVER*
- *MSK\_IPAR\_MIO\_CUT\_SELECTION\_LEVEL*
- *MSK\_IPAR\_MIO\_HEURISTIC\_LEVEL*
- *MSK\_IPAR\_MIO\_MAX\_NUM\_BRANCHES*
- *MSK\_IPAR\_MIO\_MAX\_NUM\_RELAXS*
- *MSK\_IPAR\_MIO\_MAX\_NUM\_SOLUTIONS*
- *MSK\_IPAR\_MIO\_NODE\_OPTIMIZER*
- *MSK\_IPAR\_MIO\_NODE\_SELECTION*
- *MSK\_IPAR\_MIO\_PERSPECTIVE\_REFORMULATE*
- *MSK\_IPAR\_MIO\_PROBING\_LEVEL*
- *MSK\_IPAR\_MIO\_RINS\_MAX\_NODES*
- *MSK\_IPAR\_MIO\_ROOT\_OPTIMIZER*
- *MSK\_IPAR\_MIO\_ROOT\_REPEAT\_PRESOLVE\_LEVEL*
- *MSK\_IPAR\_MIO\_VB\_DETECTION\_LEVEL*

#### Nonlinear convex method

- *MSK\_DPAR\_INTPNT\_NL\_MERIT\_BAL*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_DFEAS*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_MU\_RED*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_NEAR\_REL*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_PFEAS*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_REL\_GAP*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_REL\_STEP*
- *MSK\_DPAR\_INTPNT\_TOL\_INFEAS*
- *MSK\_IPAR\_CHECK\_CONVEXITY*
- *MSK\_IPAR\_LOG\_CHECK\_CONVEXITY*

## Output information

- *MSK\_IPAR\_INFEAS\_REPORT\_LEVEL*
- *MSK\_IPAR\_LICENSE\_SUPPRESS\_EXPIRE\_WRNS*
- *MSK\_IPAR\_LICENSE\_TRH\_EXPIRY\_WRN*
- *MSK\_IPAR\_LOG*
- *MSK\_IPAR\_LOG\_BI*
- *MSK\_IPAR\_LOG\_BI\_FREQ*
- *MSK\_IPAR\_LOG\_CUT\_SECOND\_OPT*
- *MSK\_IPAR\_LOG\_EXPAND*
- *MSK\_IPAR\_LOG\_FEAS\_REPAIR*
- *MSK\_IPAR\_LOG\_FILE*
- *MSK\_IPAR\_LOG\_INFEAS\_ANA*
- *MSK\_IPAR\_LOG\_INTPNT*
- *MSK\_IPAR\_LOG\_MIO*
- *MSK\_IPAR\_LOG\_MIO\_FREQ*
- *MSK\_IPAR\_LOG\_ORDER*
- *MSK\_IPAR\_LOG\_RESPONSE*
- *MSK\_IPAR\_LOG\_SENSITIVITY*
- *MSK\_IPAR\_LOG\_SENSITIVITY\_OPT*
- *MSK\_IPAR\_LOG\_SIM*
- *MSK\_IPAR\_LOG\_SIM\_FREQ*
- *MSK\_IPAR\_LOG\_SIM\_MINOR*
- *MSK\_IPAR\_LOG\_STORAGE*
- *MSK\_IPAR\_MAX\_NUM\_WARNINGS*

## Overall solver

- *MSK\_IPAR\_BI\_CLEAN\_OPTIMIZER*
- *MSK\_IPAR\_INFEAS\_PREFER\_PRIMAL*
- *MSK\_IPAR\_LICENSE\_WAIT*
- *MSK\_IPAR\_MIO\_MODE*
- *MSK\_IPAR\_OPTIMIZER*
- *MSK\_IPAR\_PRESOLVE\_LEVEL*
- *MSK\_IPAR\_PRESOLVE\_MAX\_NUM\_REDUCTIONS*
- *MSK\_IPAR\_PRESOLVE\_USE*
- *MSK\_IPAR\_PRIMAL\_REPAIR\_OPTIMIZER*
- *MSK\_IPAR\_SENSITIVITY\_ALL*
- *MSK\_IPAR\_SENSITIVITY\_OPTIMIZER*
- *MSK\_IPAR\_SENSITIVITY\_TYPE*

- *MSK\_IPAR\_SOLUTION\_CALLBACK*

## Overall system

- *MSK\_IPAR\_AUTO\_UPDATE\_SOL\_INFO*
- *MSK\_IPAR\_INTPNT\_MULTI\_THREAD*
- *MSK\_IPAR\_LICENSE\_WAIT*
- *MSK\_IPAR\_LOG\_STORAGE*
- *MSK\_IPAR\_MIO\_MT\_USER\_CB*
- *MSK\_IPAR\_MT\_SPINCOUNT*
- *MSK\_IPAR\_NUM\_THREADS*
- *MSK\_IPAR\_REMOVE\_UNUSED\_SOLUTIONS*
- *MSK\_IPAR\_TIMING\_LEVEL*
- *MSK\_SPAR\_REMOTE\_ACCESS\_TOKEN*

## Presolve

- *MSK\_DPAR\_PREOLVE\_TOL\_ABS\_LINDEP*
- *MSK\_DPAR\_PREOLVE\_TOL\_AIJ*
- *MSK\_DPAR\_PREOLVE\_TOL\_REL\_LINDEP*
- *MSK\_DPAR\_PREOLVE\_TOL\_S*
- *MSK\_DPAR\_PREOLVE\_TOL\_X*
- *MSK\_IPAR\_PREOLVE\_ELIMINATOR\_MAX\_FILL*
- *MSK\_IPAR\_PREOLVE\_ELIMINATOR\_MAX\_NUM\_TRIES*
- *MSK\_IPAR\_PREOLVE\_LEVEL*
- *MSK\_IPAR\_PREOLVE\_LINDEP\_ABS\_WORK\_TRH*
- *MSK\_IPAR\_PREOLVE\_LINDEP\_REL\_WORK\_TRH*
- *MSK\_IPAR\_PREOLVE\_LINDEP\_USE*
- *MSK\_IPAR\_PREOLVE\_MAX\_NUM\_REDUCTIONS*
- *MSK\_IPAR\_PREOLVE\_USE*

## Primal simplex

- *MSK\_IPAR\_SIM\_PRIMAL\_CRASH*
- *MSK\_IPAR\_SIM\_PRIMAL\_RESTRICT\_SELECTION*
- *MSK\_IPAR\_SIM\_PRIMAL\_SELECTION*

## Progress callback

- *MSK\_IPAR\_SOLUTION\_CALLBACK*

## Simplex optimizer

- *MSK\_DPAR\_BASIS\_REL\_TOL\_S*
- *MSK\_DPAR\_BASIS\_TOL\_S*
- *MSK\_DPAR\_BASIS\_TOL\_X*
- *MSK\_DPAR\_SIM\_LU\_TOL\_REL\_PIV*
- *MSK\_DPAR\_SIMPLEX\_ABS\_TOL\_PIV*
- *MSK\_IPAR\_BASIS\_SOLVE\_USE\_PLUS\_ONE*
- *MSK\_IPAR\_LOG\_SIM*
- *MSK\_IPAR\_LOG\_SIM\_FREQ*
- *MSK\_IPAR\_LOG\_SIM\_MINOR*
- *MSK\_IPAR\_SENSITIVITY\_OPTIMIZER*
- *MSK\_IPAR\_SIM\_BASIS\_FACTOR\_USE*
- *MSK\_IPAR\_SIM\_DEGEN*
- *MSK\_IPAR\_SIM\_DUAL\_PHASEONE\_METHOD*
- *MSK\_IPAR\_SIM\_EXPLOIT\_DUPVEC*
- *MSK\_IPAR\_SIM\_HOTSTART*
- *MSK\_IPAR\_SIM\_HOTSTART\_LU*
- *MSK\_IPAR\_SIM\_MAX\_ITERATIONS*
- *MSK\_IPAR\_SIM\_MAX\_NUM\_SETBACKS*
- *MSK\_IPAR\_SIM\_NON\_SINGULAR*
- *MSK\_IPAR\_SIM\_PRIMAL\_PHASEONE\_METHOD*
- *MSK\_IPAR\_SIM\_REFACTOR\_FREQ*
- *MSK\_IPAR\_SIM\_REFORMULATION*
- *MSK\_IPAR\_SIM\_SAVE\_LU*
- *MSK\_IPAR\_SIM\_SCALING*
- *MSK\_IPAR\_SIM\_SCALING\_METHOD*
- *MSK\_IPAR\_SIM\_SOLVE\_FORM*
- *MSK\_IPAR\_SIM\_STABILITY\_PRIORITY*
- *MSK\_IPAR\_SIM\_SWITCH\_OPTIMIZER*

## Solution input/output

- *MSK\_IPAR\_INFEAS\_REPORT\_AUTO*
- *MSK\_IPAR\_SOL\_FILTER\_KEEP\_BASIC*
- *MSK\_IPAR\_SOL\_FILTER\_KEEP\_RANGED*
- *MSK\_IPAR\_SOL\_READ\_NAME\_WIDTH*
- *MSK\_IPAR\_SOL\_READ\_WIDTH*
- *MSK\_IPAR\_WRITE\_BAS\_CONSTRAINTS*
- *MSK\_IPAR\_WRITE\_BAS\_HEAD*

- *MSK\_IPAR\_WRITE\_BAS\_VARIABLES*
- *MSK\_IPAR\_WRITE\_INT\_CONSTRAINTS*
- *MSK\_IPAR\_WRITE\_INT\_HEAD*
- *MSK\_IPAR\_WRITE\_INT\_VARIABLES*
- *MSK\_IPAR\_WRITE\_SOL\_BARVARIABLES*
- *MSK\_IPAR\_WRITE\_SOL\_CONSTRAINTS*
- *MSK\_IPAR\_WRITE\_SOL\_HEAD*
- *MSK\_IPAR\_WRITE\_SOL\_IGNORE\_INVALID\_NAMES*
- *MSK\_IPAR\_WRITE\_SOL\_VARIABLES*
- *MSK\_SPAR\_BAS\_SOL\_FILE\_NAME*
- *MSK\_SPAR\_INT\_SOL\_FILE\_NAME*
- *MSK\_SPAR\_ITR\_SOL\_FILE\_NAME*
- *MSK\_SPAR\_SOL\_FILTER\_XC\_LOW*
- *MSK\_SPAR\_SOL\_FILTER\_XC\_UPR*
- *MSK\_SPAR\_SOL\_FILTER\_XX\_LOW*
- *MSK\_SPAR\_SOL\_FILTER\_XX\_UPR*

#### Termination criteria

- *MSK\_DPAR\_BASIS\_REL\_TOL\_S*
- *MSK\_DPAR\_BASIS\_TOL\_S*
- *MSK\_DPAR\_BASIS\_TOL\_X*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_DFEAS*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_INFEAS*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_MU\_RED*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_NEAR\_REL*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_PFEAS*
- *MSK\_DPAR\_INTPNT\_CO\_TOL\_REL\_GAP*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_DFEAS*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_MU\_RED*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_NEAR\_REL*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_PFEAS*
- *MSK\_DPAR\_INTPNT\_NL\_TOL\_REL\_GAP*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_DFEAS*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_INFEAS*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_MU\_RED*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_NEAR\_REL*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_PFEAS*
- *MSK\_DPAR\_INTPNT\_QO\_TOL\_REL\_GAP*
- *MSK\_DPAR\_INTPNT\_TOL\_DFEAS*

- *MSK\_DPAR\_INTPNT\_TOL\_INFEAS*
- *MSK\_DPAR\_INTPNT\_TOL\_MU\_RED*
- *MSK\_DPAR\_INTPNT\_TOL\_PFEAS*
- *MSK\_DPAR\_INTPNT\_TOL\_REL\_GAP*
- *MSK\_DPAR\_LOWER\_OBJ\_CUT*
- *MSK\_DPAR\_LOWER\_OBJ\_CUT\_FINITE\_TRH*
- *MSK\_DPAR\_MIO\_DISABLE\_TERM\_TIME*
- *MSK\_DPAR\_MIO\_MAX\_TIME*
- *MSK\_DPAR\_MIO\_NEAR\_TOL\_REL\_GAP*
- *MSK\_DPAR\_MIO\_REL\_GAP\_CONST*
- *MSK\_DPAR\_MIO\_TOL\_REL\_GAP*
- *MSK\_DPAR\_OPTIMIZER\_MAX\_TIME*
- *MSK\_DPAR\_UPPER\_OBJ\_CUT*
- *MSK\_DPAR\_UPPER\_OBJ\_CUT\_FINITE\_TRH*
- *MSK\_IPAR\_BI\_MAX\_ITERATIONS*
- *MSK\_IPAR\_INTPNT\_MAX\_ITERATIONS*
- *MSK\_IPAR\_MIO\_MAX\_NUM\_BRANCHES*
- *MSK\_IPAR\_MIO\_MAX\_NUM\_SOLUTIONS*
- *MSK\_IPAR\_SIM\_MAX\_ITERATIONS*

#### Other

- *MSK\_IPAR\_COMPRESS\_STATFILE*

## 11.3 Parameters (alphabetical list sorted by type)

- *Double parameters*
- *Integer parameters*
- *String parameters*

### 11.3.1 Double parameters

#### MSK\_DPAR\_ANA\_SOL\_INFEAS\_TOL

If a constraint violates its bound with an amount larger than this value, the constraint name, index and violation will be printed by the solution analyzer.

**Default** 1e-6

**Accepted** [0.0; +inf]

**Groups** *Analysis*

#### MSK\_DPAR\_BASIS\_REL\_TOL\_S

Maximum relative dual bound violation allowed in an optimal basic solution.

**Default** 1.0e-12

**Accepted** [0.0; +inf]

**Groups** *Simplex optimizer, Termination criteria*

**MSK\_DPAR\_BASIS\_TOL\_S**

Maximum absolute dual bound violation in an optimal basic solution.

**Default** 1.0e-6

**Accepted** [1.0e-9; +inf]

**Groups** *Simplex optimizer, Termination criteria*

**MSK\_DPAR\_BASIS\_TOL\_X**

Maximum absolute primal bound violation allowed in an optimal basic solution.

**Default** 1.0e-6

**Accepted** [1.0e-9; +inf]

**Groups** *Simplex optimizer, Termination criteria*

**MSK\_DPAR\_CHECK\_CONVEXITY\_REL\_TOL**

This parameter controls when the full convexity check declares a problem to be non-convex. Increasing this tolerance relaxes the criteria for declaring the problem non-convex.

A problem is declared non-convex if negative (positive) pivot elements are detected in the Cholesky factor of a matrix which is required to be PSD (NSD). This parameter controls how much this non-negativity requirement may be violated.

If  $d_i$  is the pivot element for column  $i$ , then the matrix  $Q$  is considered to not be PSD if:

$$d_i \leq -|Q_{ii}|\text{check\_convexity\_rel\_tol}$$

**Default** 1e-10

**Accepted** [0; +inf]

**Groups** *Interior-point method*

**MSK\_DPAR\_DATA\_SYM\_MAT\_TOL**

Absolute zero tolerance for elements in symmetric matrixes. If any value in a symmetric matrix is smaller than this parameter in absolute terms **MOSEK** will treat the values as zero and generate a warning.

**Default** 1.0e-12

**Accepted** [1.0e-16; 1.0e-6]

**Groups** *Data check*

**MSK\_DPAR\_DATA\_SYM\_MAT\_TOL\_HUGE**

An element in a symmetric matrix which is larger than this value in absolute size causes an error.

**Default** 1.0e20

**Accepted** [0.0; +inf]

**Groups** *Data check*

**MSK\_DPAR\_DATA\_SYM\_MAT\_TOL\_LARGE**

An element in a symmetric matrix which is larger than this value in absolute size causes a warning message to be printed.

**Default** 1.0e10

**Accepted** [0.0; +inf]

**Groups** *Data check*

**MSK\_DPAR\_DATA\_TOL\_AIJ**

Absolute zero tolerance for elements in  $A$ . If any value  $A_{ij}$  is smaller than this parameter in absolute terms **MOSEK** will treat the values as zero and generate a warning.

**Default** 1.0e-12

**Accepted** [1.0e-16; 1.0e-6]

**Groups** *Data check*

MSK\_DPAR\_DATA\_TOL\_AIJ\_HUGE

An element in  $A$  which is larger than this value in absolute size causes an error.

**Default** 1.0e20

**Accepted** [0.0; +inf]

**Groups** *Data check*

MSK\_DPAR\_DATA\_TOL\_AIJ\_LARGE

An element in  $A$  which is larger than this value in absolute size causes a warning message to be printed.

**Default** 1.0e10

**Accepted** [0.0; +inf]

**Groups** *Data check*

MSK\_DPAR\_DATA\_TOL\_BOUND\_INF

Any bound which in absolute value is greater than this parameter is considered infinite.

**Default** 1.0e16

**Accepted** [0.0; +inf]

**Groups** *Data check*

MSK\_DPAR\_DATA\_TOL\_BOUND\_WRN

If a bound value is larger than this value in absolute size, then a warning message is issued.

**Default** 1.0e8

**Accepted** [0.0; +inf]

**Groups** *Data check*

MSK\_DPAR\_DATA\_TOL\_C\_HUGE

An element in  $c$  which is larger than the value of this parameter in absolute terms is considered to be huge and generates an error.

**Default** 1.0e16

**Accepted** [0.0; +inf]

**Groups** *Data check*

MSK\_DPAR\_DATA\_TOL\_CJ\_LARGE

An element in  $c$  which is larger than this value in absolute terms causes a warning message to be printed.

**Default** 1.0e8

**Accepted** [0.0; +inf]

**Groups** *Data check*

MSK\_DPAR\_DATA\_TOL\_QIJ

Absolute zero tolerance for elements in  $Q$  matrices.

**Default** 1.0e-16

**Accepted** [0.0; +inf]

**Groups** *Data check*

**MSK\_DPAR\_DATA\_TOL\_X**

Zero tolerance for constraints and variables i.e. if the distance between the lower and upper bound is less than this value, then the lower and upper bound is considered identical.

**Default** 1.0e-8

**Accepted** [0.0; +inf]

**Groups** *Data check*

**MSK\_DPAR\_INTPNT\_CO\_TOL\_DFEAS**

Dual feasibility tolerance used by the conic interior-point optimizer.

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria, Conic interior-point method*

**See also** *MSK\_DPAR\_INTPNT\_CO\_TOL\_NEAR\_REL*

**MSK\_DPAR\_INTPNT\_CO\_TOL\_INFEAS**

Controls when the conic interior-point optimizer declares the model primal or dual infeasible. A small number means the optimizer gets more conservative about declaring the model infeasible.

**Default** 1.0e-10

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria, Conic interior-point method*

**MSK\_DPAR\_INTPNT\_CO\_TOL\_MU\_RED**

Relative complementarity gap feasibility tolerance used by the conic interior-point optimizer.

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria, Conic interior-point method*

**MSK\_DPAR\_INTPNT\_CO\_TOL\_NEAR\_REL**

If **MOSEK** cannot compute a solution that has the prescribed accuracy, then it will multiply the termination tolerances with value of this parameter. If the solution then satisfies the termination criteria, then the solution is denoted near optimal, near feasible and so forth.

**Default** 1000

**Accepted** [1.0; +inf]

**Groups** *Interior-point method, Termination criteria, Conic interior-point method*

**MSK\_DPAR\_INTPNT\_CO\_TOL\_PFEAS**

Primal feasibility tolerance used by the conic interior-point optimizer.

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria, Conic interior-point method*

**See also** *MSK\_DPAR\_INTPNT\_CO\_TOL\_NEAR\_REL*

**MSK\_DPAR\_INTPNT\_CO\_TOL\_REL\_GAP**

Relative gap termination tolerance used by the conic interior-point optimizer.

**Default** 1.0e-7

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria, Conic interior-point method*

**See also** *MSK\_DPAR\_INTPNT\_CO\_TOL\_NEAR\_REL*

**MSK\_DPAR\_INTPNT\_NL\_MERIT\_BAL**

Controls if the complementarity and infeasibility is converging to zero at about equal rates.

**Default** 1.0e-4

**Accepted** [0.0; 0.99]

**Groups** *Interior-point method, Nonlinear convex method*

**MSK\_DPAR\_INTPNT\_NL\_TOL\_DFEAS**

Dual feasibility tolerance used when a nonlinear model is solved.

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria, Nonlinear convex method*

**MSK\_DPAR\_INTPNT\_NL\_TOL\_MU\_RED**

Relative complementarity gap tolerance for the nonlinear solver.

**Default** 1.0e-12

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria, Nonlinear convex method*

**MSK\_DPAR\_INTPNT\_NL\_TOL\_NEAR\_REL**

If the **MOSEK** nonlinear interior-point optimizer cannot compute a solution that has the prescribed accuracy, then it will multiply the termination tolerances with value of this parameter. If the solution then satisfies the termination criteria, then the solution is denoted near optimal, near feasible and so forth.

**Default** 1000.0

**Accepted** [1.0; +inf]

**Groups** *Interior-point method, Termination criteria, Nonlinear convex method*

**MSK\_DPAR\_INTPNT\_NL\_TOL\_PFEAS**

Primal feasibility tolerance used when a nonlinear model is solved.

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria, Nonlinear convex method*

**MSK\_DPAR\_INTPNT\_NL\_TOL\_REL\_GAP**

Relative gap termination tolerance for nonlinear problems.

**Default** 1.0e-6

**Accepted** [1.0e-14; +inf]

**Groups** *Termination criteria, Interior-point method, Nonlinear convex method*

**MSK\_DPAR\_INTPNT\_NL\_TOL\_REL\_STEP**

Relative step size to the boundary for general nonlinear optimization problems.

**Default** 0.995

**Accepted** [1.0e-4; 0.9999999]

**Groups** *Interior-point method, Nonlinear convex method*

**MSK\_DPAR\_INTPNT\_QO\_TOL\_DFEAS**

Dual feasibility tolerance used when the interior-point optimizer is applied to a quadratic optimization problem..

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria*

**See also** *MSK\_DPAR\_INTPNT\_QO\_TOL\_NEAR\_REL*

#### MSK\_DPAR\_INTPNT\_QO\_TOL\_INFEAS

Controls when the conic interior-point optimizer declares the model primal or dual infeasible. A small number means the optimizer gets more conservative about declaring the model infeasible.

**Default** 1.0e-10

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria*

#### MSK\_DPAR\_INTPNT\_QO\_TOL\_MU\_RED

Relative complementarity gap feasibility tolerance used when interior-point optimizer is applied to a quadratic optimization problem.

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria*

#### MSK\_DPAR\_INTPNT\_QO\_TOL\_NEAR\_REL

If **MOSEK** cannot compute a solution that has the prescribed accuracy, then it will multiply the termination tolerances with value of this parameter. If the solution then satisfies the termination criteria, then the solution is denoted near optimal, near feasible and so forth.

**Default** 1000

**Accepted** [1.0; +inf]

**Groups** *Interior-point method, Termination criteria*

#### MSK\_DPAR\_INTPNT\_QO\_TOL\_PFEAS

Primal feasibility tolerance used when the interior-point optimizer is applied to a quadratic optimization problem.

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria*

**See also** *MSK\_DPAR\_INTPNT\_QO\_TOL\_NEAR\_REL*

#### MSK\_DPAR\_INTPNT\_QO\_TOL\_REL\_GAP

Relative gap termination tolerance used when the interior-point optimizer is applied to a quadratic optimization problem.

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria*

**See also** *MSK\_DPAR\_INTPNT\_QO\_TOL\_NEAR\_REL*

#### MSK\_DPAR\_INTPNT\_TOL\_DFEAS

Dual feasibility tolerance used for linear optimization problems.

**Default** 1.0e-8

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method, Termination criteria*

#### MSK\_DPAR\_INTPNT\_TOL\_DSAFE

Controls the initial dual starting point used by the interior-point optimizer. If the interior-point optimizer converges slowly and/or the constraint or variable bounds are very large, then it might be worthwhile to increase this value.

**Default** 1.0**Accepted** [1.0e-4; +inf]**Groups** *Interior-point method***MSK\_DPAR\_INTPNT\_TOL\_INFEAS**

Controls when the optimizer declares the model primal or dual infeasible. A small number means the optimizer gets more conservative about declaring the model infeasible.

**Default** 1.0e-10**Accepted** [0.0; 1.0]**Groups** *Interior-point method, Termination criteria, Nonlinear convex method***MSK\_DPAR\_INTPNT\_TOL\_MU\_RED**

Relative complementarity gap tolerance for linear problems.

**Default** 1.0e-16**Accepted** [0.0; 1.0]**Groups** *Interior-point method, Termination criteria***MSK\_DPAR\_INTPNT\_TOL\_PATH**

Controls how close the interior-point optimizer follows the central path. A large value of this parameter means the central is followed very closely. On numerical unstable problems it may be worthwhile to increase this parameter.

**Default** 1.0e-8**Accepted** [0.0; 0.9999]**Groups** *Interior-point method***MSK\_DPAR\_INTPNT\_TOL\_PFEAS**

Primal feasibility tolerance used for linear optimization problems.

**Default** 1.0e-8**Accepted** [0.0; 1.0]**Groups** *Interior-point method, Termination criteria***MSK\_DPAR\_INTPNT\_TOL\_PSAFE**

Controls the initial primal starting point used by the interior-point optimizer. If the interior-point optimizer converges slowly and/or the constraint or variable bounds are very large, then it may be worthwhile to increase this value.

**Default** 1.0**Accepted** [1.0e-4; +inf]**Groups** *Interior-point method***MSK\_DPAR\_INTPNT\_TOL\_REL\_GAP**

Relative gap termination tolerance for linear problems.

**Default** 1.0e-8**Accepted** [1.0e-14; +inf]**Groups** *Termination criteria, Interior-point method***MSK\_DPAR\_INTPNT\_TOL\_REL\_STEP**

Relative step size to the boundary for linear and quadratic optimization problems.

**Default** 0.9999**Accepted** [1.0e-4; 0.999999]**Groups** *Interior-point method*

**MSK\_DPAR\_INTPNT\_TOL\_STEP\_SIZE**

Minimal step size tolerance. If the step size falls below the value of this parameter, then the interior-point optimizer assumes that it is stalled. In other words the interior-point optimizer does not make any progress and therefore it is better stop.

**Default** 1.0e-6

**Accepted** [0.0; 1.0]

**Groups** *Interior-point method*

**MSK\_DPAR\_LOWER\_OBJ\_CUT**

If either a primal or dual feasible solution is found proving that the optimal objective value is outside, the interval [ *MSK\_DPAR\_LOWER\_OBJ\_CUT*, *MSK\_DPAR\_UPPER\_OBJ\_CUT* ], then **MOSEK** is terminated.

**Default** -1.0e30

**Accepted** [-inf; +inf]

**Groups** *Termination criteria*

**See also** *MSK\_DPAR\_LOWER\_OBJ\_CUT\_FINITE\_TRH*

**MSK\_DPAR\_LOWER\_OBJ\_CUT\_FINITE\_TRH**

If the lower objective cut is less than the value of this parameter value, then the lower objective cut i.e. *MSK\_DPAR\_LOWER\_OBJ\_CUT* is treated as  $-\infty$ .

**Default** -0.5e30

**Accepted** [-inf; +inf]

**Groups** *Termination criteria*

**MSK\_DPAR\_MIO\_DISABLE\_TERM\_TIME**

This parameter specifies the number of seconds  $n$  during which the termination criteria governed by

- *MSK\_IPAR\_MIO\_MAX\_NUM\_RELAXS*
- *MSK\_IPAR\_MIO\_MAX\_NUM\_BRANCHES*
- *MSK\_DPAR\_MIO\_NEAR\_TOL\_ABS\_GAP*
- *MSK\_DPAR\_MIO\_NEAR\_TOL\_REL\_GAP*

is disabled since the beginning of the optimization.

A negative value is identical to infinity i.e. the termination criteria are never checked.

**Default** -1.0

**Accepted** [-inf; +inf]

**Groups** *Mixed-integer optimization, Termination criteria*

**See also** *MSK\_IPAR\_MIO\_MAX\_NUM\_RELAXS*, *MSK\_IPAR\_MIO\_MAX\_NUM\_BRANCHES*,  
*MSK\_DPAR\_MIO\_NEAR\_TOL\_ABS\_GAP*, *MSK\_DPAR\_MIO\_NEAR\_TOL\_REL\_GAP*

**MSK\_DPAR\_MIO\_MAX\_TIME**

This parameter limits the maximum time spent by the mixed-integer optimizer. A negative number means infinity.

**Default** -1.0

**Accepted** [-inf; +inf]

**Groups** *Mixed-integer optimization, Termination criteria*

**MSK\_DPAR\_MIO\_NEAR\_TOL\_ABS\_GAP**

Relaxed absolute optimality tolerance employed by the mixed-integer optimizer. This termination criteria is delayed. See [MSK\\_DPAR\\_MIO\\_DISABLE\\_TERM\\_TIME](#) for details.

**Default** 0.0

**Accepted** [0.0; +inf]

**Groups** *Mixed-integer optimization*

**See also** [MSK\\_DPAR\\_MIO\\_DISABLE\\_TERM\\_TIME](#)

**MSK\_DPAR\_MIO\_NEAR\_TOL\_REL\_GAP**

The mixed-integer optimizer is terminated when this tolerance is satisfied. This termination criteria is delayed. See [MSK\\_DPAR\\_MIO\\_DISABLE\\_TERM\\_TIME](#) for details.

**Default** 1.0e-3

**Accepted** [0.0; +inf]

**Groups** *Mixed-integer optimization, Termination criteria*

**See also** [MSK\\_DPAR\\_MIO\\_DISABLE\\_TERM\\_TIME](#)

**MSK\_DPAR\_MIO\_REL\_GAP\_CONST**

This value is used to compute the relative gap for the solution to an integer optimization problem.

**Default** 1.0e-10

**Accepted** [1.0e-15; +inf]

**Groups** *Mixed-integer optimization, Termination criteria*

**MSK\_DPAR\_MIO\_TOL\_ABS\_GAP**

Absolute optimality tolerance employed by the mixed-integer optimizer.

**Default** 0.0

**Accepted** [0.0; +inf]

**Groups** *Mixed-integer optimization*

**MSK\_DPAR\_MIO\_TOL\_ABS\_RELAX\_INT**

Absolute integer feasibility tolerance. If the distance to the nearest integer is less than this tolerance then an integer constraint is assumed to be satisfied.

**Default** 1.0e-5

**Accepted** [1e-9; +inf]

**Groups** *Mixed-integer optimization*

**MSK\_DPAR\_MIO\_TOL\_FEAS**

Feasibility tolerance for mixed integer solver.

**Default** 1.0e-6

**Accepted** [1e-9; 1e-3]

**Groups** *Mixed-integer optimization*

**MSK\_DPAR\_MIO\_TOL\_REL\_DUAL\_BOUND\_IMPROVEMENT**

If the relative improvement of the dual bound is smaller than this value, the solver will terminate the root cut generation. A value of 0.0 means that the value is selected automatically.

**Default** 0.0

**Accepted** [0.0; 1.0]

**Groups** *Mixed-integer optimization*

**MSK\_DPAR\_MIO\_TOL\_REL\_GAP**

Relative optimality tolerance employed by the mixed-integer optimizer.

**Default** 1.0e-4

**Accepted** [0.0; +inf]

**Groups** *Mixed-integer optimization, Termination criteria*

MSK\_DPAR\_OPTIMIZER\_MAX\_TIME

Maximum amount of time the optimizer is allowed to spent on the optimization. A negative number means infinity.

**Default** -1.0

**Accepted** [-inf; +inf]

**Groups** *Termination criteria*

MSK\_DPAR\_PREOLVE\_TOL\_ABS\_LINDEP

Absolute tolerance employed by the linear dependency checker.

**Default** 1.0e-6

**Accepted** [0.0; +inf]

**Groups** *Presolve*

MSK\_DPAR\_PREOLVE\_TOL\_AIJ

Absolute zero tolerance employed for  $a_{ij}$  in the presolve.

**Default** 1.0e-12

**Accepted** [1.0e-15; +inf]

**Groups** *Presolve*

MSK\_DPAR\_PREOLVE\_TOL\_REL\_LINDEP

Relative tolerance employed by the linear dependency checker.

**Default** 1.0e-10

**Accepted** [0.0; +inf]

**Groups** *Presolve*

MSK\_DPAR\_PREOLVE\_TOL\_S

Absolute zero tolerance employed for  $s_i$  in the presolve.

**Default** 1.0e-8

**Accepted** [0.0; +inf]

**Groups** *Presolve*

MSK\_DPAR\_PREOLVE\_TOL\_X

Absolute zero tolerance employed for  $x_j$  in the presolve.

**Default** 1.0e-8

**Accepted** [0.0; +inf]

**Groups** *Presolve*

MSK\_DPAR\_QCQO\_REFORMULATE\_REL\_DROP\_TOL

This parameter determines when columns are dropped in incomplete Cholesky factorization during reformulation of quadratic problems.

**Default** 1e-15

**Accepted** [0; +inf]

**Groups** *Interior-point method*

MSK\_DPAR\_SEMIDEFINITE\_TOL\_APPROX

Tolerance to define a matrix to be positive semidefinite.

**Default** 1.0e-10

**Accepted** [1.0e-15; +inf]

**Groups** *Data check*

#### MSK\_DPAR\_SIM\_LU\_TOL\_REL\_PIV

Relative pivot tolerance employed when computing the LU factorization of the basis in the simplex optimizers and in the basis identification procedure.

A value closer to 1.0 generally improves numerical stability but typically also implies an increase in the computational work.

**Default** 0.01

**Accepted** [1.0e-6; 0.999999]

**Groups** *Basis identification, Simplex optimizer*

#### MSK\_DPAR\_SIMPLEX\_ABS\_TOL\_PIV

Absolute pivot tolerance employed by the simplex optimizers.

**Default** 1.0e-7

**Accepted** [1.0e-12; +inf]

**Groups** *Simplex optimizer*

#### MSK\_DPAR\_UPPER\_OBJ\_CUT

If either a primal or dual feasible solution is found proving that the optimal objective value is outside, the interval [ *MSK\_DPAR\_LOWER\_OBJ\_CUT*, *MSK\_DPAR\_UPPER\_OBJ\_CUT* ], then **MOSEK** is terminated.

**Default** 1.0e30

**Accepted** [-inf; +inf]

**Groups** *Termination criteria*

**See also** *MSK\_DPAR\_UPPER\_OBJ\_CUT\_FINITE\_TRH*

#### MSK\_DPAR\_UPPER\_OBJ\_CUT\_FINITE\_TRH

If the upper objective cut is greater than the value of this parameter, then the upper objective cut *MSK\_DPAR\_UPPER\_OBJ\_CUT* is treated as  $\infty$ .

**Default** 0.5e30

**Accepted** [-inf; +inf]

**Groups** *Termination criteria*

## 11.3.2 Integer parameters

#### MSK\_IPAR\_ANA\_SOL\_BASIS

Controls whether the basis matrix is analyzed in solution analyzer.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Analysis*

#### MSK\_IPAR\_ANA\_SOL\_PRINT\_VIOLATED

Controls whether a list of violated constraints is printed.

All constraints violated by more than the value set by the parameter *MSK\_DPAR\_ANA\_SOL\_INFEAS\_TOL* will be printed.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Analysis***MSK\_IPAR\_AUTO\_SORT\_A\_BEFORE\_OPT**

Controls whether the elements in each column of  $A$  are sorted before an optimization is performed. This is not required but makes the optimization more deterministic.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Debugging*

**MSK\_IPAR\_AUTO\_UPDATE\_SOL\_INFO**

Controls whether the solution information items are automatically updated after an optimization is performed.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Overall system*

**MSK\_IPAR\_BASIS\_SOLVE\_USE\_PLUS\_ONE**

If a slack variable is in the basis, then the corresponding column in the basis is a unit vector with -1 in the right position. However, if this parameter is set to *MSK\_ON*, -1 is replaced by 1.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Simplex optimizer*

**MSK\_IPAR\_BI\_CLEAN\_OPTIMIZER**

Controls which simplex optimizer is used in the clean-up phase.

**Default** *FREE*

**Accepted** *FREE, INTPNT, CONIC, PRIMAL\_SIMPLEX, DUAL\_SIMPLEX, FREE\_SIMPLEX, MIXED\_INT*

**Groups** *Basis identification, Overall solver*

**MSK\_IPAR\_BI\_IGNORE\_MAX\_ITER**

If the parameter *MSK\_IPAR\_INTPNT\_BASIS* has the value *MSK\_BI\_NO\_ERROR* and the interior-point optimizer has terminated due to maximum number of iterations, then basis identification is performed if this parameter has the value *MSK\_ON*.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Interior-point method, Basis identification*

**MSK\_IPAR\_BI\_IGNORE\_NUM\_ERROR**

If the parameter *MSK\_IPAR\_INTPNT\_BASIS* has the value *MSK\_BI\_NO\_ERROR* and the interior-point optimizer has terminated due to a numerical problem, then basis identification is performed if this parameter has the value *MSK\_ON*.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Interior-point method, Basis identification*

**MSK\_IPAR\_BI\_MAX\_ITERATIONS**

Controls the maximum number of simplex iterations allowed to optimize a basis after the basis identification.

**Default** 1000000

**Accepted** [0; +inf]

**Groups** *Basis identification, Termination criteria*

#### MSK\_IPAR\_CACHE\_LICENSE

Specifies if the license is kept checked out for the lifetime of the mosek environment (*MSK\_ON*) or returned to the server immediately after the optimization (*MSK\_OFF*).

By default the license is checked out for the lifetime of the **MOSEK** environment by the first call to the optimizer.

Check-in and check-out of licenses have an overhead. Frequent communication with the license server should be avoided.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *License manager*

#### MSK\_IPAR\_CHECK\_CONVEXITY

Specify the level of convexity check on quadratic problems.

**Default** *FULL*

**Accepted** *NONE, SIMPLE, FULL*

**Groups** *Data check, Nonlinear convex method*

#### MSK\_IPAR\_COMPRESS\_STATFILE

Control compression of stat files.

**Default** *ON*

**Accepted** *ON, OFF*

#### MSK\_IPAR\_INFEAS\_GENERIC\_NAMES

Controls whether generic names are used when an infeasible subproblem is created.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Infeasibility report*

#### MSK\_IPAR\_INFEAS\_PREFER\_PRIMAL

If both certificates of primal and dual infeasibility are supplied then only the primal is used when this option is turned on.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Overall solver*

#### MSK\_IPAR\_INFEAS\_REPORT\_AUTO

Controls whether an infeasibility report is automatically produced after the optimization if the problem is primal or dual infeasible.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

#### MSK\_IPAR\_INFEAS\_REPORT\_LEVEL

Controls the amount of information presented in an infeasibility report. Higher values imply more information.

**Default** *1*

**Accepted** *[0; +inf]*

**Groups** *Infeasibility report, Output information*

**MSK\_IPAR\_INTPNT\_BASIS**

Controls whether the interior-point optimizer also computes an optimal basis.

**Default** *ALWAYS*

**Accepted** *NEVER, ALWAYS, NO\_ERROR, IF\_FEASIBLE, RESERVED*

**Groups** *Interior-point method, Basis identification*

**See also** *MSK\_IPAR\_BI\_IGNORE\_MAX\_ITER, MSK\_IPAR\_BI\_IGNORE\_NUM\_ERROR, MSK\_IPAR\_BI\_MAX\_ITERATIONS, MSK\_IPAR\_BI\_CLEAN\_OPTIMIZER*

**MSK\_IPAR\_INTPNT\_DIFF\_STEP**

Controls whether different step sizes are allowed in the primal and dual space.

**Default** *ON*

**Accepted**

- *ON*: Different step sizes are allowed.
- *OFF*: Different step sizes are not allowed.

**Groups** *Interior-point method*

**MSK\_IPAR\_INTPNT\_HOTSTART**

Currently not in use.

**Default** *NONE*

**Accepted** *NONE, PRIMAL, DUAL, PRIMAL\_DUAL*

**Groups** *Interior-point method*

**MSK\_IPAR\_INTPNT\_MAX\_ITERATIONS**

Controls the maximum number of iterations allowed in the interior-point optimizer.

**Default** 400

**Accepted** [0; +inf]

**Groups** *Interior-point method, Termination criteria*

**MSK\_IPAR\_INTPNT\_MAX\_NUM\_COR**

Controls the maximum number of correctors allowed by the multiple corrector procedure. A negative value means that **MOSEK** is making the choice.

**Default** -1

**Accepted** [-1; +inf]

**Groups** *Interior-point method*

**MSK\_IPAR\_INTPNT\_MAX\_NUM\_REFINEMENT\_STEPS**

Maximum number of steps to be used by the iterative refinement of the search direction. A negative value implies that the optimizer chooses the maximum number of iterative refinement steps.

**Default** -1

**Accepted** [-inf; +inf]

**Groups** *Interior-point method*

**MSK\_IPAR\_INTPNT\_MULTI\_THREAD**

Controls whether the interior-point optimizers are allowed to employ multiple threads if more threads is available.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Overall system*

**MSK\_IPAR\_INTPNT\_OFF\_COL\_TRH**

Controls how many offending columns are detected in the Jacobian of the constraint matrix.

|     |  |
|-----|--|
| 0   | no detection                                 |
| 1   | aggressive detection                         |
| > 1 | higher values mean less aggressive detection |

**Default** 40

**Accepted** [0; +inf]

**Groups** *Interior-point method*

**MSK\_IPAR\_INTPNT\_ORDER\_METHOD**

Controls the ordering strategy used by the interior-point optimizer when factorizing the Newton equation system.

**Default** *FREE*

**Accepted** *FREE, APPMINLOC, EXPERIMENTAL, TRY\_GRAPHPAR, FORCE\_GRAPHPAR, NONE*

**Groups** *Interior-point method*

**MSK\_IPAR\_INTPNT\_REGULARIZATION\_USE**

Controls whether regularization is allowed.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Interior-point method*

**MSK\_IPAR\_INTPNT\_SCALING**

Controls how the problem is scaled before the interior-point optimizer is used.

**Default** *FREE*

**Accepted** *FREE, NONE, MODERATE, AGGRESSIVE*

**Groups** *Interior-point method*

**MSK\_IPAR\_INTPNT\_SOLVE\_FORM**

Controls whether the primal or the dual problem is solved.

**Default** *FREE*

**Accepted** *FREE, PRIMAL, DUAL*

**Groups** *Interior-point method*

**MSK\_IPAR\_INTPNT\_STARTING\_POINT**

Starting point used by the interior-point optimizer.

**Default** *FREE*

**Accepted** *FREE, GUESS, CONSTANT, SATISFY\_BOUNDS*

**Groups** *Interior-point method*

**MSK\_IPAR\_LICENSE\_DEBUG**

This option is used to turn on debugging of the license manager.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *License manager*

**MSK\_IPAR\_LICENSE\_PAUSE\_TIME**

If *MSK\_IPAR\_LICENSE\_WAIT* = *MSK\_ON* and no license is available, then **MOSEK** sleeps a number of milliseconds between each check of whether a license has become free.

**Default** 100

**Accepted** [0; 1000000]

**Groups** *License manager*

**MSK\_IPAR\_LICENSE\_SUPPRESS\_EXPIRE\_WRNS**

Controls whether license features expire warnings are suppressed.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *License manager, Output information*

**MSK\_IPAR\_LICENSE\_TRH\_EXPIRY\_WRN**

If a license feature expires in a numbers days less than the value of this parameter then a warning will be issued.

**Default** 7

**Accepted** [0; +inf]

**Groups** *License manager, Output information*

**MSK\_IPAR\_LICENSE\_WAIT**

If all licenses are in use **MOSEK** returns with an error code. However, by turning on this parameter **MOSEK** will wait for an available license.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Overall solver, Overall system, License manager*

**MSK\_IPAR\_LOG**

Controls the amount of log information. The value 0 implies that all log information is suppressed. A higher level implies that more information is logged.

Please note that if a task is employed to solve a sequence of optimization problems the value of this parameter is reduced by the value of *MSK\_IPAR\_LOG\_CUT\_SECOND\_OPT* for the second and any subsequent optimizations.

**Default** 10

**Accepted** [0; +inf]

**Groups** *Output information, Logging*

**See also** *MSK\_IPAR\_LOG\_CUT\_SECOND\_OPT*

**MSK\_IPAR\_LOG\_ANA\_PRO**

Controls amount of output from the problem analyzer.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Analysis, Logging*

**MSK\_IPAR\_LOG\_BI**

Controls the amount of output printed by the basis identification procedure. A higher level implies that more information is logged.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Basis identification, Output information, Logging*

**MSK\_IPAR\_LOG\_BI\_FREQ**

Controls how frequent the optimizer outputs information about the basis identification and how frequent the user-defined callback function is called.

**Default** 2500

**Accepted** [0; +inf]

**Groups** *Basis identification, Output information, Logging*

**MSK\_IPAR\_LOG\_CHECK\_CONVEXITY**

Controls logging in convexity check on quadratic problems. Set to a positive value to turn logging on. If a quadratic coefficient matrix is found to violate the requirement of PSD (NSD) then a list of negative (positive) pivot elements is printed. The absolute value of the pivot elements is also shown.

**Default** 0

**Accepted** [0; +inf]

**Groups** *Data check, Nonlinear convex method*

**MSK\_IPAR\_LOG\_CUT\_SECOND\_OPT**

If a task is employed to solve a sequence of optimization problems, then the value of the log levels is reduced by the value of this parameter. E.g *MSK\_IPAR\_LOG* and *MSK\_IPAR\_LOG\_SIM* are reduced by the value of this parameter for the second and any subsequent optimizations.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Output information, Logging*

**See also** *MSK\_IPAR\_LOG*, *MSK\_IPAR\_LOG\_INTPNT*, *MSK\_IPAR\_LOG\_MIO*,  
*MSK\_IPAR\_LOG\_SIM*

**MSK\_IPAR\_LOG\_EXPAND**

Controls the amount of logging when a data item such as the maximum number constraints is expanded.

**Default** 0

**Accepted** [0; +inf]

**Groups** *Output information, Logging*

**MSK\_IPAR\_LOG\_FEAS\_REPAIR**

Controls the amount of output printed when performing feasibility repair. A value higher than one means extensive logging.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Output information, Logging*

**MSK\_IPAR\_LOG\_FILE**

If turned on, then some log info is printed when a file is written or read.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Data input/output, Output information, Logging*

**MSK\_IPAR\_LOG\_INFEAS\_ANA**

Controls amount of output printed by the infeasibility analyzer procedures. A higher level implies that more information is logged.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Infeasibility report, Output information, Logging*

#### MSK\_IPAR\_LOG\_INTPNT

Controls amount of output printed by the interior-point optimizer. A higher level implies that more information is logged.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Interior-point method, Output information, Logging*

#### MSK\_IPAR\_LOG\_MIO

Controls the log level for the mixed-integer optimizer. A higher level implies that more information is logged.

**Default** 4

**Accepted** [0; +inf]

**Groups** *Mixed-integer optimization, Output information, Logging*

#### MSK\_IPAR\_LOG\_MIO\_FREQ

Controls how frequent the mixed-integer optimizer prints the log line. It will print line every time *MSK\_IPAR\_LOG\_MIO\_FREQ* relaxations have been solved.

**Default** 10

**Accepted** [-inf; +inf]

**Groups** *Mixed-integer optimization, Output information, Logging*

#### MSK\_IPAR\_LOG\_ORDER

If turned on, then factor lines are added to the log.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Output information, Logging*

#### MSK\_IPAR\_LOG\_PRESOLVE

Controls amount of output printed by the presolve procedure. A higher level implies that more information is logged.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Logging*

#### MSK\_IPAR\_LOG\_RESPONSE

Controls amount of output printed when response codes are reported. A higher level implies that more information is logged.

**Default** 0

**Accepted** [0; +inf]

**Groups** *Output information, Logging*

#### MSK\_IPAR\_LOG\_SENSITIVITY

Controls the amount of logging during the sensitivity analysis.

- 0. Means no logging information is produced.
- 1. Timing information is printed.
- 2. Sensitivity results are printed.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Output information, Logging*

**MSK\_IPAR\_LOG\_SENSITIVITY\_OPT**

Controls the amount of logging from the optimizers employed during the sensitivity analysis. 0 means no logging information is produced.

**Default** 0

**Accepted** [0; +inf]

**Groups** *Output information, Logging*

**MSK\_IPAR\_LOG\_SIM**

Controls amount of output printed by the simplex optimizer. A higher level implies that more information is logged.

**Default** 4

**Accepted** [0; +inf]

**Groups** *Simplex optimizer, Output information, Logging*

**MSK\_IPAR\_LOG\_SIM\_FREQ**

Controls how frequent the simplex optimizer outputs information about the optimization and how frequent the user-defined callback function is called.

**Default** 1000

**Accepted** [0; +inf]

**Groups** *Simplex optimizer, Output information, Logging*

**MSK\_IPAR\_LOG\_SIM\_MINOR**

Currently not in use.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Simplex optimizer, Output information*

**MSK\_IPAR\_LOG\_STORAGE**

When turned on, **MOSEK** prints messages regarding the storage usage and allocation.

**Default** 0

**Accepted** [0; +inf]

**Groups** *Output information, Overall system, Logging*

**MSK\_IPAR\_MAX\_NUM\_WARNINGS**

Each warning is shown a limit number times controlled by this parameter. A negative value is identical to infinite number of times.

**Default** 10

**Accepted** [-inf; +inf]

**Groups** *Output information*

**MSK\_IPAR\_MIO\_BRANCH\_DIR**

Controls whether the mixed-integer optimizer is branching up or down by default.

**Default** *FREE*

**Accepted** *FREE, UP, DOWN, NEAR, FAR, ROOT\_LP, GUIDED, PSEUDOCOST*

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_CONSTRUCT\_SOL**

If set to *MSK\_ON* and all integer variables have been given a value for which a feasible mixed integer solution exists, then **MOSEK** generates an initial solution to the mixed integer problem by fixing all integer values and solving the remaining problem.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_CUT\_CLIQUE**

Controls whether clique cuts should be generated.

**Default** *ON*

**Accepted**

- *ON*: Turns generation of this cut class on.
- *OFF*: Turns generation of this cut class off.

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_CUT\_CMIR**

Controls whether mixed integer rounding cuts should be generated.

**Default** *ON*

**Accepted**

- *ON*: Turns generation of this cut class on.
- *OFF*: Turns generation of this cut class off.

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_CUT\_GMI**

Controls whether GMI cuts should be generated.

**Default** *ON*

**Accepted**

- *ON*: Turns generation of this cut class on.
- *OFF*: Turns generation of this cut class off.

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_CUT\_IMPLIED\_BOUND**

Controls whether implied bound cuts should be generated.

**Default** *OFF*

**Accepted**

- *ON*: Turns generation of this cut class on.
- *OFF*: Turns generation of this cut class off.

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_CUT\_KNAPSACK\_COVER**

Controls whether knapsack cover cuts should be generated.

**Default** *OFF*

**Accepted**

- *ON*: Turns generation of this cut class on.
- *OFF*: Turns generation of this cut class off.

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_CUT\_SELECTION\_LEVEL**

Controls how aggressively generated cuts are selected to be included in the relaxation.

- 1. The optimizer chooses the level of cut selection
- 0. Generated cuts less likely to be added to the relaxation
- 1. Cuts are more aggressively selected to be included in the relaxation

**Default** -1

**Accepted** [-1; +1]

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_HEURISTIC\_LEVEL**

Controls the heuristic employed by the mixed-integer optimizer to locate an initial good integer feasible solution. A value of zero means the heuristic is not used at all. A larger value than 0 means that a gradually more sophisticated heuristic is used which is computationally more expensive. A negative value implies that the optimizer chooses the heuristic. Normally a value around 3 to 5 should be optimal.

**Default** -1

**Accepted** [-inf; +inf]

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_MAX\_NUM\_BRANCHES**

Maximum number of branches allowed during the branch and bound search. A negative value means infinite.

**Default** -1

**Accepted** [-inf; +inf]

**Groups** *Mixed-integer optimization, Termination criteria*

**See also** *MSK\_DPAR\_MIO\_DISABLE\_TERM\_TIME*

**MSK\_IPAR\_MIO\_MAX\_NUM\_RELAXS**

Maximum number of relaxations allowed during the branch and bound search. A negative value means infinite.

**Default** -1

**Accepted** [-inf; +inf]

**Groups** *Mixed-integer optimization*

**See also** *MSK\_DPAR\_MIO\_DISABLE\_TERM\_TIME*

**MSK\_IPAR\_MIO\_MAX\_NUM\_SOLUTIONS**

The mixed-integer optimizer can be terminated after a certain number of different feasible solutions has been located. If this parameter has the value  $n > 0$ , then the mixed-integer optimizer will be terminated when  $n$  feasible solutions have been located.

**Default** -1

**Accepted** [-inf; +inf]

**Groups** *Mixed-integer optimization, Termination criteria*

**See also** *MSK\_DPAR\_MIO\_DISABLE\_TERM\_TIME*

**MSK\_IPAR\_MIO\_MODE**

Controls whether the optimizer includes the integer restrictions when solving a (mixed) integer optimization problem.

**Default** *SATISFIED*

**Accepted** *IGNORED, SATISFIED*

**Groups** *Overall solver*

MSK\_IPAR\_MIO\_MT\_USER\_CB

If true user callbacks are called from each thread used by mixed-integer optimizer. Otherwise it is only called from a single thread.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Overall system*

MSK\_IPAR\_MIO\_NODE\_OPTIMIZER

Controls which optimizer is employed at the non-root nodes in the mixed-integer optimizer.

**Default** *FREE*

**Accepted** *FREE, INTPNT, CONIC, PRIMAL\_SIMPLEX, DUAL\_SIMPLEX, FREE\_SIMPLEX, MIXED\_INT*

**Groups** *Mixed-integer optimization*

MSK\_IPAR\_MIO\_NODE\_SELECTION

Controls the node selection strategy employed by the mixed-integer optimizer.

**Default** *FREE*

**Accepted** *FREE, FIRST, BEST, WORST, HYBRID, PSEUDO*

**Groups** *Mixed-integer optimization*

MSK\_IPAR\_MIO\_PERSPECTIVE\_REFORMULATE

Enables or disables perspective reformulation in presolve.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Mixed-integer optimization*

MSK\_IPAR\_MIO\_PROBING\_LEVEL

Controls the amount of probing employed by the mixed-integer optimizer in presolve.

-1. The optimizer chooses the level of probing employed

0. Probing is disabled

1. A low amount of probing is employed

2. A medium amount of probing is employed

3. A high amount of probing is employed

**Default** *-1*

**Accepted** *[-1; 3]*

**Groups** *Mixed-integer optimization*

MSK\_IPAR\_MIO\_RINS\_MAX\_NODES

Controls the maximum number of nodes allowed in each call to the RINS heuristic. The default value of -1 means that the value is determined automatically. A value of zero turns off the heuristic.

**Default** *-1*

**Accepted** *[-1; +inf]*

**Groups** *Mixed-integer optimization*

MSK\_IPAR\_MIO\_ROOT\_OPTIMIZER

Controls which optimizer is employed at the root node in the mixed-integer optimizer.

**Default** *FREE*

**Accepted** *FREE, INTPNT, CONIC, PRIMAL\_SIMPLEX, DUAL\_SIMPLEX, FREE\_SIMPLEX, MIXED\_INT*

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_ROOT\_REPEAT\_PRESOLVE\_LEVEL**

Controls whether presolve can be repeated at root node.

- -1 The optimizer chooses whether presolve is repeated
- 0 Never repeat presolve
- 1 Always repeat presolve

**Default** -1

**Accepted** [-1; 1]

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MIO\_VB\_DETECTION\_LEVEL**

Controls how much effort is put into detecting variable bounds.

- 1. The optimizer chooses
- 0. No variable bounds are detected
- 1. Only detect variable bounds that are directly represented in the problem
- 2. Detect variable bounds in probing

**Default** -1

**Accepted** [-1; +2]

**Groups** *Mixed-integer optimization*

**MSK\_IPAR\_MT\_SPINCOUNT**

Set the number of iterations to spin before sleeping.

**Default** 0

**Accepted** [0; 1000000000]

**Groups** *Overall system*

**MSK\_IPAR\_NUM\_THREADS**

Controls the number of threads employed by the optimizer. If set to 0 the number of threads used will be equal to the number of cores detected on the machine.

**Default** 0

**Accepted** [0; +inf]

**Groups** *Overall system*

**MSK\_IPAR\_OPF\_MAX\_TERMS\_PER\_LINE**

The maximum number of terms (linear and quadratic) per line when an OPF file is written.

**Default** 5

**Accepted** [0; +inf]

**Groups** *Data input/output*

**MSK\_IPAR\_OPF\_WRITE\_HEADER**

Write a text header with date and **MOSEK** version in an OPF file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

#### MSK\_IPAR\_OPF\_WRITE\_HINTS

Write a hint section with problem dimensions in the beginning of an OPF file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

#### MSK\_IPAR\_OPF\_WRITE\_PARAMETERS

Write a parameter section in an OPF file.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

#### MSK\_IPAR\_OPF\_WRITE\_PROBLEM

Write objective, constraints, bounds etc. to an OPF file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

#### MSK\_IPAR\_OPF\_WRITE\_SOL\_BAS

If *MSK\_IPAR\_OPF\_WRITE\_SOLUTIONS* is *MSK\_ON* and a basic solution is defined, include the basic solution in OPF files.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

#### MSK\_IPAR\_OPF\_WRITE\_SOL\_ITG

If *MSK\_IPAR\_OPF\_WRITE\_SOLUTIONS* is *MSK\_ON* and an integer solution is defined, write the integer solution in OPF files.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

#### MSK\_IPAR\_OPF\_WRITE\_SOL\_ITR

If *MSK\_IPAR\_OPF\_WRITE\_SOLUTIONS* is *MSK\_ON* and an interior solution is defined, write the interior solution in OPF files.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

#### MSK\_IPAR\_OPF\_WRITE\_SOLUTIONS

Enable inclusion of solutions in the OPF files.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

#### MSK\_IPAR\_OPTIMIZER

The parameter controls which optimizer is used to optimize the task.

**Default** *FREE*

**Accepted** *FREE, INTPNT, CONIC, PRIMAL\_SIMPLEX, DUAL\_SIMPLEX, FREE\_SIMPLEX, MIXED\_INT*

**Groups** *Overall solver*

MSK\_IPAR\_PARAM\_READ\_CASE\_NAME

If turned on, then names in the parameter file are case sensitive.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

MSK\_IPAR\_PARAM\_READ\_IGN\_ERROR

If turned on, then errors in parameter settings is ignored.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

MSK\_IPAR\_PREOLVE\_ELIMINATOR\_MAX\_FILL

Controls the maximum amount of fill-in that can be created by one pivot in the elimination phase of the presolve. A negative value means the parameter value is selected automatically.

**Default** *-1*

**Accepted** *[-inf; +inf]*

**Groups** *Presolve*

MSK\_IPAR\_PREOLVE\_ELIMINATOR\_MAX\_NUM\_TRIES

Control the maximum number of times the eliminator is tried. A negative value implies **MOSEK** decides.

**Default** *-1*

**Accepted** *[-inf; +inf]*

**Groups** *Presolve*

MSK\_IPAR\_PREOLVE\_LEVEL

Currently not used.

**Default** *-1*

**Accepted** *[-inf; +inf]*

**Groups** *Overall solver, Presolve*

MSK\_IPAR\_PREOLVE\_LINDEP\_ABS\_WORK\_TRH

The linear dependency check is potentially computationally expensive.

**Default** *100*

**Accepted** *[-inf; +inf]*

**Groups** *Presolve*

MSK\_IPAR\_PREOLVE\_LINDEP\_REL\_WORK\_TRH

The linear dependency check is potentially computationally expensive.

**Default** *100*

**Accepted** *[-inf; +inf]*

**Groups** *Presolve*

MSK\_IPAR\_PREOLVE\_LINDEP\_USE

Controls whether the linear constraints are checked for linear dependencies.

**Default** *ON*

**Accepted**

- *ON*: Turns the linear dependency check on.
- *OFF*: Turns the linear dependency check off.

**Groups** *Presolve***MSK\_IPAR\_PRESOLVE\_MAX\_NUM\_REDUCTIONS**

Controls the maximum number of reductions performed by the presolve. The value of the parameter is normally only changed in connection with debugging. A negative value implies that an infinite number of reductions are allowed.

**Default** -1

**Accepted** [-inf; +inf]

**Groups** *Overall solver, Presolve*

**MSK\_IPAR\_PRESOLVE\_USE**

Controls whether the presolve is applied to a problem before it is optimized.

**Default** *FREE*

**Accepted** *OFF, ON, FREE*

**Groups** *Overall solver, Presolve*

**MSK\_IPAR\_PRIMAL\_REPAIR\_OPTIMIZER**

Controls which optimizer that is used to find the optimal repair.

**Default** *FREE*

**Accepted** *FREE, INTPNT, CONIC, PRIMAL\_SIMPLEX, DUAL\_SIMPLEX, FREE\_SIMPLEX, MIXED\_INT*

**Groups** *Overall solver*

**MSK\_IPAR\_READ\_DATA\_COMPRESSED**

If this option is turned on, it is assumed that the data file is compressed.

**Default** *FREE*

**Accepted** *NONE, FREE, GZIP*

**Groups** *Data input/output*

**MSK\_IPAR\_READ\_DATA\_FORMAT**

Format of the data file to be read.

**Default** *EXTENSION*

**Accepted** *EXTENSION, MPS, LP, OP, XML, FREE\_MPS, TASK, CB, JSON\_TASK*

**Groups** *Data input/output*

**MSK\_IPAR\_READ\_DEBUG**

Turns on additional debugging information when reading files.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

**MSK\_IPAR\_READ\_KEEP\_FREE\_CON**

Controls whether the free constraints are included in the problem.

**Default** *OFF*

**Accepted**

- *ON*: The free constraints are kept.

- *OFF*: The free constraints are discarded.

**Groups** *Data input/output*

**MSK\_IPAR\_READ\_LP\_DROP\_NEW\_VARS\_IN\_BOU**

If this option is turned on, **MOSEK** will drop variables that are defined for the first time in the bounds section.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

**MSK\_IPAR\_READ\_LP\_QUOTED\_NAMES**

If a name is in quotes when reading an LP file, the quotes will be removed.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

**MSK\_IPAR\_READ\_MPS\_FORMAT**

Controls how strictly the MPS file reader interprets the MPS format.

**Default** *FREE*

**Accepted** *STRICT, RELAXED, FREE, CPLEX*

**Groups** *Data input/output*

**MSK\_IPAR\_READ\_MPS\_WIDTH**

Controls the maximal number of characters allowed in one line of the MPS file.

**Default** 1024

**Accepted** [80; +inf]

**Groups** *Data input/output*

**MSK\_IPAR\_READ\_TASK\_IGNORE\_PARAM**

Controls whether **MOSEK** should ignore the parameter setting defined in the task file and use the default parameter setting instead.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

**MSK\_IPAR\_REMOVE\_UNUSED\_SOLUTIONS**

Removes unused solutions before the optimization is performed.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Overall system*

**MSK\_IPAR\_SENSITIVITY\_ALL**

Not applicable.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Overall solver*

**MSK\_IPAR\_SENSITIVITY\_OPTIMIZER**

Controls which optimizer is used for optimal partition sensitivity analysis.

**Default** *FREE\_SIMPLEX*

**Accepted** *FREE, INTPNT, CONIC, PRIMAL\_SIMPLEX, DUAL\_SIMPLEX, FREE\_SIMPLEX, MIXED\_INT*

**Groups** *Overall solver, Simplex optimizer*

#### MSK\_IPAR\_SENSITIVITY\_TYPE

Controls which type of sensitivity analysis is to be performed.

**Default** *BASIS*

**Accepted** *BASIS, OPTIMAL\_PARTITION*

**Groups** *Overall solver*

#### MSK\_IPAR\_SIM\_BASIS\_FACTOR\_USE

Controls whether an LU factorization of the basis is used in a hot-start. Forcing a refactorization sometimes improves the stability of the simplex optimizers, but in most cases there is a performance penalty.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Simplex optimizer*

#### MSK\_IPAR\_SIM\_DEGEN

Controls how aggressively degeneration is handled.

**Default** *FREE*

**Accepted** *NONE, FREE, AGGRESSIVE, MODERATE, MINIMUM*

**Groups** *Simplex optimizer*

#### MSK\_IPAR\_SIM\_DUAL\_CRASH

Controls whether crashing is performed in the dual simplex optimizer.

If this parameter is set to  $x$ , then a crash will be performed if a basis consists of more than  $(100 - x) \bmod f_v$  entries, where  $f_v$  is the number of fixed variables.

**Default** *90*

**Accepted** *[0; +inf]*

**Groups** *Dual simplex*

#### MSK\_IPAR\_SIM\_DUAL\_PHASEONE\_METHOD

An experimental feature.

**Default** *0*

**Accepted** *[0; 10]*

**Groups** *Simplex optimizer*

#### MSK\_IPAR\_SIM\_DUAL\_RESTRICT\_SELECTION

The dual simplex optimizer can use a so-called restricted selection/pricing strategy to choose the outgoing variable. Hence, if restricted selection is applied, then the dual simplex optimizer first choose a subset of all the potential outgoing variables. Next, for some time it will choose the outgoing variable only among the subset. From time to time the subset is redefined.

A larger value of this parameter implies that the optimizer will be more aggressive in its restriction strategy, i.e. a value of 0 implies that the restriction strategy is not applied at all.

**Default** *50*

**Accepted** *[0; 100]*

**Groups** *Dual simplex*

**MSK\_IPAR\_SIM\_DUAL\_SELECTION**

Controls the choice of the incoming variable, known as the selection strategy, in the dual simplex optimizer.

**Default** *FREE*

**Accepted** *FREE, FULL, ASE, DEVEX, SE, PARTIAL*

**Groups** *Dual simplex*

**MSK\_IPAR\_SIM\_EXPLOIT\_DUPVEC**

Controls if the simplex optimizers are allowed to exploit duplicated columns.

**Default** *OFF*

**Accepted** *ON, OFF, FREE*

**Groups** *Simplex optimizer*

**MSK\_IPAR\_SIM\_HOTSTART**

Controls the type of hot-start that the simplex optimizer perform.

**Default** *FREE*

**Accepted** *NONE, FREE, STATUS\_KEYS*

**Groups** *Simplex optimizer*

**MSK\_IPAR\_SIM\_HOTSTART\_LU**

Determines if the simplex optimizer should exploit the initial factorization.

**Default** *ON*

**Accepted**

- *ON*: Factorization is reused if possible.
- *OFF*: Factorization is recomputed.

**Groups** *Simplex optimizer*

**MSK\_IPAR\_SIM\_MAX\_ITERATIONS**

Maximum number of iterations that can be used by a simplex optimizer.

**Default** 10000000

**Accepted** [0; +inf]

**Groups** *Simplex optimizer, Termination criteria*

**MSK\_IPAR\_SIM\_MAX\_NUM\_SETBACKS**

Controls how many set-backs are allowed within a simplex optimizer. A set-back is an event where the optimizer moves in the wrong direction. This is impossible in theory but may happen due to numerical problems.

**Default** 250

**Accepted** [0; +inf]

**Groups** *Simplex optimizer*

**MSK\_IPAR\_SIM\_NON\_SINGULAR**

Controls if the simplex optimizer ensures a non-singular basis, if possible.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Simplex optimizer*

**MSK\_IPAR\_SIM\_PRIMAL\_CRASH**

Controls whether crashing is performed in the primal simplex optimizer.

In general, if a basis consists of more than (100-this parameter value)% fixed variables, then a crash will be performed.

**Default** 90

**Accepted** [0; +inf]

**Groups** *Primal simplex*

**MSK\_IPAR\_SIM\_PRIMAL\_PHASEONE\_METHOD**

An experimental feature.

**Default** 0

**Accepted** [0; 10]

**Groups** *Simplex optimizer*

**MSK\_IPAR\_SIM\_PRIMAL\_RESTRICT\_SELECTION**

The primal simplex optimizer can use a so-called restricted selection/pricing strategy to choose the outgoing variable. Hence, if restricted selection is applied, then the primal simplex optimizer first choose a subset of all the potential incoming variables. Next, for some time it will choose the incoming variable only among the subset. From time to time the subset is redefined.

A larger value of this parameter implies that the optimizer will be more aggressive in its restriction strategy, i.e. a value of 0 implies that the restriction strategy is not applied at all.

**Default** 50

**Accepted** [0; 100]

**Groups** *Primal simplex*

**MSK\_IPAR\_SIM\_PRIMAL\_SELECTION**

Controls the choice of the incoming variable, known as the selection strategy, in the primal simplex optimizer.

**Default** *FREE*

**Accepted** *FREE*, *FULL*, *ASE*, *DEVEX*, *SE*, *PARTIAL*

**Groups** *Primal simplex*

**MSK\_IPAR\_SIM\_REFACTOR\_FREQ**

Controls how frequent the basis is refactorized. The value 0 means that the optimizer determines the best point of refactorization.

It is strongly recommended NOT to change this parameter.

**Default** 0

**Accepted** [0; +inf]

**Groups** *Simplex optimizer*

**MSK\_IPAR\_SIM\_REFORMULATION**

Controls if the simplex optimizers are allowed to reformulate the problem.

**Default** *OFF*

**Accepted** *ON*, *OFF*, *FREE*, *AGGRESSIVE*

**Groups** *Simplex optimizer*

**MSK\_IPAR\_SIM\_SAVE\_LU**

Controls if the LU factorization stored should be replaced with the LU factorization corresponding to the initial basis.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Simplex optimizer*

#### MSK\_IPAR\_SIM\_SCALING

Controls how much effort is used in scaling the problem before a simplex optimizer is used.

**Default** *FREE*

**Accepted** *FREE, NONE, MODERATE, AGGRESSIVE*

**Groups** *Simplex optimizer*

#### MSK\_IPAR\_SIM\_SCALING\_METHOD

Controls how the problem is scaled before a simplex optimizer is used.

**Default** *POW2*

**Accepted** *POW2, FREE*

**Groups** *Simplex optimizer*

#### MSK\_IPAR\_SIM\_SOLVE\_FORM

Controls whether the primal or the dual problem is solved by the primal-/dual-simplex optimizer.

**Default** *FREE*

**Accepted** *FREE, PRIMAL, DUAL*

**Groups** *Simplex optimizer*

#### MSK\_IPAR\_SIM\_STABILITY\_PRIORITY

Controls how high priority the numerical stability should be given.

**Default** *50*

**Accepted** *[0; 100]*

**Groups** *Simplex optimizer*

#### MSK\_IPAR\_SIM\_SWITCH\_OPTIMIZER

The simplex optimizer sometimes chooses to solve the dual problem instead of the primal problem. This implies that if you have chosen to use the dual simplex optimizer and the problem is dualized, then it actually makes sense to use the primal simplex optimizer instead. If this parameter is on and the problem is dualized and furthermore the simplex optimizer is chosen to be the primal (dual) one, then it is switched to the dual (primal).

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Simplex optimizer*

#### MSK\_IPAR\_SOL\_FILTER\_KEEP\_BASIC

If turned on, then basic and super basic constraints and variables are written to the solution file independent of the filter setting.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Solution input/output*

#### MSK\_IPAR\_SOL\_FILTER\_KEEP\_RANGED

If turned on, then ranged constraints and variables are written to the solution file independent of the filter setting.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Solution input/output*

**MSK\_IPAR\_SOL\_READ\_NAME\_WIDTH**

When a solution is read by **MOSEK** and some constraint, variable or cone names contain blanks, then a maximum name width must be specified. A negative value implies that no name contains blanks.

**Default** -1

**Accepted** [-inf; +inf]

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_SOL\_READ\_WIDTH**

Controls the maximal acceptable width of line in the solutions when read by **MOSEK**.

**Default** 1024

**Accepted** [80; +inf]

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_SOLUTION\_CALLBACK**

Indicates whether solution callbacks will be performed during the optimization.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Progress callback, Overall solver*

**MSK\_IPAR\_TIMING\_LEVEL**

Controls the amount of timing performed inside **MOSEK**.

**Default** 1

**Accepted** [0; +inf]

**Groups** *Overall system*

**MSK\_IPAR\_WRITE\_BAS\_CONSTRAINTS**

Controls whether the constraint section is written to the basic solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_BAS\_HEAD**

Controls whether the header section is written to the basic solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_BAS\_VARIABLES**

Controls whether the variables section is written to the basic solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_DATA\_COMPRESSED**

Controls whether the data file is compressed while it is written. 0 means no compression while higher values mean more compression.

**Default** 0

**Accepted** [0; +inf]

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_DATA\_FORMAT**

Controls the file format when writing task data to a file.

**Default** *EXTENSION*

**Accepted** *EXTENSION, MPS, LP, OP, XML, FREE\_MPS, TASK, CB, JSON\_TASK*

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_DATA\_PARAM**

If this option is turned on the parameter settings are written to the data file as parameters.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_FREE\_CON**

Controls whether the free constraints are written to the data file.

**Default** *ON*

**Accepted**

- *ON*: The free constraints are written.
- *OFF*: The free constraints are discarded.

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_GENERIC\_NAMES**

Controls whether the generic names or user-defined names are used in the data file.

**Default** *OFF*

**Accepted**

- *ON*: Generic names are used.
- *OFF*: Generic names are not used.

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_GENERIC\_NAMES\_IO**

Index origin used in generic names.

**Default** *1*

**Accepted** *[0; +inf]*

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_IGNORE\_INCOMPATIBLE\_ITEMS**

Controls if the writer ignores incompatible problem items when writing files.

**Default** *OFF*

**Accepted**

- *ON*: Ignore items that cannot be written to the current output file format.
- *OFF*: Produce an error if the problem contains items that cannot be written to the current output file format.

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_INT\_CONSTRAINTS**

Controls whether the constraint section is written to the integer solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_INT\_HEAD**

Controls whether the header section is written to the integer solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_INT\_VARIABLES**

Controls whether the variables section is written to the integer solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_LP\_FULL\_OBJ**

Write all variables, including the ones with 0-coefficients, in the objective.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_LP\_LINE\_WIDTH**

Maximum width of line in an LP file written by **MOSEK**.

**Default** 80

**Accepted** [40; +inf]

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_LP\_QUOTED\_NAMES**

If this option is turned on, then **MOSEK** will quote invalid LP names when writing an LP file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_LP\_STRICT\_FORMAT**

Controls whether LP output files satisfy the LP format strictly.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_LP\_TERMS\_PER\_LINE**

Maximum number of terms on a single line in an LP file written by **MOSEK**. 0 means unlimited.

**Default** 10

**Accepted** [0; +inf]

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_MPS\_FORMAT**

Controls in which format the MPS is written.

**Default** *FREE*

**Accepted** *STRICT, RELAXED, FREE, CPLEX*

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_MPS\_INT**

Controls if marker records are written to the MPS file to indicate whether variables are integer restricted.

**Default** *ON*

**Accepted**

- *ON*: Marker records are written.
- *OFF*: Marker records are not written.

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_PRECISION**

Controls the precision with which **double** numbers are printed in the MPS data file. In general it is not worthwhile to use a value higher than 15.

**Default** 15

**Accepted** [0; +inf]

**Groups** *Data input/output*

**MSK\_IPAR\_WRITE\_SOL\_BARVARIABLES**

Controls whether the symmetric matrix variables section is written to the solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_SOL\_CONSTRAINTS**

Controls whether the constraint section is written to the solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_SOL\_HEAD**

Controls whether the header section is written to the solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_SOL\_IGNORE\_INVALID\_NAMES**

Even if the names are invalid MPS names, then they are employed when writing the solution file.

**Default** *OFF*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_SOL\_VARIABLES**

Controls whether the variables section is written to the solution file.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output, Solution input/output*

**MSK\_IPAR\_WRITE\_TASK\_INC\_SOL**

Controls whether the solutions are stored in the task file too.

**Default** *ON*

**Accepted** *ON, OFF*

**Groups** *Data input/output*

MSK\_IPAR\_WRITE\_XML\_MODE

Controls if linear coefficients should be written by row or column when writing in the XML file format.

**Default** *ROW*

**Accepted** *ROW, COL*

**Groups** *Data input/output*

### 11.3.3 String parameters

MSK\_SPAR\_BAS\_SOL\_FILE\_NAME

Name of the *bas* solution file.

**Accepted** Any valid file name.

**Groups** *Data input/output, Solution input/output*

MSK\_SPAR\_DATA\_FILE\_NAME

Data are read and written to this file.

**Accepted** Any valid file name.

**Groups** *Data input/output*

MSK\_SPAR\_DEBUG\_FILE\_NAME

**MOSEK** debug file.

**Accepted** Any valid file name.

**Groups** *Data input/output*

MSK\_SPAR\_INT\_SOL\_FILE\_NAME

Name of the *int* solution file.

**Accepted** Any valid file name.

**Groups** *Data input/output, Solution input/output*

MSK\_SPAR\_ITR\_SOL\_FILE\_NAME

Name of the *itr* solution file.

**Accepted** Any valid file name.

**Groups** *Data input/output, Solution input/output*

MSK\_SPAR\_MIO\_DEBUG\_STRING

For internal debugging purposes.

**Accepted** Any valid string.

**Groups** *Data input/output*

MSK\_SPAR\_PARAM\_COMMENT\_SIGN

Only the first character in this string is used. It is considered as a start of comment sign in the **MOSEK** parameter file. Spaces are ignored in the string.

**Default**

*%%*

**Accepted** Any valid string.

**Groups** *Data input/output*

**MSK\_SPAR\_PARAM\_READ\_FILE\_NAME**

Modifications to the parameter database is read from this file.

**Accepted** Any valid file name.

**Groups** *Data input/output*

**MSK\_SPAR\_PARAM\_WRITE\_FILE\_NAME**

The parameter database is written to this file.

**Accepted** Any valid file name.

**Groups** *Data input/output*

**MSK\_SPAR\_READ\_MPS\_BOU\_NAME**

Name of the BOUNDS vector used. An empty name means that the first BOUNDS vector is used.

**Accepted** Any valid MPS name.

**Groups** *Data input/output*

**MSK\_SPAR\_READ\_MPS\_OBJ\_NAME**

Name of the free constraint used as objective function. An empty name means that the first constraint is used as objective function.

**Accepted** Any valid MPS name.

**Groups** *Data input/output*

**MSK\_SPAR\_READ\_MPS\_RAN\_NAME**

Name of the RANGE vector used. An empty name means that the first RANGE vector is used.

**Accepted** Any valid MPS name.

**Groups** *Data input/output*

**MSK\_SPAR\_READ\_MPS\_RHS\_NAME**

Name of the RHS used. An empty name means that the first RHS vector is used.

**Accepted** Any valid MPS name.

**Groups** *Data input/output*

**MSK\_SPAR\_REMOTE\_ACCESS\_TOKEN**

An access token used to submit tasks to a remote **MOSEK** server. An access token is a random 32-byte string encoded in base64, i.e. it is a 44 character ASCII string.

**Accepted** Any valid string.

**Groups** *Overall system*

**MSK\_SPAR\_SENSITIVITY\_FILE\_NAME**

If defined, **MOSEK** reads this file as a sensitivity analysis data file specifying the type of analysis to be done.

**Accepted** Any valid string.

**Groups** *Data input/output*

**MSK\_SPAR\_SENSITIVITY\_RES\_FILE\_NAME**

**Accepted** Any valid string.

**Groups** *Data input/output*

**MSK\_SPAR\_SOL\_FILTER\_XC\_LOW**

A filter used to determine which constraints should be listed in the solution file. A value of 0.5 means that all constraints having  $xc[i] > 0.5$  should be listed, whereas +0.5 means that all constraints having  $xc[i] \geq blc[i] + 0.5$  should be listed. An empty filter means that no filter is applied.

**Accepted** Any valid filter.

**Groups** *Data input/output, Solution input/output*

**MSK\_SPAR\_SOL\_FILTER\_XC\_UPR**

A filter used to determine which constraints should be listed in the solution file. A value of 0.5 means that all constraints having  $xc[i] < 0.5$  should be listed, whereas -0.5 means all constraints having  $xc[i] \leq buc[i] - 0.5$  should be listed. An empty filter means that no filter is applied.

**Accepted** Any valid filter.

**Groups** *Data input/output, Solution input/output*

**MSK\_SPAR\_SOL\_FILTER\_XX\_LOW**

A filter used to determine which variables should be listed in the solution file. A value of “0.5” means that all constraints having  $xx[j] \geq 0.5$  should be listed, whereas “+0.5” means that all constraints having  $xx[j] \geq blx[j] + 0.5$  should be listed. An empty filter means no filter is applied.

**Accepted** Any valid filter.

**Groups** *Data input/output, Solution input/output*

**MSK\_SPAR\_SOL\_FILTER\_XX\_UPR**

A filter used to determine which variables should be listed in the solution file. A value of “0.5” means that all constraints having  $xx[j] < 0.5$  should be printed, whereas “-0.5” means all constraints having  $xx[j] \leq bux[j] - 0.5$  should be listed. An empty filter means no filter is applied.

**Accepted** Any valid file name.

**Groups** *Data input/output, Solution input/output*

**MSK\_SPAR\_STAT\_FILE\_NAME**

Statistics file name.

**Accepted** Any valid file name.

**Groups** *Data input/output*

**MSK\_SPAR\_STAT\_KEY**

Key used when writing the summary file.

**Accepted** Any valid string.

**Groups** *Data input/output*

**MSK\_SPAR\_STAT\_NAME**

Name used when writing the statistics file.

**Accepted** Any valid XML string.

**Groups** *Data input/output*

**MSK\_SPAR\_WRITE\_LP\_GEN\_VAR\_NAME**

Sometimes when an LP file is written additional variables must be inserted. They will have the prefix denoted by this parameter.

**Default** xmskgen

**Accepted** Any valid string.

**Groups** *Data input/output*

## 11.4 Response codes

- *Termination*
- *Warnings*
- *Errors*

### 11.4.1 Termination

#### MSK\_RES\_OK

No error occurred.

#### MSK\_RES\_TRM\_MAX\_ITERATIONS

The optimizer terminated at the maximum number of iterations.

#### MSK\_RES\_TRM\_MAX\_TIME

The optimizer terminated at the maximum amount of time.

#### MSK\_RES\_TRM\_OBJECTIVE\_RANGE

The optimizer terminated with an objective value outside the objective range.

#### MSK\_RES\_TRM\_MIO\_NEAR\_REL\_GAP

The mixed-integer optimizer terminated as the delayed near optimal relative gap tolerance was satisfied.

#### MSK\_RES\_TRM\_MIO\_NEAR\_ABS\_GAP

The mixed-integer optimizer terminated as the delayed near optimal absolute gap tolerance was satisfied.

#### MSK\_RES\_TRM\_MIO\_NUM\_RELAXS

The mixed-integer optimizer terminated as the maximum number of relaxations was reached.

#### MSK\_RES\_TRM\_MIO\_NUM\_BRANCHES

The mixed-integer optimizer terminated as the maximum number of branches was reached.

#### MSK\_RES\_TRM\_NUM\_MAX\_NUM\_INT\_SOLUTIONS

The mixed-integer optimizer terminated as the maximum number of feasible solutions was reached.

#### MSK\_RES\_TRM\_STALL

The optimizer is terminated due to slow progress.

Stalling means that numerical problems prevent the optimizer from making reasonable progress and that it make no sense to continue. In many cases this happens if the problem is badly scaled or otherwise ill-conditioned. There is no guarantee that the solution will be (near) feasible or near optimal. However, often stalling happens near the optimum, and the returned solution may be of good quality. Therefore, it is recommended to check the status of then solution. If the solution near optimal the solution is most likely good enough for most practical purposes.

Please note that if a linear optimization problem is solved using the interior-point optimizer with basis identification turned on, the returned basic solution likely to have high accuracy, even though the optimizer stalled.

Some common causes of stalling are a) badly scaled models, b) near feasible or near infeasible problems and c) a non-convex problems. Case c) is only relevant for general non-linear problems. It is not possible in general for **MOSEK** to check if a specific problems is convex since such a check would be NP hard in itself. This implies that care should be taken when solving problems involving general user defined functions.

#### MSK\_RES\_TRM\_USER\_CALLBACK

The optimizer terminated due to the return of the user-defined callback function.

#### MSK\_RES\_TRM\_MAX\_NUM\_SETBACKS

The optimizer terminated as the maximum number of set-backs was reached. This indicates serious numerical problems and a possibly badly formulated problem.

#### MSK\_RES\_TRM\_NUMERICAL\_PROBLEM

The optimizer terminated due to numerical problems.

#### MSK\_RES\_TRM\_INTERNAL

The optimizer terminated due to some internal reason. Please contact **MOSEK** support.

#### MSK\_RES\_TRM\_INTERNAL\_STOP

The optimizer terminated for internal reasons. Please contact **MOSEK** support.

## 11.4.2 Warnings

### MSK\_RES\_WRN\_OPEN\_PARAM\_FILE

The parameter file could not be opened.

### MSK\_RES\_WRN\_LARGE\_BOUND

A numerically large bound value is specified.

### MSK\_RES\_WRN\_LARGE\_LO\_BOUND

A numerically large lower bound value is specified.

### MSK\_RES\_WRN\_LARGE\_UP\_BOUND

A numerically large upper bound value is specified.

### MSK\_RES\_WRN\_LARGE\_CON\_FX

An equality constraint is fixed to a numerically large value. This can cause numerical problems.

### MSK\_RES\_WRN\_LARGE\_CJ

A numerically large value is specified for one  $c_j$ .

### MSK\_RES\_WRN\_LARGE\_AIJ

A numerically large value is specified for an  $a_{i,j}$  element in  $A$ . The parameter *MSK\_DPAR\_DATA\_TOL\_AIJ\_LARGE* controls when an  $a_{i,j}$  is considered large.

### MSK\_RES\_WRN\_ZERO\_AIJ

One or more zero elements are specified in  $A$ .

### MSK\_RES\_WRN\_NAME\_MAX\_LEN

A name is longer than the buffer that is supposed to hold it.

### MSK\_RES\_WRN\_SPAR\_MAX\_LEN

A value for a string parameter is longer than the buffer that is supposed to hold it.

### MSK\_RES\_WRN\_MPS\_SPLIT\_RHS\_VECTOR

An RHS vector is split into several nonadjacent parts in an MPS file.

### MSK\_RES\_WRN\_MPS\_SPLIT\_RAN\_VECTOR

A RANGE vector is split into several nonadjacent parts in an MPS file.

### MSK\_RES\_WRN\_MPS\_SPLIT\_BOU\_VECTOR

A BOUNDS vector is split into several nonadjacent parts in an MPS file.

### MSK\_RES\_WRN\_LP\_OLD\_QUAD\_FORMAT

Missing  $/2$  after quadratic expressions in bound or objective.

### MSK\_RES\_WRN\_LP\_DROP\_VARIABLE

Ignored a variable because the variable was not previously defined. Usually this implies that a variable appears in the bound section but not in the objective or the constraints.

### MSK\_RES\_WRN\_NZ\_IN\_UPR\_TRI

Non-zero elements specified in the upper triangle of a matrix were ignored.

### MSK\_RES\_WRN\_DROPPED\_NZ\_QOBJ

One or more non-zero elements were dropped in the  $Q$  matrix in the objective.

### MSK\_RES\_WRN\_IGNORE\_INTEGER

Ignored integer constraints.

### MSK\_RES\_WRN\_NO\_GLOBAL\_OPTIMIZER

No global optimizer is available.

### MSK\_RES\_WRN\_MIO\_INFEASIBLE\_FINAL

The final mixed-integer problem with all the integer variables fixed at their optimal values is infeasible.

### MSK\_RES\_WRN\_SOL\_FILTER

Invalid solution filter is specified.

**MSK\_RES\_WRN\_UNDEF\_SOL\_FILE\_NAME**

Undefined name occurred in a solution.

**MSK\_RES\_WRN\_SOL\_FILE\_IGNORED\_CON**

One or more lines in the constraint section were ignored when reading a solution file.

**MSK\_RES\_WRN\_SOL\_FILE\_IGNORED\_VAR**

One or more lines in the variable section were ignored when reading a solution file.

**MSK\_RES\_WRN\_TOO\_FEW\_BASIS\_VARS**

An incomplete basis has been specified. Too few basis variables are specified.

**MSK\_RES\_WRN\_TOO\_MANY\_BASIS\_VARS**

A basis with too many variables has been specified.

**MSK\_RES\_WRN\_NO\_NONLINEAR\_FUNCTION\_WRITE**

The problem contains a general nonlinear function in either the objective or the constraints. Such a nonlinear function cannot be written to a disk file. Note that quadratic terms when inputted explicitly can be written to disk.

**MSK\_RES\_WRN\_LICENSE\_EXPIRE**

The license expires.

**MSK\_RES\_WRN\_LICENSE\_SERVER**

The license server is not responding.

**MSK\_RES\_WRN\_EMPTY\_NAME**

A variable or constraint name is empty. The output file may be invalid.

**MSK\_RES\_WRN\_USING\_GENERIC\_NAMES**

Generic names are used because a name is not valid. For instance when writing an LP file the names must not contain blanks or start with a digit.

**MSK\_RES\_WRN\_LICENSE\_FEATURE\_EXPIRE**

The license expires.

**MSK\_RES\_WRN\_PARAM\_NAME\_DOUB**

The parameter name is not recognized as a double parameter.

**MSK\_RES\_WRN\_PARAM\_NAME\_INT**

The parameter name is not recognized as an integer parameter.

**MSK\_RES\_WRN\_PARAM\_NAME\_STR**

The parameter name is not recognized as a string parameter.

**MSK\_RES\_WRN\_PARAM\_STR\_VALUE**

The string is not recognized as a symbolic value for the parameter.

**MSK\_RES\_WRN\_PARAM\_IGNORED\_CMIO**

A parameter was ignored by the conic mixed integer optimizer.

**MSK\_RES\_WRN\_ZEROS\_IN\_SPARSE\_ROW**

One or more (near) zero elements are specified in a sparse row of a matrix. Since, it is redundant to specify zero elements then it may indicate an error.

**MSK\_RES\_WRN\_ZEROS\_IN\_SPARSE\_COL**

One or more (near) zero elements are specified in a sparse column of a matrix. It is redundant to specify zero elements. Hence, it may indicate an error.

**MSK\_RES\_WRN\_INCOMPLETE\_LINEAR\_DEPENDENCY\_CHECK**

The linear dependency check(s) is incomplete. Normally this is not an important warning unless the optimization problem has been formulated with linear dependencies. Linear dependencies may prevent **MOSEK** from solving the problem.

**MSK\_RES\_WRN\_ELIMINATOR\_SPACE**

The eliminator is skipped at least once due to lack of space.

**MSK\_RES\_WRN\_PREOLVE\_OUTOFSPACE**

The presolve is incomplete due to lack of space.

**MSK\_RES\_WRN\_WRITE\_CHANGED\_NAMES**

Some names were changed because they were invalid for the output file format.

**MSK\_RES\_WRN\_WRITE\_DISCARDED\_CFIX**

The fixed objective term could not be converted to a variable and was discarded in the output file.

**MSK\_RES\_WRN\_CONSTRUCT\_SOLUTION\_INFEAS**

After fixing the integer variables at the suggested values then the problem is infeasible.

**MSK\_RES\_WRN\_CONSTRUCT\_INVALID\_SOL\_ITG**

The initial value for one or more of the integer variables is not feasible.

**MSK\_RES\_WRN\_CONSTRUCT\_NO\_SOL\_ITG**

The construct solution requires an integer solution.

**MSK\_RES\_WRN\_DUPLICATE\_CONSTRAINT\_NAMES**

Two constraint names are identical.

**MSK\_RES\_WRN\_DUPLICATE\_VARIABLE\_NAMES**

Two variable names are identical.

**MSK\_RES\_WRN\_DUPLICATE\_BARVARIABLE\_NAMES**

Two barvariable names are identical.

**MSK\_RES\_WRN\_DUPLICATE\_CONE\_NAMES**

Two cone names are identical.

**MSK\_RES\_WRN\_ANA\_LARGE\_BOUNDS**

This warning is issued by the problem analyzer, if one or more constraint or variable bounds are very large. One should consider omitting these bounds entirely by setting them to  $+\text{inf}$  or  $-\text{inf}$ .

**MSK\_RES\_WRN\_ANA\_C\_ZERO**

This warning is issued by the problem analyzer, if the coefficients in the linear part of the objective are all zero.

**MSK\_RES\_WRN\_ANA\_EMPTY\_COLS**

This warning is issued by the problem analyzer, if columns, in which all coefficients are zero, are found.

**MSK\_RES\_WRN\_ANA\_CLOSE\_BOUNDS**

This warning is issued by problem analyzer, if ranged constraints or variables with very close upper and lower bounds are detected. One should consider treating such constraints as equalities and such variables as constants.

**MSK\_RES\_WRN\_ANA\_ALMOST\_INT\_BOUNDS**

This warning is issued by the problem analyzer if a constraint is bound nearly integral.

**MSK\_RES\_WRN\_QUAD\_CONES\_WITH\_ROOT\_FIXED\_AT\_ZERO**

For at least one quadratic cone the root is fixed at (nearly) zero. This may cause problems such as a very large dual solution. Therefore, it is recommended to remove such cones before optimizing the problems, or to fix all the variables in the cone to 0.

**MSK\_RES\_WRN\_RQUAD\_CONES\_WITH\_ROOT\_FIXED\_AT\_ZERO**

For at least one rotated quadratic cone at least one of the root variables are fixed at (nearly) zero. This may cause problems such as a very large dual solution. Therefore, it is recommended to remove such cones before optimizing the problems, or to fix all the variables in the cone to 0.

**MSK\_RES\_WRN\_NO\_DUALIZER**

No automatic dualizer is available for the specified problem. The primal problem is solved.

**MSK\_RES\_WRN\_SYM\_MAT\_LARGE**

A numerically large value is specified for an  $e_{i,j}$  element in  $E$ . The parameter `MSK_DPAR_DATA_SYM_MAT_TOL_LARGE` controls when an  $e_{i,j}$  is considered large.

### 11.4.3 Errors

MSK\_RES\_ERR\_LICENSE

Invalid license.

MSK\_RES\_ERR\_LICENSE\_EXPIRED

The license has expired.

MSK\_RES\_ERR\_LICENSE\_VERSION

The license is valid for another version of **MOSEK**.

MSK\_RES\_ERR\_SIZE\_LICENSE

The problem is bigger than the license.

MSK\_RES\_ERR\_PROB\_LICENSE

The software is not licensed to solve the problem.

MSK\_RES\_ERR\_FILE\_LICENSE

Invalid license file.

MSK\_RES\_ERR\_MISSING\_LICENSE\_FILE

**MOSEK** cannot license file or a token server. See the **MOSEK** installation manual for details.

MSK\_RES\_ERR\_SIZE\_LICENSE\_CON

The problem has too many constraints to be solved with the available license.

MSK\_RES\_ERR\_SIZE\_LICENSE\_VAR

The problem has too many variables to be solved with the available license.

MSK\_RES\_ERR\_SIZE\_LICENSE\_INTVAR

The problem contains too many integer variables to be solved with the available license.

MSK\_RES\_ERR\_OPTIMIZER\_LICENSE

The optimizer required is not licensed.

MSK\_RES\_ERR\_FLEXLM

The FLEXlm license manager reported an error.

MSK\_RES\_ERR\_LICENSE\_SERVER

The license server is not responding.

MSK\_RES\_ERR\_LICENSE\_MAX

Maximum number of licenses is reached.

MSK\_RES\_ERR\_LICENSE\_MOSEKLM\_DAEMON

The MOSEKLM license manager daemon is not up and running.

MSK\_RES\_ERR\_LICENSE\_FEATURE

A requested feature is not available in the license file(s). Most likely due to an incorrect license system setup.

MSK\_RES\_ERR\_PLATFORM\_NOT\_LICENSED

A requested license feature is not available for the required platform.

MSK\_RES\_ERR\_LICENSE\_CANNOT\_ALLOCATE

The license system cannot allocate the memory required.

MSK\_RES\_ERR\_LICENSE\_CANNOT\_CONNECT

**MOSEK** cannot connect to the license server. Most likely the license server is not up and running.

MSK\_RES\_ERR\_LICENSE\_INVALID\_HOSTID

The host ID specified in the license file does not match the host ID of the computer.

MSK\_RES\_ERR\_LICENSE\_SERVER\_VERSION

The version specified in the checkout request is greater than the highest version number the daemon supports.

MSK\_RES\_ERR\_LICENSE\_NO\_SERVER\_SUPPORT

The license server does not support the requested feature. Possible reasons for this error include:

- The feature has expired.
- The feature's start date is later than today's date.
- The version requested is higher than feature's the highest supported version.
- A corrupted license file.

Try restarting the license and inspect the license server debug file, usually called `lmgrd.log`.

**MSK\_RES\_ERR\_LICENSE\_NO\_SERVER\_LINE**

There is no **SERVER** line in the license file. All non-zero license count features need at least one **SERVER** line.

**MSK\_RES\_ERR\_OPEN\_DL**

A dynamic link library could not be opened.

**MSK\_RES\_ERR\_OLDER\_DLL**

The dynamic link library is older than the specified version.

**MSK\_RES\_ERR\_NEWER\_DLL**

The dynamic link library is newer than the specified version.

**MSK\_RES\_ERR\_LINK\_FILE\_DLL**

A file cannot be linked to a stream in the DLL version.

**MSK\_RES\_ERR\_THREAD\_MUTEX\_INIT**

Could not initialize a mutex.

**MSK\_RES\_ERR\_THREAD\_MUTEX\_LOCK**

Could not lock a mutex.

**MSK\_RES\_ERR\_THREAD\_MUTEX\_UNLOCK**

Could not unlock a mutex.

**MSK\_RES\_ERR\_THREAD\_CREATE**

Could not create a thread. This error may occur if a large number of environments are created and not deleted again. In any case it is a good practice to minimize the number of environments created.

**MSK\_RES\_ERR\_THREAD\_COND\_INIT**

Could not initialize a condition.

**MSK\_RES\_ERR\_UNKNOWN**

Unknown error.

**MSK\_RES\_ERR\_SPACE**

Out of space.

**MSK\_RES\_ERR\_FILE\_OPEN**

Error while opening a file.

**MSK\_RES\_ERR\_FILE\_READ**

File read error.

**MSK\_RES\_ERR\_FILE\_WRITE**

File write error.

**MSK\_RES\_ERR\_DATA\_FILE\_EXT**

The data file format cannot be determined from the file name.

**MSK\_RES\_ERR\_INVALID\_FILE\_NAME**

An invalid file name has been specified.

**MSK\_RES\_ERR\_INVALID\_SOL\_FILE\_NAME**

An invalid file name has been specified.

**MSK\_RES\_ERR\_END\_OF\_FILE**

End of file reached.

|                                 |   |
|---------------------------------|---|
| MSK_RES_ERR_NULL_ENV            | <code>env</code> is a NULL pointer.   |
| MSK_RES_ERR_NULL_TASK           | <code>task</code> is a NULL pointer.  |
| MSK_RES_ERR_INVALID_STREAM      | An invalid stream is referenced.  |
| MSK_RES_ERR_NO_INIT_ENV         | <code>env</code> is not initialized.  |
| MSK_RES_ERR_INVALID_TASK        | The <code>task</code> is invalid.   |
| MSK_RES_ERR_NULL_POINTER        | An argument to a function is unexpectedly a NULL pointer.   |
| MSK_RES_ERR_LIVING_TASKS        | All tasks associated with an environment must be deleted before the environment is deleted. There are still some undeleted tasks. |
| MSK_RES_ERR_BLANK_NAME          | An all blank name has been specified.   |
| MSK_RES_ERR_DUP_NAME            | The same name was used multiple times for the same problem item type.   |
| MSK_RES_ERR_INVALID_OBJ_NAME    | An invalid objective name is specified.   |
| MSK_RES_ERR_INVALID_CON_NAME    | An invalid constraint name is used.   |
| MSK_RES_ERR_INVALID_VAR_NAME    | An invalid variable name is used.   |
| MSK_RES_ERR_INVALID_CONE_NAME   | An invalid cone name is used.   |
| MSK_RES_ERR_INVALID_BARVAR_NAME | An invalid symmetric matrix variable name is used.  |
| MSK_RES_ERR_SPACE_LEAKING       | <b>MOSEK</b> is leaking memory. This can be due to either an incorrect use of <b>MOSEK</b> or a bug.                              |
| MSK_RES_ERR_SPACE_NO_INFO       | No available information about the space usage.   |
| MSK_RES_ERR_READ_FORMAT         | The specified format cannot be read.  |
| MSK_RES_ERR_MPS_FILE            | An error occurred while reading an MPS file.  |
| MSK_RES_ERR_MPS_INV_FIELD       | A field in the MPS file is invalid. Probably it is too wide.  |
| MSK_RES_ERR_MPS_INV_MARKER      | An invalid marker has been specified in the MPS file.   |
| MSK_RES_ERR_MPS_NULL_CON_NAME   | An empty constraint name is used in an MPS file.  |
| MSK_RES_ERR_MPS_NULL_VAR_NAME   | An empty variable name is used in an MPS file.  |
| MSK_RES_ERR_MPS_UNDEF_CON_NAME  | An undefined constraint name occurred in an MPS file.   |

MSK\_RES\_ERR\_MPS\_UNDEF\_VAR\_NAME

An undefined variable name occurred in an MPS file.

MSK\_RES\_ERR\_MPS\_INV\_CON\_KEY

An invalid constraint key occurred in an MPS file.

MSK\_RES\_ERR\_MPS\_INV\_BOUND\_KEY

An invalid bound key occurred in an MPS file.

MSK\_RES\_ERR\_MPS\_INV\_SEC\_NAME

An invalid section name occurred in an MPS file.

MSK\_RES\_ERR\_MPS\_NO\_OBJECTIVE

No objective is defined in an MPS file.

MSK\_RES\_ERR\_MPS\_SPLITTED\_VAR

All elements in a column of the  $A$  matrix must be specified consecutively. Hence, it is illegal to specify non-zero elements in  $A$  for variable 1, then for variable 2 and then variable 1 again.

MSK\_RES\_ERR\_MPS\_MUL\_CON\_NAME

A constraint name was specified multiple times in the ROWS section.

MSK\_RES\_ERR\_MPS\_MUL\_QSEC

Multiple QSECTIONs are specified for a constraint in the MPS data file.

MSK\_RES\_ERR\_MPS\_MUL\_QOBJ

The  $Q$  term in the objective is specified multiple times in the MPS data file.

MSK\_RES\_ERR\_MPS\_INV\_SEC\_ORDER

The sections in the MPS data file are not in the correct order.

MSK\_RES\_ERR\_MPS\_MUL\_CSEC

Multiple CSECTIONs are given the same name.

MSK\_RES\_ERR\_MPS\_CONE\_TYPE

Invalid cone type specified in a CSECTION.

MSK\_RES\_ERR\_MPS\_CONE\_OVERLAP

A variable is specified to be a member of several cones.

MSK\_RES\_ERR\_MPS\_CONE\_REPEAT

A variable is repeated within the CSECTION.

MSK\_RES\_ERR\_MPS\_NON\_SYMMETRIC\_Q

A non symmetric matrix has been specified.

MSK\_RES\_ERR\_MPS\_DUPLICATE\_Q\_ELEMENT

Duplicate elements is specified in a  $Q$  matrix.

MSK\_RES\_ERR\_MPS\_INVALID\_OBJSENSE

An invalid objective sense is specified.

MSK\_RES\_ERR\_MPS\_TAB\_IN\_FIELD2

A tab char occurred in field 2.

MSK\_RES\_ERR\_MPS\_TAB\_IN\_FIELD3

A tab char occurred in field 3.

MSK\_RES\_ERR\_MPS\_TAB\_IN\_FIELD5

A tab char occurred in field 5.

MSK\_RES\_ERR\_MPS\_INVALID\_OBJ\_NAME

An invalid objective name is specified.

MSK\_RES\_ERR\_LP\_INCOMPATIBLE

The problem cannot be written to an LP formatted file.

MSK\_RES\_ERR\_LP\_EMPTY

The problem cannot be written to an LP formatted file.

**MSK\_RES\_ERR\_LP\_DUP\_SLACK\_NAME**

The name of the slack variable added to a ranged constraint already exists.

**MSK\_RES\_ERR\_WRITE\_MPS\_INVALID\_NAME**

An invalid name is created while writing an MPS file. Usually this will make the MPS file unreadable.

**MSK\_RES\_ERR\_LP\_INVALID\_VAR\_NAME**

A variable name is invalid when used in an LP formatted file.

**MSK\_RES\_ERR\_LP\_FREE\_CONSTRAINT**

Free constraints cannot be written in LP file format.

**MSK\_RES\_ERR\_WRITE\_OPF\_INVALID\_VAR\_NAME**

Empty variable names cannot be written to OPF files.

**MSK\_RES\_ERR\_LP\_FILE\_FORMAT**

Syntax error in an LP file.

**MSK\_RES\_ERR\_WRITE\_LP\_FORMAT**

Problem cannot be written as an LP file.

**MSK\_RES\_ERR\_READ\_LP\_MISSING\_END\_TAG**

Syntax error in LP file. Possibly missing End tag.

**MSK\_RES\_ERR\_LP\_FORMAT**

Syntax error in an LP file.

**MSK\_RES\_ERR\_WRITE\_LP\_NON\_UNIQUE\_NAME**

An auto-generated name is not unique.

**MSK\_RES\_ERR\_READ\_LP\_NONEXISTING\_NAME**

A variable never occurred in objective or constraints.

**MSK\_RES\_ERR\_LP\_WRITE\_CONIC\_PROBLEM**

The problem contains cones that cannot be written to an LP formatted file.

**MSK\_RES\_ERR\_LP\_WRITE\_GECO\_PROBLEM**

The problem contains general convex terms that cannot be written to an LP formatted file.

**MSK\_RES\_ERR\_WRITING\_FILE**

An error occurred while writing file

**MSK\_RES\_ERR\_OPF\_FORMAT**

Syntax error in an OPF file

**MSK\_RES\_ERR\_OPF\_NEW\_VARIABLE**

Introducing new variables is now allowed. When a `[variables]` section is present, it is not allowed to introduce new variables later in the problem.

**MSK\_RES\_ERR\_INVALID\_NAME\_IN\_SOL\_FILE**

An invalid name occurred in a solution file.

**MSK\_RES\_ERR\_LP\_INVALID\_CON\_NAME**

A constraint name is invalid when used in an LP formatted file.

**MSK\_RES\_ERR\_OPF\_PREMATURE\_EOF**

Premature end of file in an OPF file.

**MSK\_RES\_ERR\_JSON\_SYNTAX**

Syntax error in an JSON data

**MSK\_RES\_ERR\_JSON\_STRING**

Error in JSON string.

**MSK\_RES\_ERR\_JSON\_NUMBER\_OVERFLOW**

Invalid number entry - wrong type or value overflow.

**MSK\_RES\_ERR\_JSON\_FORMAT**  
Error in an JSON Task file

**MSK\_RES\_ERR\_JSON\_DATA**  
Inconsistent data in JSON Task file

**MSK\_RES\_ERR\_JSON\_MISSING\_DATA**  
Missing data section in JSON task file.

**MSK\_RES\_ERR\_ARGUMENT\_LENNEQ**  
Incorrect length of arguments.

**MSK\_RES\_ERR\_ARGUMENT\_TYPE**  
Incorrect argument type.

**MSK\_RES\_ERR\_NR\_ARGUMENTS**  
Incorrect number of function arguments.

**MSK\_RES\_ERR\_IN\_ARGUMENT**  
A function argument is incorrect.

**MSK\_RES\_ERR\_ARGUMENT\_DIMENSION**  
A function argument is of incorrect dimension.

**MSK\_RES\_ERR\_INDEX\_IS\_TOO\_SMALL**  
An index in an argument is too small.

**MSK\_RES\_ERR\_INDEX\_IS\_TOO\_LARGE**  
An index in an argument is too large.

**MSK\_RES\_ERR\_PARAM\_NAME**  
The parameter name is not correct.

**MSK\_RES\_ERR\_PARAM\_NAME\_DOU**  
The parameter name is not correct for a double parameter.

**MSK\_RES\_ERR\_PARAM\_NAME\_INT**  
The parameter name is not correct for an integer parameter.

**MSK\_RES\_ERR\_PARAM\_NAME\_STR**  
The parameter name is not correct for a string parameter.

**MSK\_RES\_ERR\_PARAM\_INDEX**  
Parameter index is out of range.

**MSK\_RES\_ERR\_PARAM\_IS\_TOO\_LARGE**  
The parameter value is too large.

**MSK\_RES\_ERR\_PARAM\_IS\_TOO\_SMALL**  
The parameter value is too small.

**MSK\_RES\_ERR\_PARAM\_VALUE\_STR**  
The parameter value string is incorrect.

**MSK\_RES\_ERR\_PARAM\_TYPE**  
The parameter type is invalid.

**MSK\_RES\_ERR\_INF\_DOU\_INDEX**  
A double information index is out of range for the specified type.

**MSK\_RES\_ERR\_INF\_INT\_INDEX**  
An integer information index is out of range for the specified type.

**MSK\_RES\_ERR\_INDEX\_ARR\_IS\_TOO\_SMALL**  
An index in an array argument is too small.

**MSK\_RES\_ERR\_INDEX\_ARR\_IS\_TOO\_LARGE**  
An index in an array argument is too large.

**MSK\_RES\_ERR\_INF\_LINT\_INDEX**

A long integer information index is out of range for the specified type.

**MSK\_RES\_ERR\_ARG\_IS\_TOO\_SMALL**

The value of a argument is too small.

**MSK\_RES\_ERR\_ARG\_IS\_TOO\_LARGE**

The value of a argument is too small.

**MSK\_RES\_ERR\_INVALID\_WHICHSOL**

*whichsol* is invalid.

**MSK\_RES\_ERR\_INF\_DOU\_NAME**

A double information name is invalid.

**MSK\_RES\_ERR\_INF\_INT\_NAME**

An integer information name is invalid.

**MSK\_RES\_ERR\_INF\_TYPE**

The information type is invalid.

**MSK\_RES\_ERR\_INF\_LINT\_NAME**

A long integer information name is invalid.

**MSK\_RES\_ERR\_INDEX**

An index is out of range.

**MSK\_RES\_ERR\_WHICHSOL**

The solution defined by *whichsol* does not exists.

**MSK\_RES\_ERR\_SOLITEM**

The solution item number *solitem* is invalid. Please note that *MSK\_SOL\_ITEM\_SNX* is invalid for the basic solution.

**MSK\_RES\_ERR\_WHICHITEM\_NOT\_ALLOWED**

*whichitem* is unacceptable.

**MSK\_RES\_ERR\_MAXNUMCON**

The maximum number of constraints specified is smaller than the number of constraints in the task.

**MSK\_RES\_ERR\_MAXNUMVAR**

The maximum number of variables specified is smaller than the number of variables in the task.

**MSK\_RES\_ERR\_MAXNUMBARVAR**

The maximum number of semidefinite variables specified is smaller than the number of semidefinite variables in the task.

**MSK\_RES\_ERR\_MAXNUMQNZ**

The maximum number of non-zeros specified for the  $Q$  matrices is smaller than the number of non-zeros in the current  $Q$  matrices.

**MSK\_RES\_ERR\_TOO\_SMALL\_MAX\_NUM\_NZ**

The maximum number of non-zeros specified is too small.

**MSK\_RES\_ERR\_INVALID\_IDX**

A specified index is invalid.

**MSK\_RES\_ERR\_INVALID\_MAX\_NUM**

A specified index is invalid.

**MSK\_RES\_ERR\_NUMCONLIM**

Maximum number of constraints limit is exceeded.

**MSK\_RES\_ERR\_NUMVARLIM**

Maximum number of variables limit is exceeded.

**MSK\_RES\_ERR\_TOO\_SMALL\_MAXNUMANZ**

The maximum number of non-zeros specified for  $A$  is smaller than the number of non-zeros in the current  $A$ .

**MSK\_RES\_ERR\_INV\_APTRE**

`aptre[j]` is strictly smaller than `aptrb[j]` for some  $j$ .

**MSK\_RES\_ERR\_MUL\_A\_ELEMENT**

An element in  $A$  is defined multiple times.

**MSK\_RES\_ERR\_INV\_BK**

Invalid bound key.

**MSK\_RES\_ERR\_INV\_BKC**

Invalid bound key is specified for a constraint.

**MSK\_RES\_ERR\_INV\_BKX**

An invalid bound key is specified for a variable.

**MSK\_RES\_ERR\_INV\_VAR\_TYPE**

An invalid variable type is specified for a variable.

**MSK\_RES\_ERR\_SOLVER\_PROBTYPE**

Problem type does not match the chosen optimizer.

**MSK\_RES\_ERR\_OBJECTIVE\_RANGE**

Empty objective range.

**MSK\_RES\_ERR\_FIRST**

Invalid `first`.

**MSK\_RES\_ERR\_LAST**

Invalid index `last`. A given index was out of expected range.

**MSK\_RES\_ERR\_NEGATIVE\_SURPLUS**

Negative surplus.

**MSK\_RES\_ERR\_NEGATIVE\_APPEND**

Cannot append a negative number.

**MSK\_RES\_ERR\_UNDEF\_SOLUTION**

**MOSEK** has the following solution types:

- an interior-point solution,
- an basic solution,
- and an integer solution.

Each optimizer may set one or more of these solutions; e.g by default a successful optimization with the interior-point optimizer defines the interior-point solution, and, for linear problems, also the basic solution. This error occurs when asking for a solution or for information about a solution that is not defined.

**MSK\_RES\_ERR\_BASIS**

An invalid basis is specified. Either too many or too few basis variables are specified.

**MSK\_RES\_ERR\_INV\_SKC**

Invalid value in `skc`.

**MSK\_RES\_ERR\_INV\_SKX**

Invalid value in `skx`.

**MSK\_RES\_ERR\_INV\_SKN**

Invalid value in `skn`.

**MSK\_RES\_ERR\_INV\_SK\_STR**

Invalid status key string encountered.

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|                                  |   |
|----------------------------------|---|
| MSK_RES_ERR_INV_SK               | Invalid status key code.  |
| MSK_RES_ERR_INV_CONE_TYPE_STR    | Invalid cone type string encountered.   |
| MSK_RES_ERR_INV_CONE_TYPE        | Invalid cone type code is encountered.  |
| MSK_RES_ERR_INVALID_SURPLUS      | Invalid surplus.  |
| MSK_RES_ERR_INV_NAME_ITEM        | An invalid name item code is used.  |
| MSK_RES_ERR_PRO_ITEM             | An invalid problem is used.   |
| MSK_RES_ERR_INVALID_FORMAT_TYPE  | Invalid format type.  |
| MSK_RES_ERR_FIRSTI               | Invalid <code>firsti</code> .   |
| MSK_RES_ERR_LASTI                | Invalid <code>lasti</code> .  |
| MSK_RES_ERR_FIRSTJ               | Invalid <code>firstj</code> .   |
| MSK_RES_ERR_LASTJ                | Invalid <code>lastj</code> .  |
| MSK_RES_ERR_MAX_LEN_IS_TOO_SMALL | An maximum length that is too small has been specified.   |
| MSK_RES_ERR_NONLINEAR_EQUALITY   | The model contains a nonlinear equality which defines a nonconvex set.  |
| MSK_RES_ERR_NONCONVEX            | The optimization problem is nonconvex.  |
| MSK_RES_ERR_NONLINEAR_RANGED     | Nonlinear constraints with finite lower and upper bound always define a nonconvex feasible set.   |
| MSK_RES_ERR_CON_Q_NOT_PSD        | The quadratic constraint matrix is not positive semidefinite as expected for a constraint with finite upper bound. This results in a nonconvex problem. The parameter <code>MSK_DPAR_CHECK_CONVEXITY_REL_TOL</code> can be used to relax the convexity check. |
| MSK_RES_ERR_CON_Q_NOT_NSD        | The quadratic constraint matrix is not negative semidefinite as expected for a constraint with finite lower bound. This results in a nonconvex problem. The parameter <code>MSK_DPAR_CHECK_CONVEXITY_REL_TOL</code> can be used to relax the convexity check. |
| MSK_RES_ERR_OBJ_Q_NOT_PSD        | The quadratic coefficient matrix in the objective is not positive semidefinite as expected for a minimization problem. The parameter <code>MSK_DPAR_CHECK_CONVEXITY_REL_TOL</code> can be used to relax the convexity check.                                  |
| MSK_RES_ERR_OBJ_Q_NOT_NSD        | The quadratic coefficient matrix in the objective is not negative semidefinite as expected for a maximization problem. The parameter <code>MSK_DPAR_CHECK_CONVEXITY_REL_TOL</code> can be used to relax the convexity check.                                  |
| MSK_RES_ERR_ARGUMENT_PERM_ARRAY  | An invalid permutation array is specified.  |

**MSK\_RES\_ERR\_CONE\_INDEX**

An index of a non-existing cone has been specified.

**MSK\_RES\_ERR\_CONE\_SIZE**

A cone with too few members is specified.

**MSK\_RES\_ERR\_CONE\_OVERLAP**

One or more of the variables in the cone to be added is already member of another cone. Now assume the variable is  $x_j$  then add a new variable say  $x_k$  and the constraint

$$x_j = x_k$$

and then let  $x_k$  be member of the cone to be appended.

**MSK\_RES\_ERR\_CONE\_REP\_VAR**

A variable is included multiple times in the cone.

**MSK\_RES\_ERR\_MAXNUMCONE**

The value specified for `maxnumcone` is too small.

**MSK\_RES\_ERR\_CONE\_TYPE**

Invalid cone type specified.

**MSK\_RES\_ERR\_CONE\_TYPE\_STR**

Invalid cone type specified.

**MSK\_RES\_ERR\_CONE\_OVERLAP\_APPEND**

The cone to be appended has one variable which is already member of another cone.

**MSK\_RES\_ERR\_REMOVE\_CONE\_VARIABLE**

A variable cannot be removed because it will make a cone invalid.

**MSK\_RES\_ERR\_SOL\_FILE\_INVALID\_NUMBER**

An invalid number is specified in a solution file.

**MSK\_RES\_ERR\_HUGE\_C**

A huge value in absolute size is specified for one  $c_j$ .

**MSK\_RES\_ERR\_HUGE\_AIJ**

A numerically huge value is specified for an  $a_{i,j}$  element in  $A$ . The parameter `MSK_DPAR_DATA_TOL_AIJ_HUGE` controls when an  $a_{i,j}$  is considered huge.

**MSK\_RES\_ERR\_DUPLICATE\_AIJ**

An element in the  $A$  matrix is specified twice.

**MSK\_RES\_ERR\_LOWER\_BOUND\_IS\_A\_NAN**

The lower bound specified is not a number (nan).

**MSK\_RES\_ERR\_UPPER\_BOUND\_IS\_A\_NAN**

The upper bound specified is not a number (nan).

**MSK\_RES\_ERR\_INFINITE\_BOUND**

A numerically huge bound value is specified.

**MSK\_RES\_ERR\_INV\_QOBJ\_SUBI**

Invalid value in `qosubi`.

**MSK\_RES\_ERR\_INV\_QOBJ\_SUBJ**

Invalid value in `qosubj`.

**MSK\_RES\_ERR\_INV\_QOBJ\_VAL**

Invalid value in `qoval`.

**MSK\_RES\_ERR\_INV\_QCON\_SUBK**

Invalid value in `qcsubk`.

**MSK\_RES\_ERR\_INV\_QCON\_SUBI**

Invalid value in `qcsubi`.

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|   |  |
|---|--|
| MSK_RES_ERR_INV_QCON_SUBJ                   | Invalid value in <code>qcsbj</code> .  |
| MSK_RES_ERR_INV_QCON_VAL                    | Invalid value in <code>qcval</code> .  |
| MSK_RES_ERR_QCON_SUBI_TOO_SMALL             | Invalid value in <code>qcsubi</code> .   |
| MSK_RES_ERR_QCON_SUBI_TOO_LARGE             | Invalid value in <code>qcsubi</code> .   |
| MSK_RES_ERR_QOBJ_UPPER_TRIANGLE             | An element in the upper triangle of $Q^o$ is specified. Only elements in the lower triangle should be specified.                       |
| MSK_RES_ERR_QCON_UPPER_TRIANGLE             | An element in the upper triangle of a $Q^k$ is specified. Only elements in the lower triangle should be specified.                     |
| MSK_RES_ERR_FIXED_BOUND_VALUES              | A fixed constraint/variable has been specified using the bound keys but the numerical value of the lower and upper bound is different. |
| MSK_RES_ERR_NONLINEAR_FUNCTIONS_NOT_ALLOWED | An operation that is invalid for problems with nonlinear functions defined has been attempted.   |
| MSK_RES_ERR_USER_FUNC_RET                   | An user function reported an error.  |
| MSK_RES_ERR_USER_FUNC_RET_DATA              | An user function returned invalid data.  |
| MSK_RES_ERR_USER_NLO_FUNC                   | The user-defined nonlinear function reported an error.   |
| MSK_RES_ERR_USER_NLO_EVAL                   | The user-defined nonlinear function reported an error.   |
| MSK_RES_ERR_USER_NLO_EVAL_HESSUBI           | The user-defined nonlinear function reported an invalid subscript in the Hessian.  |
| MSK_RES_ERR_USER_NLO_EVAL_HESSUBJ           | The user-defined nonlinear function reported an invalid subscript in the Hessian.  |
| MSK_RES_ERR_INVALID_OBJECTIVE_SENSE         | An invalid objective sense is specified.   |
| MSK_RES_ERR_UNDEFINED_OBJECTIVE_SENSE       | The objective sense has not been specified before the optimization.  |
| MSK_RES_ERR_Y_IS_UNDEFINED                  | The solution item $y$ is undefined.  |
| MSK_RES_ERR_NAN_IN_DOUBLE_DATA              | An invalid floating point value was used in some double data.  |
| MSK_RES_ERR_NAN_IN_BLC                      | $l^c$ contains an invalid floating point value, i.e. a NaN.  |
| MSK_RES_ERR_NAN_IN_BUC                      | $u^c$ contains an invalid floating point value, i.e. a NaN.  |
| MSK_RES_ERR_NAN_IN_C                        | $c$ contains an invalid floating point value, i.e. a NaN.  |
| MSK_RES_ERR_NAN_IN_BLX                      | $l^x$ contains an invalid floating point value, i.e. a NaN.  |

**MSK\_RES\_ERR\_NAN\_IN\_BUX**

$u^x$  contains an invalid floating point value, i.e. a NaN.

**MSK\_RES\_ERR\_INVALID\_AIJ**

$a_{i,j}$  contains an invalid floating point value, i.e. a NaN or an infinite value.

**MSK\_RES\_ERR\_SYM\_MAT\_INVALID**

A symmetric matrix contains an invalid floating point value, i.e. a NaN or an infinite value.

**MSK\_RES\_ERR\_SYM\_MAT\_HUGE**

A symmetric matrix contains a huge value in absolute size. The parameter *MSK\_DPAR\_DATA\_SYM\_MAT\_TOL\_HUGE* controls when an  $e_{i,j}$  is considered huge.

**MSK\_RES\_ERR\_INV\_PROBLEM**

Invalid problem type. Probably a nonconvex problem has been specified.

**MSK\_RES\_ERR\_MIXED\_CONIC\_AND\_NL**

The problem contains nonlinear terms conic constraints. The requested operation cannot be applied to this type of problem.

**MSK\_RES\_ERR\_GLOBAL\_INV\_CONIC\_PROBLEM**

The global optimizer can only be applied to problems without semidefinite variables.

**MSK\_RES\_ERR\_INV\_OPTIMIZER**

An invalid optimizer has been chosen for the problem. This means that the simplex or the conic optimizer is chosen to optimize a nonlinear problem.

**MSK\_RES\_ERR\_MIO\_NO\_OPTIMIZER**

No optimizer is available for the current class of integer optimization problems.

**MSK\_RES\_ERR\_NO\_OPTIMIZER\_VAR\_TYPE**

No optimizer is available for this class of optimization problems.

**MSK\_RES\_ERR\_FINAL\_SOLUTION**

An error occurred during the solution finalization.

**MSK\_RES\_ERR\_POSTSOLVE**

An error occurred during the postsolve. Please contact **MOSEK** support.

**MSK\_RES\_ERR\_OVERFLOW**

A computation produced an overflow i.e. a very large number.

**MSK\_RES\_ERR\_NO\_BASIS\_SOL**

No basic solution is defined.

**MSK\_RES\_ERR\_BASIS\_FACTOR**

The factorization of the basis is invalid.

**MSK\_RES\_ERR\_BASIS\_SINGULAR**

The basis is singular and hence cannot be factored.

**MSK\_RES\_ERR\_FACTOR**

An error occurred while factorizing a matrix.

**MSK\_RES\_ERR\_FEASREPAIR\_CANNOT\_RELAX**

An optimization problem cannot be relaxed. This is the case e.g. for general nonlinear optimization problems.

**MSK\_RES\_ERR\_FEASREPAIR\_SOLVING\_RELAXED**

The relaxed problem could not be solved to optimality. Please consult the log file for further details.

**MSK\_RES\_ERR\_FEASREPAIR\_INCONSISTENT\_BOUND**

The upper bound is less than the lower bound for a variable or a constraint. Please correct this before running the feasibility repair.

**MSK\_RES\_ERR\_REPAIR\_INVALID\_PROBLEM**

The feasibility repair does not support the specified problem type.

**MSK\_RES\_ERR\_REPAIR\_OPTIMIZATION\_FAILED**

Computation the optimal relaxation failed. The cause may have been numerical problems.

**MSK\_RES\_ERR\_NAME\_MAX\_LEN**

A name is longer than the buffer that is supposed to hold it.

**MSK\_RES\_ERR\_NAME\_IS\_NULL**

The name buffer is a NULL pointer.

**MSK\_RES\_ERR\_INVALID\_COMPRESSION**

Invalid compression type.

**MSK\_RES\_ERR\_INVALID\_IOMODE**

Invalid io mode.

**MSK\_RES\_ERR\_NO\_PRIMAL\_INFEAS\_CER**

A certificate of primal infeasibility is not available.

**MSK\_RES\_ERR\_NO\_DUAL\_INFEAS\_CER**

A certificate of infeasibility is not available.

**MSK\_RES\_ERR\_NO\_SOLUTION\_IN\_CALLBACK**

The required solution is not available.

**MSK\_RES\_ERR\_INV\_MARKI**

Invalid value in marki.

**MSK\_RES\_ERR\_INV\_MARKJ**

Invalid value in markj.

**MSK\_RES\_ERR\_INV\_NUMI**

Invalid numi.

**MSK\_RES\_ERR\_INV\_NUMJ**

Invalid numj.

**MSK\_RES\_ERR\_CANNOT\_CLONE\_NL**

A task with a nonlinear function callback cannot be cloned.

**MSK\_RES\_ERR\_CANNOT\_HANDLE\_NL**

A function cannot handle a task with nonlinear function callbacks.

**MSK\_RES\_ERR\_INVALID\_ACCMODE**

An invalid access mode is specified.

**MSK\_RES\_ERR\_TASK\_INCOMPATIBLE**

The Task file is incompatible with this platform. This results from reading a file on a 32 bit platform generated on a 64 bit platform.

**MSK\_RES\_ERR\_TASK\_INVALID**

The Task file is invalid.

**MSK\_RES\_ERR\_TASK\_WRITE**

Failed to write the task file.

**MSK\_RES\_ERR\_LU\_MAX\_NUM\_TRIES**

Could not compute the LU factors of the matrix within the maximum number of allowed tries.

**MSK\_RES\_ERR\_INVALID\_UTF8**

An invalid UTF8 string is encountered.

**MSK\_RES\_ERR\_INVALID\_WCHAR**

An invalid `wchar` string is encountered.

**MSK\_RES\_ERR\_NO\_DUAL\_FOR\_ITG\_SOL**

No dual information is available for the integer solution.

**MSK\_RES\_ERR\_NO\_SNX\_FOR\_BAS\_SOL**

$s_n^x$  is not available for the basis solution.

**MSK\_RES\_ERR\_INTERNAL**

An internal error occurred. Please report this problem.

**MSK\_RES\_ERR\_API\_ARRAY\_TOO\_SMALL**

An input array was too short.

**MSK\_RES\_ERR\_API\_CB\_CONNECT**

Failed to connect a callback object.

**MSK\_RES\_ERR\_API\_FATAL\_ERROR**

An internal error occurred in the API. Please report this problem.

**MSK\_RES\_ERR\_API\_INTERNAL**

An internal fatal error occurred in an interface function.

**MSK\_RES\_ERR\_SEN\_FORMAT**

Syntax error in sensitivity analysis file.

**MSK\_RES\_ERR\_SEN\_UNDEF\_NAME**

An undefined name was encountered in the sensitivity analysis file.

**MSK\_RES\_ERR\_SEN\_INDEX\_RANGE**

Index out of range in the sensitivity analysis file.

**MSK\_RES\_ERR\_SEN\_BOUND\_INVALID\_UP**

Analysis of upper bound requested for an index, where no upper bound exists.

**MSK\_RES\_ERR\_SEN\_BOUND\_INVALID\_LO**

Analysis of lower bound requested for an index, where no lower bound exists.

**MSK\_RES\_ERR\_SEN\_INDEX\_INVALID**

Invalid range given in the sensitivity file.

**MSK\_RES\_ERR\_SEN\_INVALID\_REGEX**

Syntax error in regexp or regexp longer than 1024.

**MSK\_RES\_ERR\_SEN\_SOLUTION\_STATUS**

No optimal solution found to the original problem given for sensitivity analysis.

**MSK\_RES\_ERR\_SEN\_NUMERICAL**

Numerical difficulties encountered performing the sensitivity analysis.

**MSK\_RES\_ERR\_SEN\_UNHANDLED\_PROBLEM\_TYPE**

Sensitivity analysis cannot be performed for the specified problem. Sensitivity analysis is only possible for linear problems.

**MSK\_RES\_ERR\_UNB\_STEP\_SIZE**

A step size in an optimizer was unexpectedly unbounded. For instance, if the step-size becomes unbounded in phase 1 of the simplex algorithm then an error occurs. Normally this will happen only if the problem is badly formulated. Please contact **MOSEK** support if this error occurs.

**MSK\_RES\_ERR\_IDENTICAL\_TASKS**

Some tasks related to this function call were identical. Unique tasks were expected.

**MSK\_RES\_ERR\_AD\_INVALID\_CODELIST**

The code list data was invalid.

**MSK\_RES\_ERR\_INTERNAL\_TEST\_FAILED**

An internal unit test function failed.

**MSK\_RES\_ERR\_XML\_INVALID\_PROBLEM\_TYPE**

The problem type is not supported by the XML format.

**MSK\_RES\_ERR\_INVALIDAMPL\_STUB**

Invalid AMPL stub.

**MSK\_RES\_ERR\_INT64\_TO\_INT32\_CAST**

An 32 bit integer could not cast to a 64 bit integer.

**MSK\_RES\_ERR\_SIZE\_LICENSE\_NUMCORES**

The computer contains more cpu cores than the license allows for.

**MSK\_RES\_ERR\_INFEAS\_UNDEFINED**

The requested value is not defined for this solution type.

**MSK\_RES\_ERR\_NO\_BARX\_FOR\_SOLUTION**

There is no  $\bar{X}$  available for the solution specified. In particular note there are no  $\bar{X}$  defined for the basic and integer solutions.

**MSK\_RES\_ERR\_NO\_BARS\_FOR\_SOLUTION**

There is no  $\bar{s}$  available for the solution specified. In particular note there are no  $\bar{s}$  defined for the basic and integer solutions.

**MSK\_RES\_ERR\_BAR\_VAR\_DIM**

The dimension of a symmetric matrix variable has to be greater than 0.

**MSK\_RES\_ERR\_SYM\_MAT\_INVALID\_ROW\_INDEX**

A row index specified for sparse symmetric matrix is invalid.

**MSK\_RES\_ERR\_SYM\_MAT\_INVALID\_COL\_INDEX**

A column index specified for sparse symmetric matrix is invalid.

**MSK\_RES\_ERR\_SYM\_MAT\_NOT\_LOWER\_TRINGULAR**

Only the lower triangular part of sparse symmetric matrix should be specified.

**MSK\_RES\_ERR\_SYM\_MAT\_INVALID\_VALUE**

The numerical value specified in a sparse symmetric matrix is not a floating value.

**MSK\_RES\_ERR\_SYM\_MAT\_DUPLICATE**

A value in a symmetric matrix has been specified more than once.

**MSK\_RES\_ERR\_INVALID\_SYM\_MAT\_DIM**

A sparse symmetric matrix of invalid dimension is specified.

**MSK\_RES\_ERR\_INVALID\_FILE\_FORMAT\_FOR\_SYM\_MAT**

The file format does not support a problem with symmetric matrix variables.

**MSK\_RES\_ERR\_INVALID\_FILE\_FORMAT\_FOR\_CONES**

The file format does not support a problem with conic constraints.

**MSK\_RES\_ERR\_INVALID\_FILE\_FORMAT\_FOR\_GENERAL\_NL**

The file format does not support a problem with general nonlinear terms.

**MSK\_RES\_ERR\_DUPLICATE\_CONSTRAINT\_NAMES**

Two constraint names are identical.

**MSK\_RES\_ERR\_DUPLICATE\_VARIABLE\_NAMES**

Two variable names are identical.

**MSK\_RES\_ERR\_DUPLICATE\_BARVARIABLE\_NAMES**

Two barvariable names are identical.

**MSK\_RES\_ERR\_DUPLICATE\_CONE\_NAMES**

Two cone names are identical.

**MSK\_RES\_ERR\_NON\_UNIQUE\_ARRAY**

An array does not contain unique elements.

**MSK\_RES\_ERR\_ARGUMENT\_IS\_TOO\_LARGE**

The value of a function argument is too large.

**MSK\_RES\_ERR\_MIO\_INTERNAL**

A fatal error occurred in the mixed integer optimizer. Please contact **MOSEK** support.

**MSK\_RES\_ERR\_INVALID\_PROBLEM\_TYPE**

An invalid problem type.

MSK\_RES\_ERR\_UNHANDLED\_SOLUTION\_STATUS

Unhandled solution status.

MSK\_RES\_ERR\_UPPER\_TRIANGLE

An element in the upper triangle of a lower triangular matrix is specified.

MSK\_RES\_ERR\_LAU\_SINGULAR\_MATRIX

A matrix is singular.

MSK\_RES\_ERR\_LAU\_NOT\_POSITIVE\_DEFINITE

A matrix is not positive definite.

MSK\_RES\_ERR\_LAU\_INVALID\_LOWER\_TRIANGULAR\_MATRIX

An invalid lower triangular matrix.

MSK\_RES\_ERR\_LAU\_UNKNOWN

An unknown error.

MSK\_RES\_ERR\_LAU\_ARG\_M

Invalid argument m.

MSK\_RES\_ERR\_LAU\_ARG\_N

Invalid argument n.

MSK\_RES\_ERR\_LAU\_ARG\_K

Invalid argument k.

MSK\_RES\_ERR\_LAU\_ARG\_TRANSA

Invalid argument transa.

MSK\_RES\_ERR\_LAU\_ARG\_TRANSB

Invalid argument transb.

MSK\_RES\_ERR\_LAU\_ARG\_UPLO

Invalid argument uplo.

MSK\_RES\_ERR\_LAU\_ARG\_TRANS

Invalid argument trans.

MSK\_RES\_ERR\_LAU\_INVALID\_SPARSE\_SYMMETRIC\_MATRIX

An invalid sparse symmetric matrix is specified. Note only the lower triangular part with no duplicates is specified.

MSK\_RES\_ERR\_CBF\_PARSE

An error occurred while parsing an CBF file.

MSK\_RES\_ERR\_CBF\_OBJ\_SENSE

An invalid objective sense is specified.

MSK\_RES\_ERR\_CBF\_NO\_VARIABLES

No variables are specified.

MSK\_RES\_ERR\_CBF\_TOO\_MANY\_CONSTRAINTS

Too many constraints specified.

MSK\_RES\_ERR\_CBF\_TOO\_MANY\_VARIABLES

Too many variables specified.

MSK\_RES\_ERR\_CBF\_NO\_VERSION\_SPECIFIED

No version specified.

MSK\_RES\_ERR\_CBF\_SYNTAX

Invalid syntax.

MSK\_RES\_ERR\_CBF\_DUPLICATE\_OBJ

Duplicate OBJ keyword.

MSK\_RES\_ERR\_CBF\_DUPLICATE\_CON

Duplicate CON keyword.

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|  |  |
|--|--|
| MSK_RES_ERR_CBF_DUPLICATE_VAR            | Duplicate VAR keyword.   |
| MSK_RES_ERR_CBF_DUPLICATE_INT            | Duplicate INT keyword.   |
| MSK_RES_ERR_CBF_INVALID_VAR_TYPE         | Invalid variable type.   |
| MSK_RES_ERR_CBF_INVALID_CON_TYPE         | Invalid constraint type.   |
| MSK_RES_ERR_CBF_INVALID_DOMAIN_DIMENSION | Invalid domain dimension.  |
| MSK_RES_ERR_CBF_DUPLICATE_OBJCOORD       | Duplicate index in OBJCOORD.   |
| MSK_RES_ERR_CBF_DUPLICATE_BCOORD         | Duplicate index in BCOORD.   |
| MSK_RES_ERR_CBF_DUPLICATE_ACOORD         | Duplicate index in ACOORD.   |
| MSK_RES_ERR_CBF_TOO_FEW_VARIABLES        | Too few variables defined.   |
| MSK_RES_ERR_CBF_TOO_FEW_CONSTRAINTS      | Too few constraints defined.   |
| MSK_RES_ERR_CBF_TOO_FEW_INTS             | Too few ints are specified.  |
| MSK_RES_ERR_CBF_TOO_MANY_INTS            | Too many ints are specified.   |
| MSK_RES_ERR_CBF_INVALID_INT_INDEX        | Invalid INT index.   |
| MSK_RES_ERR_CBF_UNSUPPORTED              | Unsupported feature is present.  |
| MSK_RES_ERR_CBF_DUPLICATE_PSDVAR         | Duplicate PSDVAR keyword.  |
| MSK_RES_ERR_CBF_INVALID_PSDVAR_DIMENSION | Invalid PSDVAR dimension.  |
| MSK_RES_ERR_CBF_TOO_FEW_PSDVAR           | Too few variables defined.   |
| MSK_RES_ERR_MIO_INVALID_ROOT_OPTIMIZER   | An invalid root optimizer was selected for the problem type.                               |
| MSK_RES_ERR_MIO_INVALID_NODE_OPTIMIZER   | An invalid node optimizer was selected for the problem type.                               |
| MSK_RES_ERR_TOCONIC_CONSTR_Q_NOT_PSD     | The matrix defining the quadratic part of constraint is not positive semidefinite.         |
| MSK_RES_ERR_TOCONIC_CONSTRAINT_FX        | The quadratic constraint is an equality, thus not convex.                                  |
| MSK_RES_ERR_TOCONIC_CONSTRAINT_RA        | The quadratic constraint has finite lower and upper bound, and therefore it is not convex. |
| MSK_RES_ERR_TOCONIC_CONSTR_NOT_CONIC     | The constraint is not conic representable.   |

MSK\_RES\_ERR\_TOCONIC\_OBJECTIVE\_NOT\_PSD

The matrix defining the quadratic part of the objective function is not positive semidefinite.

MSK\_RES\_ERR\_SERVER\_CONNECT

Failed to connect to remote solver server. The server string or the port string were invalid, or the server did not accept connection.

MSK\_RES\_ERR\_SERVER\_PROTOCOL

Unexpected message or data from solver server.

MSK\_RES\_ERR\_SERVER\_STATUS

Server returned non-ok HTTP status code

MSK\_RES\_ERR\_SERVER\_TOKEN

The job ID specified is incorrect or invalid

## 11.5 Constants

### 11.5.1 Language selection constants

MSK\_LANG\_ENG

English language selection

MSK\_LANG\_DAN

Danish language selection

### 11.5.2 Constraint or variable access modes. All functions using this enum are deprecated. Use separate functions for rows/columns instead.

MSK\_ACC\_VAR

Access data by columns (variable oriented)

MSK\_ACC\_CON

Access data by rows (constraint oriented)

### 11.5.3 Basis identification

MSK\_BI\_NEVER

Never do basis identification.

MSK\_BI\_ALWAYS

Basis identification is always performed even if the interior-point optimizer terminates abnormally.

MSK\_BI\_NO\_ERROR

Basis identification is performed if the interior-point optimizer terminates without an error.

MSK\_BI\_IF\_FEASIBLE

Basis identification is not performed if the interior-point optimizer terminates with a problem status saying that the problem is primal or dual infeasible.

MSK\_BI\_RESERVED

Not currently in use.

### 11.5.4 Bound keys

MSK\_BK\_LO

The constraint or variable has a finite lower bound and an infinite upper bound.

MSK\_BK\_UP

The constraint or variable has an infinite lower bound and an finite upper bound.

MSK\_BK\_FX

The constraint or variable is fixed.

MSK\_BK\_FR

The constraint or variable is free.

MSK\_BK\_RA

The constraint or variable is ranged.

### 11.5.5 Mark

MSK\_MARK\_LO

The lower bound is selected for sensitivity analysis.

MSK\_MARK\_UP

The upper bound is selected for sensitivity analysis.

### 11.5.6 Degeneracy strategies

MSK\_SIM\_DEGEN\_NONE

The simplex optimizer should use no degeneration strategy.

MSK\_SIM\_DEGEN\_FREE

The simplex optimizer chooses the degeneration strategy.

MSK\_SIM\_DEGEN\_AGGRESSIVE

The simplex optimizer should use an aggressive degeneration strategy.

MSK\_SIM\_DEGEN\_MODERATE

The simplex optimizer should use a moderate degeneration strategy.

MSK\_SIM\_DEGEN\_MINIMUM

The simplex optimizer should use a minimum degeneration strategy.

### 11.5.7 Transposed matrix.

MSK\_TRANSPOSE\_NO

No transpose is applied.

MSK\_TRANSPOSE\_YES

A transpose is applied.

### 11.5.8 Triangular part of a symmetric matrix.

MSK\_UPLO\_LO

Lower part.

MSK\_UPLO\_UP

Upper part

### 11.5.9 Problem reformulation.

MSK\_SIM\_REFORMULATION\_ON

Allow the simplex optimizer to reformulate the problem.

MSK\_SIM\_REFORMULATION\_OFF

Disallow the simplex optimizer to reformulate the problem.

MSK\_SIM\_REFORMULATION\_FREE

The simplex optimizer can choose freely.

MSK\_SIM\_REFORMULATION\_AGGRESSIVE

The simplex optimizer should use an aggressive reformulation strategy.

### 11.5.10 Exploit duplicate columns.

MSK\_SIM\_EXPLOIT\_DUPVEC\_ON

Allow the simplex optimizer to exploit duplicated columns.

MSK\_SIM\_EXPLOIT\_DUPVEC\_OFF

Disallow the simplex optimizer to exploit duplicated columns.

MSK\_SIM\_EXPLOIT\_DUPVEC\_FREE

The simplex optimizer can choose freely.

### 11.5.11 Hot-start type employed by the simplex optimizer

MSK\_SIM\_HOTSTART\_NONE

The simplex optimizer performs a coldstart.

MSK\_SIM\_HOTSTART\_FREE

The simplex optimizer chooses the hot-start type.

MSK\_SIM\_HOTSTART\_STATUS\_KEYS

Only the status keys of the constraints and variables are used to choose the type of hot-start.

### 11.5.12 Hot-start type employed by the interior-point optimizers.

MSK\_INTPNT\_HOTSTART\_NONE

The interior-point optimizer performs a coldstart.

MSK\_INTPNT\_HOTSTART\_PRIMAL

The interior-point optimizer exploits the primal solution only.

MSK\_INTPNT\_HOTSTART\_DUAL

The interior-point optimizer exploits the dual solution only.

MSK\_INTPNT\_HOTSTART\_PRIMAL\_DUAL

The interior-point optimizer exploits both the primal and dual solution.

### 11.5.13 Progress callback codes

MSK\_CALLBACK\_BEGIN\_BI

The basis identification procedure has been started.

MSK\_CALLBACK\_BEGIN\_CONIC

The callback function is called when the conic optimizer is started.

MSK\_CALLBACK\_BEGIN\_DUAL\_BI

The callback function is called from within the basis identification procedure when the dual phase is started.

MSK\_CALLBACK\_BEGIN\_DUAL\_SENSITIVITY

Dual sensitivity analysis is started.

**MSK\_CALLBACK\_BEGIN\_DUAL\_SETUP\_BI**

The callback function is called when the dual BI phase is started.

**MSK\_CALLBACK\_BEGIN\_DUAL\_SIMPLEX**

The callback function is called when the dual simplex optimizer started.

**MSK\_CALLBACK\_BEGIN\_DUAL\_SIMPLEX\_BI**

The callback function is called from within the basis identification procedure when the dual simplex clean-up phase is started.

**MSK\_CALLBACK\_BEGIN\_FULL\_CONVEXITY\_CHECK**

Begin full convexity check.

**MSK\_CALLBACK\_BEGIN\_INFEAS\_ANA**

The callback function is called when the infeasibility analyzer is started.

**MSK\_CALLBACK\_BEGIN\_INTPNT**

The callback function is called when the interior-point optimizer is started.

**MSK\_CALLBACK\_BEGIN\_LICENSE\_WAIT**

Begin waiting for license.

**MSK\_CALLBACK\_BEGIN\_MIO**

The callback function is called when the mixed-integer optimizer is started.

**MSK\_CALLBACK\_BEGIN\_OPTIMIZER**

The callback function is called when the optimizer is started.

**MSK\_CALLBACK\_BEGIN\_PRESOLVE**

The callback function is called when the presolve is started.

**MSK\_CALLBACK\_BEGIN\_PRIMAL\_BI**

The callback function is called from within the basis identification procedure when the primal phase is started.

**MSK\_CALLBACK\_BEGIN\_PRIMAL\_REPAIR**

Begin primal feasibility repair.

**MSK\_CALLBACK\_BEGIN\_PRIMAL\_SENSITIVITY**

Primal sensitivity analysis is started.

**MSK\_CALLBACK\_BEGIN\_PRIMAL\_SETUP\_BI**

The callback function is called when the primal BI setup is started.

**MSK\_CALLBACK\_BEGIN\_PRIMAL\_SIMPLEX**

The callback function is called when the primal simplex optimizer is started.

**MSK\_CALLBACK\_BEGIN\_PRIMAL\_SIMPLEX\_BI**

The callback function is called from within the basis identification procedure when the primal simplex clean-up phase is started.

**MSK\_CALLBACK\_BEGIN\_QCQO\_REFORMULATE**

Begin QCQO reformulation.

**MSK\_CALLBACK\_BEGIN\_READ**

**MOSEK** has started reading a problem file.

**MSK\_CALLBACK\_BEGIN\_ROOT\_CUTGEN**

The callback function is called when root cut generation is started.

**MSK\_CALLBACK\_BEGIN\_SIMPLEX**

The callback function is called when the simplex optimizer is started.

**MSK\_CALLBACK\_BEGIN\_SIMPLEX\_BI**

The callback function is called from within the basis identification procedure when the simplex clean-up phase is started.

**MSK\_CALLBACK\_BEGIN\_TO\_CONIC**

Begin conic reformulation.

**MSK\_CALLBACK\_BEGIN\_WRITE**

**MOSEK** has started writing a problem file.

**MSK\_CALLBACK\_CONIC**

The callback function is called from within the conic optimizer after the information database has been updated.

**MSK\_CALLBACK\_DUAL\_SIMPLEX**

The callback function is called from within the dual simplex optimizer.

**MSK\_CALLBACK\_END\_BI**

The callback function is called when the basis identification procedure is terminated.

**MSK\_CALLBACK\_END\_CONIC**

The callback function is called when the conic optimizer is terminated.

**MSK\_CALLBACK\_END\_DUAL\_BI**

The callback function is called from within the basis identification procedure when the dual phase is terminated.

**MSK\_CALLBACK\_END\_DUAL\_SENSITIVITY**

Dual sensitivity analysis is terminated.

**MSK\_CALLBACK\_END\_DUAL\_SETUP\_BI**

The callback function is called when the dual BI phase is terminated.

**MSK\_CALLBACK\_END\_DUAL\_SIMPLEX**

The callback function is called when the dual simplex optimizer is terminated.

**MSK\_CALLBACK\_END\_DUAL\_SIMPLEX\_BI**

The callback function is called from within the basis identification procedure when the dual clean-up phase is terminated.

**MSK\_CALLBACK\_END\_FULL\_CONVEXITY\_CHECK**

End full convexity check.

**MSK\_CALLBACK\_END\_INFEAS\_ANA**

The callback function is called when the infeasibility analyzer is terminated.

**MSK\_CALLBACK\_END\_INTPNT**

The callback function is called when the interior-point optimizer is terminated.

**MSK\_CALLBACK\_END\_LICENSE\_WAIT**

End waiting for license.

**MSK\_CALLBACK\_END\_MIO**

The callback function is called when the mixed-integer optimizer is terminated.

**MSK\_CALLBACK\_END\_OPTIMIZER**

The callback function is called when the optimizer is terminated.

**MSK\_CALLBACK\_END\_PREOLVE**

The callback function is called when the presolve is completed.

**MSK\_CALLBACK\_END\_PRIMAL\_BI**

The callback function is called from within the basis identification procedure when the primal phase is terminated.

**MSK\_CALLBACK\_END\_PRIMAL\_REPAIR**

End primal feasibility repair.

**MSK\_CALLBACK\_END\_PRIMAL\_SENSITIVITY**

Primal sensitivity analysis is terminated.

**MSK\_CALLBACK\_END\_PRIMAL\_SETUP\_BI**

The callback function is called when the primal BI setup is terminated.

**MSK\_CALLBACK\_END\_PRIMAL\_SIMPLEX**

The callback function is called when the primal simplex optimizer is terminated.

**MSK\_CALLBACK\_END\_PRIMAL\_SIMPLEX\_BI**

The callback function is called from within the basis identification procedure when the primal clean-up phase is terminated.

**MSK\_CALLBACK\_END\_QCQO\_REFORMULATE**

End QCQO reformulation.

**MSK\_CALLBACK\_END\_READ**

**MOSEK** has finished reading a problem file.

**MSK\_CALLBACK\_END\_ROOT\_CUTGEN**

The callback function is called when root cut generation is terminated.

**MSK\_CALLBACK\_END\_SIMPLEX**

The callback function is called when the simplex optimizer is terminated.

**MSK\_CALLBACK\_END\_SIMPLEX\_BI**

The callback function is called from within the basis identification procedure when the simplex clean-up phase is terminated.

**MSK\_CALLBACK\_END\_TO\_CONIC**

End conic reformulation.

**MSK\_CALLBACK\_END\_WRITE**

**MOSEK** has finished writing a problem file.

**MSK\_CALLBACK\_IM\_BI**

The callback function is called from within the basis identification procedure at an intermediate point.

**MSK\_CALLBACK\_IM\_CONIC**

The callback function is called at an intermediate stage within the conic optimizer where the information database has not been updated.

**MSK\_CALLBACK\_IM\_DUAL\_BI**

The callback function is called from within the basis identification procedure at an intermediate point in the dual phase.

**MSK\_CALLBACK\_IM\_DUAL\_SENSIVITY**

The callback function is called at an intermediate stage of the dual sensitivity analysis.

**MSK\_CALLBACK\_IM\_DUAL\_SIMPLEX**

The callback function is called at an intermediate point in the dual simplex optimizer.

**MSK\_CALLBACK\_IM\_FULL\_CONVEXITY\_CHECK**

The callback function is called at an intermediate stage of the full convexity check.

**MSK\_CALLBACK\_IM\_INTPNT**

The callback function is called at an intermediate stage within the interior-point optimizer where the information database has not been updated.

**MSK\_CALLBACK\_IM\_LICENSE\_WAIT**

**MOSEK** is waiting for a license.

**MSK\_CALLBACK\_IM\_LU**

The callback function is called from within the LU factorization procedure at an intermediate point.

**MSK\_CALLBACK\_IM\_MIO**

The callback function is called at an intermediate point in the mixed-integer optimizer.

**MSK\_CALLBACK\_IM\_MIO\_DUAL\_SIMPLEX**

The callback function is called at an intermediate point in the mixed-integer optimizer while running the dual simplex optimizer.

**MSK\_CALLBACK\_IM\_MIO\_INTPNT**

The callback function is called at an intermediate point in the mixed-integer optimizer while running the interior-point optimizer.

**MSK\_CALLBACK\_IM\_MIO\_PRIMAL\_SIMPLEX**

The callback function is called at an intermediate point in the mixed-integer optimizer while running the primal simplex optimizer.

**MSK\_CALLBACK\_IM\_ORDER**

The callback function is called from within the matrix ordering procedure at an intermediate point.

**MSK\_CALLBACK\_IM\_PRESOLVE**

The callback function is called from within the presolve procedure at an intermediate stage.

**MSK\_CALLBACK\_IM\_PRIMAL\_BI**

The callback function is called from within the basis identification procedure at an intermediate point in the primal phase.

**MSK\_CALLBACK\_IM\_PRIMAL\_SENSIVITY**

The callback function is called at an intermediate stage of the primal sensitivity analysis.

**MSK\_CALLBACK\_IM\_PRIMAL\_SIMPLEX**

The callback function is called at an intermediate point in the primal simplex optimizer.

**MSK\_CALLBACK\_IM\_QO\_REFORMULATE**

The callback function is called at an intermediate stage of the conic quadratic reformulation.

**MSK\_CALLBACK\_IM\_READ**

Intermediate stage in reading.

**MSK\_CALLBACK\_IM\_ROOT\_CUTGEN**

The callback is called from within root cut generation at an intermediate stage.

**MSK\_CALLBACK\_IM\_SIMPLEX**

The callback function is called from within the simplex optimizer at an intermediate point.

**MSK\_CALLBACK\_IM\_SIMPLEX\_BI**

The callback function is called from within the basis identification procedure at an intermediate point in the simplex clean-up phase. The frequency of the callbacks is controlled by the *MSK\_IPAR\_LOG\_SIM\_FREQ* parameter.

**MSK\_CALLBACK\_INTPNT**

The callback function is called from within the interior-point optimizer after the information database has been updated.

**MSK\_CALLBACK\_NEW\_INT\_MIO**

The callback function is called after a new integer solution has been located by the mixed-integer optimizer.

**MSK\_CALLBACK\_PRIMAL\_SIMPLEX**

The callback function is called from within the primal simplex optimizer.

**MSK\_CALLBACK\_READ\_OPF**

The callback function is called from the OPF reader.

**MSK\_CALLBACK\_READ\_OPF\_SECTION**

A chunk of  $Q$  non-zeros has been read from a problem file.

**MSK\_CALLBACK\_SOLVING\_REMOTE**

The callback function is called while the task is being solved on a remote server.

**MSK\_CALLBACK\_UPDATE\_DUAL\_BI**

The callback function is called from within the basis identification procedure at an intermediate point in the dual phase.

**MSK\_CALLBACK\_UPDATE\_DUAL\_SIMPLEX**

The callback function is called in the dual simplex optimizer.

**MSK\_CALLBACK\_UPDATE\_DUAL\_SIMPLEX\_BI**

The callback function is called from within the basis identification procedure at an intermediate point in the dual simplex clean-up phase. The frequency of the callbacks is controlled by the *MSK\_IPAR\_LOG\_SIM\_FREQ* parameter.

**MSK\_CALLBACK\_UPDATE\_PRESOLVE**

The callback function is called from within the presolve procedure.

**MSK\_CALLBACK\_UPDATE\_PRIMAL\_BI**

The callback function is called from within the basis identification procedure at an intermediate point in the primal phase.

**MSK\_CALLBACK\_UPDATE\_PRIMAL\_SIMPLEX**

The callback function is called in the primal simplex optimizer.

**MSK\_CALLBACK\_UPDATE\_PRIMAL\_SIMPLEX\_BI**

The callback function is called from within the basis identification procedure at an intermediate point in the primal simplex clean-up phase. The frequency of the callbacks is controlled by the *MSK\_IPAR\_LOG\_SIM\_FREQ* parameter.

**MSK\_CALLBACK\_WRITE\_OPF**

The callback function is called from the OPF writer.

### 11.5.14 Types of convexity checks.

**MSK\_CHECK\_CONVEXITY\_NONE**

No convexity check.

**MSK\_CHECK\_CONVEXITY\_SIMPLE**

Perform simple and fast convexity check.

**MSK\_CHECK\_CONVEXITY\_FULL**

Perform a full convexity check.

### 11.5.15 Compression types

**MSK\_COMPRESS\_NONE**

No compression is used.

**MSK\_COMPRESS\_FREE**

The type of compression used is chosen automatically.

**MSK\_COMPRESS\_GZIP**

The type of compression used is gzip compatible.

### 11.5.16 Cone types

**MSK\_CT\_QUAD**

The cone is a quadratic cone.

**MSK\_CT\_RQUAD**

The cone is a rotated quadratic cone.

### 11.5.17 Name types

**MSK\_NAME\_TYPE\_GEN**

General names. However, no duplicate and blank names are allowed.

**MSK\_NAME\_TYPE\_MPS**

MPS type names.

**MSK\_NAME\_TYPE\_LP**

LP type names.

### 11.5.18 Cone types

MSK\_SYMMAT\_TYPE\_SPARSE

Sparse symmetric matrix.

### 11.5.19 Data format types

MSK\_DATA\_FORMAT\_EXTENSION

The file extension is used to determine the data file format.

MSK\_DATA\_FORMAT\_MPS

The data file is MPS formatted.

MSK\_DATA\_FORMAT\_LP

The data file is LP formatted.

MSK\_DATA\_FORMAT\_OP

The data file is an optimization problem formatted file.

MSK\_DATA\_FORMAT\_XML

The data file is an XML formatted file.

MSK\_DATA\_FORMAT\_FREE\_MPS

The data a free MPS formatted file.

MSK\_DATA\_FORMAT\_TASK

Generic task dump file.

MSK\_DATA\_FORMAT\_CB

Conic benchmark format,

MSK\_DATA\_FORMAT\_JSON\_TASK

JSON based task format.

### 11.5.20 Double information items

MSK\_DINF\_BI\_CLEAN\_DUAL\_TIME

Time spent within the dual clean-up optimizer of the basis identification procedure since its invocation.

MSK\_DINF\_BI\_CLEAN\_PRIMAL\_TIME

Time spent within the primal clean-up optimizer of the basis identification procedure since its invocation.

MSK\_DINF\_BI\_CLEAN\_TIME

Time spent within the clean-up phase of the basis identification procedure since its invocation.

MSK\_DINF\_BI\_DUAL\_TIME

Time spent within the dual phase basis identification procedure since its invocation.

MSK\_DINF\_BI\_PRIMAL\_TIME

Time spent within the primal phase of the basis identification procedure since its invocation.

MSK\_DINF\_BI\_TIME

Time spent within the basis identification procedure since its invocation.

MSK\_DINF\_INTPNT\_DUAL\_FEAS

Dual feasibility measure reported by the interior-point optimizer. (For the interior-point optimizer this measure is not directly related to the original problem because a homogeneous model is employed.)

MSK\_DINF\_INTPNT\_DUAL\_OBJ

Dual objective value reported by the interior-point optimizer.

**MSK\_DINF\_INTPNT\_FACTOR\_NUM\_FLOPS**

An estimate of the number of flops used in the factorization.

**MSK\_DINF\_INTPNT\_OPT\_STATUS**

A measure of optimality of the solution. It should converge to +1 if the problem has a primal-dual optimal solution, and converge to -1 if the problem is (strictly) primal or dual infeasible. If the measure converges to another constant, or fails to settle, the problem is usually ill-posed.

**MSK\_DINF\_INTPNT\_ORDER\_TIME**

Order time (in seconds).

**MSK\_DINF\_INTPNT\_PRIMAL\_FEAS**

Primal feasibility measure reported by the interior-point optimizer. (For the interior-point optimizer this measure is not directly related to the original problem because a homogeneous model is employed).

**MSK\_DINF\_INTPNT\_PRIMAL\_OBJ**

Primal objective value reported by the interior-point optimizer.

**MSK\_DINF\_INTPNT\_TIME**

Time spent within the interior-point optimizer since its invocation.

**MSK\_DINF\_MIO\_CLIQUÉ\_SEPARATION\_TIME**

Separation time for clique cuts.

**MSK\_DINF\_MIO\_CMIR\_SEPARATION\_TIME**

Separation time for CMIR cuts.

**MSK\_DINF\_MIO\_CONSTRUCT\_SOLUTION\_OBJ**

If **MOSEK** has successfully constructed an integer feasible solution, then this item contains the optimal objective value corresponding to the feasible solution.

**MSK\_DINF\_MIO\_DUAL\_BOUND\_AFTER\_PRESOLVE**

Value of the dual bound after presolve but before cut generation.

**MSK\_DINF\_MIO\_GMI\_SEPARATION\_TIME**

Separation time for GMI cuts.

**MSK\_DINF\_MIO\_HEURISTIC\_TIME**

Total time spent in the optimizer.

**MSK\_DINF\_MIO\_IMPLIED\_BOUND\_TIME**

Separation time for implied bound cuts.

**MSK\_DINF\_MIO\_KNAPSACK\_COVER\_SEPARATION\_TIME**

Separation time for knapsack cover.

**MSK\_DINF\_MIO\_OBJ\_ABS\_GAP**

Given the mixed-integer optimizer has computed a feasible solution and a bound on the optimal objective value, then this item contains the absolute gap defined by

$$|(\text{objective value of feasible solution}) - (\text{objective bound})|.$$

Otherwise it has the value -1.0.

**MSK\_DINF\_MIO\_OBJ\_BOUND**

The best known bound on the objective function. This value is undefined until at least one relaxation has been solved: To see if this is the case check that *MSK\_IINF\_MIO\_NUM\_RELAX* is strictly positive.

**MSK\_DINF\_MIO\_OBJ\_INT**

The primal objective value corresponding to the best integer feasible solution. Please note that at least one integer feasible solution must have been located i.e. check *MSK\_IINF\_MIO\_NUM\_INT\_SOLUTIONS*.

**MSK\_DINF\_MIO\_OBJ\_REL\_GAP**

Given that the mixed-integer optimizer has computed a feasible solution and a bound on the optimal objective value, then this item contains the relative gap defined by

$$\frac{|(\text{objective value of feasible solution}) - (\text{objective bound})|}{\max(\delta, |(\text{objective value of feasible solution})|)}.$$

where  $\delta$  is given by the parameter `MSK_DPAR_MIO_REL_GAP_CONST`. Otherwise it has the value  $-1.0$ .

**MSK\_DINF\_MIO\_OPTIMIZER\_TIME**

Total time spent in the optimizer.

**MSK\_DINF\_MIO\_PROBING\_TIME**

Total time for probing.

**MSK\_DINF\_MIO\_ROOT\_CUTGEN\_TIME**

Total time for cut generation.

**MSK\_DINF\_MIO\_ROOT\_OPTIMIZER\_TIME**

Time spent in the optimizer while solving the root relaxation.

**MSK\_DINF\_MIO\_ROOT\_PRESOLVE\_TIME**

Time spent in while presolving the root relaxation.

**MSK\_DINF\_MIO\_TIME**

Time spent in the mixed-integer optimizer.

**MSK\_DINF\_MIO\_USER\_OBJ\_CUT**

If the objective cut is used, then this information item has the value of the cut.

**MSK\_DINF\_OPTIMIZER\_TIME**

Total time spent in the optimizer since it was invoked.

**MSK\_DINF\_PRESOLVE\_ELI\_TIME**

Total time spent in the eliminator since the presolve was invoked.

**MSK\_DINF\_PRESOLVE\_LINDEP\_TIME**

Total time spent in the linear dependency checker since the presolve was invoked.

**MSK\_DINF\_PRESOLVE\_TIME**

Total time (in seconds) spent in the presolve since it was invoked.

**MSK\_DINF\_PRIMAL\_REPAIR\_PENALTY\_OBJ**

The optimal objective value of the penalty function.

**MSK\_DINF\_QCQO\_REFORMULATE\_MAX\_PERTURBATION**

Maximum absolute diagonal perturbation occurring during the QCQO reformulation.

**MSK\_DINF\_QCQO\_REFORMULATE\_TIME**

Time spent with conic quadratic reformulation.

**MSK\_DINF\_QCQO\_REFORMULATE\_WORST\_CHOLESKY\_COLUMN\_SCALING**

Worst Cholesky column scaling.

**MSK\_DINF\_QCQO\_REFORMULATE\_WORST\_CHOLESKY\_DIAG\_SCALING**

Worst Cholesky diagonal scaling.

**MSK\_DINF\_RD\_TIME**

Time spent reading the data file.

**MSK\_DINF\_SIM\_DUAL\_TIME**

Time spent in the dual simplex optimizer since invoking it.

**MSK\_DINF\_SIM\_FEAS**

Feasibility measure reported by the simplex optimizer.

**MSK\_DINF\_SIM\_OBJ**

Objective value reported by the simplex optimizer.

MSK\_DINF\_SIM\_PRIMAL\_TIME

Time spent in the primal simplex optimizer since invoking it.

MSK\_DINF\_SIM\_TIME

Time spent in the simplex optimizer since invoking it.

MSK\_DINF\_SOL\_BAS\_DUAL\_OBJ

Dual objective value of the basic solution.

MSK\_DINF\_SOL\_BAS\_DVIOLCON

Maximal dual bound violation for  $x^c$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_DVIOLVAR

Maximal dual bound violation for  $x^x$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_NRM\_BARX

Infinity norm of  $\bar{X}$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_NRM\_SLC

Infinity norm of  $s_l^c$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_NRM\_SLX

Infinity norm of  $s_l^x$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_NRM\_SUC

Infinity norm of  $s_u^c$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_NRM\_SUX

Infinity norm of  $s_u^X$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_NRM\_XC

Infinity norm of  $x^c$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_NRM\_XX

Infinity norm of  $x^x$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_NRM\_Y

Infinity norm of  $y$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_PRIMAL\_OBJ

Primal objective value of the basic solution.

MSK\_DINF\_SOL\_BAS\_PVIOLCON

Maximal primal bound violation for  $x^c$  in the basic solution.

MSK\_DINF\_SOL\_BAS\_PVIOLVAR

Maximal primal bound violation for  $x^x$  in the basic solution.

MSK\_DINF\_SOL\_ITG\_NRM\_BARX

Infinity norm of  $\bar{X}$  in the integer solution.

MSK\_DINF\_SOL\_ITG\_NRM\_XC

Infinity norm of  $x^c$  in the integer solution.

MSK\_DINF\_SOL\_ITG\_NRM\_XX

Infinity norm of  $x^x$  in the integer solution.

MSK\_DINF\_SOL\_ITG\_PRIMAL\_OBJ

Primal objective value of the integer solution.

MSK\_DINF\_SOL\_ITG\_PVIOLBARVAR

Maximal primal bound violation for  $\bar{X}$  in the integer solution.

MSK\_DINF\_SOL\_ITG\_PVIOLCON

Maximal primal bound violation for  $x^c$  in the integer solution.

MSK\_DINF\_SOL\_ITG\_PVIOLCONES

Maximal primal violation for primal conic constraints in the integer solution.

MSK\_DINF\_SOL\_ITG\_PVIOLITG

Maximal violation for the integer constraints in the integer solution.

MSK\_DINF\_SOL\_ITG\_PVIOLVAR

Maximal primal bound violation for  $x^x$  in the integer solution.

MSK\_DINF\_SOL\_ITR\_DUAL\_OBJ

Dual objective value of the interior-point solution.

MSK\_DINF\_SOL\_ITR\_DVIOLBARVAR

Maximal dual bound violation for  $\bar{X}$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_DVIOLCON

Maximal dual bound violation for  $x^c$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_DVIOLCONES

Maximal dual violation for dual conic constraints in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_DVIOLVAR

Maximal dual bound violation for  $x^x$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_BARS

Infinity norm of  $\bar{S}$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_BARX

Infinity norm of  $\bar{X}$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_SLC

Infinity norm of  $s_l^c$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_SLX

Infinity norm of  $s_l^x$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_SNX

Infinity norm of  $s_n^x$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_SUC

Infinity norm of  $s_u^c$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_SUX

Infinity norm of  $s_u^X$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_XC

Infinity norm of  $x^c$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_XX

Infinity norm of  $x^x$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_NRM\_Y

Infinity norm of  $y$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_PRIMAL\_OBJ

Primal objective value of the interior-point solution.

MSK\_DINF\_SOL\_ITR\_PVIOLBARVAR

Maximal primal bound violation for  $\bar{X}$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_PVIOLCON

Maximal primal bound violation for  $x^c$  in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_PVIOLCONES

Maximal primal violation for primal conic constraints in the interior-point solution.

MSK\_DINF\_SOL\_ITR\_PVIOLVAR

Maximal primal bound violation for  $x^x$  in the interior-point solution.

MSK\_DINF\_TO\_CONIC\_TIME

Time spent in the last to conic reformulation.

### 11.5.21 License feature

MSK\_FEATURE\_PTS

Base system.

MSK\_FEATURE\_PTON

Nonlinear extension.

### 11.5.22 Long integer information items.

MSK\_LIINF\_BI\_CLEAN\_DUAL\_DEG\_ITER

Number of dual degenerate clean iterations performed in the basis identification.

MSK\_LIINF\_BI\_CLEAN\_DUAL\_ITER

Number of dual clean iterations performed in the basis identification.

MSK\_LIINF\_BI\_CLEAN\_PRIMAL\_DEG\_ITER

Number of primal degenerate clean iterations performed in the basis identification.

MSK\_LIINF\_BI\_CLEAN\_PRIMAL\_ITER

Number of primal clean iterations performed in the basis identification.

MSK\_LIINF\_BI\_DUAL\_ITER

Number of dual pivots performed in the basis identification.

MSK\_LIINF\_BI\_PRIMAL\_ITER

Number of primal pivots performed in the basis identification.

MSK\_LIINF\_INTPNT\_FACTOR\_NUM\_NZ

Number of non-zeros in factorization.

MSK\_LIINF\_MIO\_INTPNT\_ITER

Number of interior-point iterations performed by the mixed-integer optimizer.

MSK\_LIINF\_MIO\_PRE SOLVED\_ANZ

Number of non-zero entries in the constraint matrix of presolved problem.

MSK\_LIINF\_MIO\_SIM\_MAXITER\_SETBACKS

Number of times the the simplex optimizer has hit the maximum iteration limit when re-optimizing.

MSK\_LIINF\_MIO\_SIMPLEX\_ITER

Number of simplex iterations performed by the mixed-integer optimizer.

MSK\_LIINF\_RD\_NUMANZ

Number of non-zeros in A that is read.

MSK\_LIINF\_RD\_NUMQNZ

Number of Q non-zeros.

### 11.5.23 Integer information items.

MSK\_IINF\_ANA\_PRO\_NUM\_CON

Number of constraints in the problem.

MSK\_IINF\_ANA\_PRO\_NUM\_CON\_EQ

Number of equality constraints.

MSK\_IINF\_ANA\_PRO\_NUM\_CON\_FR

Number of unbounded constraints.

MSK\_IINF\_ANA\_PRO\_NUM\_CON\_LO

Number of constraints with a lower bound and an infinite upper bound.

MSK\_IINF\_ANA\_PRO\_NUM\_CON\_RA

Number of constraints with finite lower and upper bounds.

MSK\_IINF\_ANA\_PRO\_NUM\_CON\_UP

Number of constraints with an upper bound and an infinite lower bound.

MSK\_IINF\_ANA\_PRO\_NUM\_VAR

Number of variables in the problem.

MSK\_IINF\_ANA\_PRO\_NUM\_VAR\_BIN

Number of binary (0-1) variables.

MSK\_IINF\_ANA\_PRO\_NUM\_VAR\_CONT

Number of continuous variables.

MSK\_IINF\_ANA\_PRO\_NUM\_VAR\_EQ

Number of fixed variables.

MSK\_IINF\_ANA\_PRO\_NUM\_VAR\_FR

Number of free variables.

MSK\_IINF\_ANA\_PRO\_NUM\_VAR\_INT

Number of general integer variables.

MSK\_IINF\_ANA\_PRO\_NUM\_VAR\_LO

Number of variables with a lower bound and an infinite upper bound.

MSK\_IINF\_ANA\_PRO\_NUM\_VAR\_RA

Number of variables with finite lower and upper bounds.

MSK\_IINF\_ANA\_PRO\_NUM\_VAR\_UP

Number of variables with an upper bound and an infinite lower bound. This value is set by

MSK\_IINF\_INTPNT\_FACTOR\_DIM\_DENSE

Dimension of the dense sub system in factorization.

MSK\_IINF\_INTPNT\_ITER

Number of interior-point iterations since invoking the interior-point optimizer.

MSK\_IINF\_INTPNT\_NUM\_THREADS

Number of threads that the interior-point optimizer is using.

MSK\_IINF\_INTPNT\_SOLVE\_DUAL

Non-zero if the interior-point optimizer is solving the dual problem.

MSK\_IINF\_MIO\_ABSGAP\_SATISFIED

Non-zero if absolute gap is within tolerances.

MSK\_IINF\_MIO\_CLIQUE\_TABLE\_SIZE

Size of the clique table.

MSK\_IINF\_MIO\_CONSTRUCT\_NUM\_ROUNDINGS

Number of values in the integer solution that is rounded to an integer value.

MSK\_IINF\_MIO\_CONSTRUCT\_SOLUTION

If this item has the value 0, then **MOSEK** did not try to construct an initial integer feasible solution. If the item has a positive value, then **MOSEK** successfully constructed an initial integer feasible solution.

MSK\_IINF\_MIO\_INITIAL\_SOLUTION

Is non-zero if an initial integer solution is specified.

MSK\_IINF\_MIO\_NEAR\_ABSGAP\_SATISFIED

Non-zero if absolute gap is within relaxed tolerances.

MSK\_IINF\_MIO\_NEAR\_RELGAP\_SATISFIED

Non-zero if relative gap is within relaxed tolerances.

MSK\_IINF\_MIO\_NODE\_DEPTH

Depth of the last node solved.

---

|                                      |  |
|--------------------------------------|--|
| MSK_IINF_MIO_NUM_ACTIVE_NODES        | Number of active branch bound nodes.   |
| MSK_IINF_MIO_NUM_BRANCH              | Number of branches performed during the optimization.                                |
| MSK_IINF_MIO_NUM_CLIQUE_CUTS         | Number of clique cuts.   |
| MSK_IINF_MIO_NUM_CMIR_CUTS           | Number of Complemented Mixed Integer Rounding (CMIR) cuts.                           |
| MSK_IINF_MIO_NUM_GOMORY_CUTS         | Number of Gomory cuts.   |
| MSK_IINF_MIO_NUM_IMPLIED_BOUND_CUTS  | Number of implied bound cuts.  |
| MSK_IINF_MIO_NUM_INT_SOLUTIONS       | Number of integer feasible solutions that has been found.                            |
| MSK_IINF_MIO_NUM_KNAPSACK_COVER_CUTS | Number of clique cuts.   |
| MSK_IINF_MIO_NUM_RELAX               | Number of relaxations solved during the optimization.                                |
| MSK_IINF_MIO_NUM_REPEATED_PRESOLVE   | Number of times presolve was repeated at root.                                       |
| MSK_IINF_MIO_NUMCON                  | Number of constraints in the problem solved by the mixed-integer optimizer.          |
| MSK_IINF_MIO_NUMINT                  | Number of integer variables in the problem solved by the mixed-integer optimizer.    |
| MSK_IINF_MIO_NUMVAR                  | Number of variables in the problem solved by the mixed-integer optimizer.            |
| MSK_IINF_MIO_OBJ_BOUND_DEFINED       | Non-zero if a valid objective bound has been found, otherwise zero.                  |
| MSK_IINF_MIO_PRESOLVED_NUMBIN        | Number of binary variables in the problem solved by the mixed-integer optimizer.     |
| MSK_IINF_MIO_PRESOLVED_NUMCON        | Number of constraints in the presolved problem.                                      |
| MSK_IINF_MIO_PRESOLVED_NUMCONT       | Number of continuous variables in the problem solved by the mixed-integer optimizer. |
| MSK_IINF_MIO_PRESOLVED_NUMINT        | Number of integer variables in the presolved problem.                                |
| MSK_IINF_MIO_PRESOLVED_NUMVAR        | Number of variables in the presolved problem.  |
| MSK_IINF_MIO_RELGAP_SATISFIED        | Non-zero if relative gap is within tolerances.                                       |
| MSK_IINF_MIO_TOTAL_NUM_CUTS          | Total number of cuts generated by the mixed-integer optimizer.                       |
| MSK_IINF_MIO_USER_OBJ_CUT            | If it is non-zero, then the objective cut is used.                                   |
| MSK_IINF_OPT_NUMCON                  | Number of constraints in the problem solved when the optimizer is called.            |

|                                 |  |
|---------------------------------|--|
| MSK_IINF_OPT_NUMVAR             | Number of variables in the problem solved when the optimizer is called                                   |
| MSK_IINF_OPTIMIZE_RESPONSE      | The response code returned by optimize.  |
| MSK_IINF_RD_NUMBARVAR           | Number of variables read.  |
| MSK_IINF_RD_NUMCON              | Number of constraints read.  |
| MSK_IINF_RD_NUMCONE             | Number of conic constraints read.  |
| MSK_IINF_RD_NUMINTVAR           | Number of integer-constrained variables read.  |
| MSK_IINF_RD_NUMQ                | Number of nonempty Q matrices read.  |
| MSK_IINF_RD_NUMVAR              | Number of variables read.  |
| MSK_IINF_RD_PROTOTYPE           | Problem type.  |
| MSK_IINF_SIM_DUAL_DEG_ITER      | The number of dual degenerate iterations.  |
| MSK_IINF_SIM_DUAL_HOTSTART      | If 1 then the dual simplex algorithm is solving from an advanced basis.                                  |
| MSK_IINF_SIM_DUAL_HOTSTART_LU   | If 1 then a valid basis factorization of full rank was located and used by the dual simplex algorithm.   |
| MSK_IINF_SIM_DUAL_INF_ITER      | The number of iterations taken with dual infeasibility.  |
| MSK_IINF_SIM_DUAL_ITER          | Number of dual simplex iterations during the last optimization.  |
| MSK_IINF_SIM_NUMCON             | Number of constraints in the problem solved by the simplex optimizer.                                    |
| MSK_IINF_SIM_NUMVAR             | Number of variables in the problem solved by the simplex optimizer.                                      |
| MSK_IINF_SIM_PRIMAL_DEG_ITER    | The number of primal degenerate iterations.  |
| MSK_IINF_SIM_PRIMAL_HOTSTART    | If 1 then the primal simplex algorithm is solving from an advanced basis.                                |
| MSK_IINF_SIM_PRIMAL_HOTSTART_LU | If 1 then a valid basis factorization of full rank was located and used by the primal simplex algorithm. |
| MSK_IINF_SIM_PRIMAL_INF_ITER    | The number of iterations taken with primal infeasibility.  |
| MSK_IINF_SIM_PRIMAL_ITER        | Number of primal simplex iterations during the last optimization.  |
| MSK_IINF_SIM_SOLVE_DUAL         | Is non-zero if dual problem is solved.   |
| MSK_IINF_SOL_BAS_PROSTA         | Problem status of the basic solution. Updated after each optimization.                                   |

MSK\_IINF\_SOL\_BAS\_SOLSTA

Solution status of the basic solution. Updated after each optimization.

MSK\_IINF\_SOL\_ITG\_PROSTA

Problem status of the integer solution. Updated after each optimization.

MSK\_IINF\_SOL\_ITG\_SOLSTA

Solution status of the integer solution. Updated after each optimization.

MSK\_IINF\_SOL\_ITR\_PROSTA

Problem status of the interior-point solution. Updated after each optimization.

MSK\_IINF\_SOL\_ITR\_SOLSTA

Solution status of the interior-point solution. Updated after each optimization.

MSK\_IINF\_STO\_NUM\_A\_REALLOC

Number of times the storage for storing  $A$  has been changed. A large value may indicate that memory fragmentation may occur.

### 11.5.24 Information item types

MSK\_INF\_DOU\_TYPE

Is a double information type.

MSK\_INF\_INT\_TYPE

Is an integer.

MSK\_INF\_LINT\_TYPE

Is a long integer.

### 11.5.25 Input/output modes

MSK\_IOMODE\_READ

The file is read-only.

MSK\_IOMODE\_WRITE

The file is write-only. If the file exists then it is truncated when it is opened. Otherwise it is created when it is opened.

MSK\_IOMODE\_READWRITE

The file is to read and written.

### 11.5.26 Specifies the branching direction.

MSK\_BRANCH\_DIR\_FREE

The mixed-integer optimizer decides which branch to choose.

MSK\_BRANCH\_DIR\_UP

The mixed-integer optimizer always chooses the up branch first.

MSK\_BRANCH\_DIR\_DOWN

The mixed-integer optimizer always chooses the down branch first.

MSK\_BRANCH\_DIR\_NEAR

Branch in direction nearest to selected fractional variable.

MSK\_BRANCH\_DIR\_FAR

Branch in direction farthest from selected fractional variable.

MSK\_BRANCH\_DIR\_ROOT\_LP

Chose direction based on root lp value of selected variable.

**MSK\_BRANCH\_DIR\_GUIDED**

Branch in direction of current incumbent.

**MSK\_BRANCH\_DIR\_PSEUDOCOST**

Branch based on the pseudocost of the variable.

### 11.5.27 Continuous mixed-integer solution type

**MSK\_MIO\_CONT\_SOL\_NONE**

No interior-point or basic solution are reported when the mixed-integer optimizer is used.

**MSK\_MIO\_CONT\_SOL\_ROOT**

The reported interior-point and basic solutions are a solution to the root node problem when mixed-integer optimizer is used.

**MSK\_MIO\_CONT\_SOL\_ITG**

The reported interior-point and basic solutions are a solution to the problem with all integer variables fixed at the value they have in the integer solution. A solution is only reported in case the problem has a primal feasible solution.

**MSK\_MIO\_CONT\_SOL\_ITG\_REL**

In case the problem is primal feasible then the reported interior-point and basic solutions are a solution to the problem with all integer variables fixed at the value they have in the integer solution. If the problem is primal infeasible, then the solution to the root node problem is reported.

### 11.5.28 Integer restrictions

**MSK\_MIO\_MODE\_IGNORED**

The integer constraints are ignored and the problem is solved as a continuous problem.

**MSK\_MIO\_MODE\_SATISFIED**

Integer restrictions should be satisfied.

### 11.5.29 Mixed-integer node selection types

**MSK\_MIO\_NODE\_SELECTION\_FREE**

The optimizer decides the node selection strategy.

**MSK\_MIO\_NODE\_SELECTION\_FIRST**

The optimizer employs a depth first node selection strategy.

**MSK\_MIO\_NODE\_SELECTION\_BEST**

The optimizer employs a best bound node selection strategy.

**MSK\_MIO\_NODE\_SELECTION\_WORST**

The optimizer employs a worst bound node selection strategy.

**MSK\_MIO\_NODE\_SELECTION\_HYBRID**

The optimizer employs a hybrid strategy.

**MSK\_MIO\_NODE\_SELECTION\_PSEUDO**

The optimizer employs selects the node based on a pseudo cost estimate.

### 11.5.30 MPS file format type

**MSK\_MPS\_FORMAT\_STRICT**

It is assumed that the input file satisfies the MPS format strictly.

**MSK\_MPS\_FORMAT\_RELAXED**

It is assumed that the input file satisfies a slightly relaxed version of the MPS format.

**MSK\_MPS\_FORMAT\_FREE**

It is assumed that the input file satisfies the free MPS format. This implies that spaces are not allowed in names. Otherwise the format is free.

**MSK\_MPS\_FORMAT\_CPLEX**

The CPLEX compatible version of the MPS format is employed.

### 11.5.31 Objective sense types

**MSK\_OBJECTIVE\_SENSE\_MINIMIZE**

The problem should be minimized.

**MSK\_OBJECTIVE\_SENSE\_MAXIMIZE**

The problem should be maximized.

### 11.5.32 On/off

**MSK\_ON**

Switch the option on.

**MSK\_OFF**

Switch the option off.

### 11.5.33 Optimizer types

**MSK\_OPTIMIZER\_CONIC**

The optimizer for problems having conic constraints.

**MSK\_OPTIMIZER\_DUAL\_SIMPLEX**

The dual simplex optimizer is used.

**MSK\_OPTIMIZER\_FREE**

The optimizer is chosen automatically.

**MSK\_OPTIMIZER\_FREE\_SIMPLEX**

One of the simplex optimizers is used.

**MSK\_OPTIMIZER\_INTPNT**

The interior-point optimizer is used.

**MSK\_OPTIMIZER\_MIXED\_INT**

The mixed-integer optimizer.

**MSK\_OPTIMIZER\_PRIMAL\_SIMPLEX**

The primal simplex optimizer is used.

### 11.5.34 Ordering strategies

**MSK\_ORDER\_METHOD\_FREE**

The ordering method is chosen automatically.

**MSK\_ORDER\_METHOD\_APPMINLOC**

Approximate minimum local fill-in ordering is employed.

**MSK\_ORDER\_METHOD\_EXPERIMENTAL**

This option should not be used.

**MSK\_ORDER\_METHOD\_TRY\_GRAPHPAR**

Always try the graph partitioning based ordering.

MSK\_ORDER\_METHOD\_FORCE\_GRAPHPAR

Always use the graph partitioning based ordering even if it is worse than the approximate minimum local fill ordering.

MSK\_ORDER\_METHOD\_NONE

No ordering is used.

### 11.5.35 Presolve method.

MSK\_PRESOLVE\_MODE\_OFF

The problem is not presolved before it is optimized.

MSK\_PRESOLVE\_MODE\_ON

The problem is presolved before it is optimized.

MSK\_PRESOLVE\_MODE\_FREE

It is decided automatically whether to presolve before the problem is optimized.

### 11.5.36 Parameter type

MSK\_PAR\_INVALID\_TYPE

Not a valid parameter.

MSK\_PAR\_DOUB\_TYPE

Is a double parameter.

MSK\_PAR\_INT\_TYPE

Is an integer parameter.

MSK\_PAR\_STR\_TYPE

Is a string parameter.

### 11.5.37 Problem data items

MSK\_PI\_VAR

Item is a variable.

MSK\_PI\_CON

Item is a constraint.

MSK\_PI\_CONE

Item is a cone.

### 11.5.38 Problem types

MSK\_PROBTYPE\_LO

The problem is a linear optimization problem.

MSK\_PROBTYPE\_QO

The problem is a quadratic optimization problem.

MSK\_PROBTYPE\_QCQO

The problem is a quadratically constrained optimization problem.

MSK\_PROBTYPE\_GECO

General convex optimization.

MSK\_PROBTYPE\_CONIC

A conic optimization.

MSK\_PROBTYPE\_MIXED

General nonlinear constraints and conic constraints. This combination can not be solved by MOSEK.

### 11.5.39 Problem status keys

MSK\_PRO\_STA\_UNKNOWN

Unknown problem status.

MSK\_PRO\_STA\_PRIM\_AND\_DUAL\_FEAS

The problem is primal and dual feasible.

MSK\_PRO\_STA\_PRIM\_FEAS

The problem is primal feasible.

MSK\_PRO\_STA\_DUAL\_FEAS

The problem is dual feasible.

MSK\_PRO\_STA\_NEAR\_PRIM\_AND\_DUAL\_FEAS

The problem is at least nearly primal and dual feasible.

MSK\_PRO\_STA\_NEAR\_PRIM\_FEAS

The problem is at least nearly primal feasible.

MSK\_PRO\_STA\_NEAR\_DUAL\_FEAS

The problem is at least nearly dual feasible.

MSK\_PRO\_STA\_PRIM\_INFEAS

The problem is primal infeasible.

MSK\_PRO\_STA\_DUAL\_INFEAS

The problem is dual infeasible.

MSK\_PRO\_STA\_PRIM\_AND\_DUAL\_INFEAS

The problem is primal and dual infeasible.

MSK\_PRO\_STA\_ILL\_POSED

The problem is ill-posed. For example, it may be primal and dual feasible but have a positive duality gap.

MSK\_PRO\_STA\_PRIM\_INFEAS\_OR\_UNBOUNDED

The problem is either primal infeasible or unbounded. This may occur for mixed-integer problems.

### 11.5.40 XML writer output mode

MSK\_WRITE\_XML\_MODE\_ROW

Write in row order.

MSK\_WRITE\_XML\_MODE\_COL

Write in column order.

### 11.5.41 Response code type

MSK\_RESPONSE\_OK

The response code is OK.

MSK\_RESPONSE\_WRN

The response code is a warning.

MSK\_RESPONSE\_TRM

The response code is an optimizer termination status.

MSK\_RESPONSE\_ERR

The response code is an error.

MSK\_RESPONSE\_UNK

The response code does not belong to any class.

### 11.5.42 Scaling type

MSK\_SCALING\_FREE

The optimizer chooses the scaling heuristic.

MSK\_SCALING\_NONE

No scaling is performed.

MSK\_SCALING\_MODERATE

A conservative scaling is performed.

MSK\_SCALING\_AGGRESSIVE

A very aggressive scaling is performed.

### 11.5.43 Scaling method

MSK\_SCALING\_METHOD\_POW2

Scales only with power of 2 leaving the mantissa untouched.

MSK\_SCALING\_METHOD\_FREE

The optimizer chooses the scaling heuristic.

### 11.5.44 Sensitivity types

MSK\_SENSITIVITY\_TYPE\_BASIS

Basis sensitivity analysis is performed.

MSK\_SENSITIVITY\_TYPE\_OPTIMAL\_PARTITION

Optimal partition sensitivity analysis is performed.

### 11.5.45 Simplex selection strategy

MSK\_SIM\_SELECTION\_FREE

The optimizer chooses the pricing strategy.

MSK\_SIM\_SELECTION\_FULL

The optimizer uses full pricing.

MSK\_SIM\_SELECTION\_ASE

The optimizer uses approximate steepest-edge pricing.

MSK\_SIM\_SELECTION\_DEVEX

The optimizer uses devex steepest-edge pricing (or if it is not available an approximate steep-edge selection).

MSK\_SIM\_SELECTION\_SE

The optimizer uses steepest-edge selection (or if it is not available an approximate steep-edge selection).

MSK\_SIM\_SELECTION\_PARTIAL

The optimizer uses a partial selection approach. The approach is usually beneficial if the number of variables is much larger than the number of constraints.

### 11.5.46 Solution items

MSK\_SOL\_ITEM\_XC

Solution for the constraints.

MSK\_SOL\_ITEM\_XX

Variable solution.

MSK\_SOL\_ITEM\_Y

Lagrange multipliers for equations.

MSK\_SOL\_ITEM\_SLC

Lagrange multipliers for lower bounds on the constraints.

MSK\_SOL\_ITEM\_SUC

Lagrange multipliers for upper bounds on the constraints.

MSK\_SOL\_ITEM\_SLX

Lagrange multipliers for lower bounds on the variables.

MSK\_SOL\_ITEM\_SUX

Lagrange multipliers for upper bounds on the variables.

MSK\_SOL\_ITEM\_SNX

Lagrange multipliers corresponding to the conic constraints on the variables.

### 11.5.47 Solution status keys

MSK\_SOL\_STA\_UNKNOWN

Status of the solution is unknown.

MSK\_SOL\_STA\_OPTIMAL

The solution is optimal.

MSK\_SOL\_STA\_PRIM\_FEAS

The solution is primal feasible.

MSK\_SOL\_STA\_DUAL\_FEAS

The solution is dual feasible.

MSK\_SOL\_STA\_PRIM\_AND\_DUAL\_FEAS

The solution is both primal and dual feasible.

MSK\_SOL\_STA\_NEAR\_OPTIMAL

The solution is nearly optimal.

MSK\_SOL\_STA\_NEAR\_PRIM\_FEAS

The solution is nearly primal feasible.

MSK\_SOL\_STA\_NEAR\_DUAL\_FEAS

The solution is nearly dual feasible.

MSK\_SOL\_STA\_NEAR\_PRIM\_AND\_DUAL\_FEAS

The solution is nearly both primal and dual feasible.

MSK\_SOL\_STA\_PRIM\_INFEAS\_CER

The solution is a certificate of primal infeasibility.

MSK\_SOL\_STA\_DUAL\_INFEAS\_CER

The solution is a certificate of dual infeasibility.

MSK\_SOL\_STA\_NEAR\_PRIM\_INFEAS\_CER

The solution is almost a certificate of primal infeasibility.

MSK\_SOL\_STA\_NEAR\_DUAL\_INFEAS\_CER

The solution is almost a certificate of dual infeasibility.

MSK\_SOL\_STA\_PRIM\_ILLPOSED\_CER

The solution is a certificate that the primal problem is illposed.

MSK\_SOL\_STA\_DUAL\_ILLPOSED\_CER

The solution is a certificate that the dual problem is illposed.

MSK\_SOL\_STA\_INTEGER\_OPTIMAL

The primal solution is integer optimal.

MSK\_SOL\_STA\_NEAR\_INTEGER\_OPTIMAL

The primal solution is near integer optimal.

### 11.5.48 Solution types

MSK\_SOL\_BAS

The basic solution.

MSK\_SOL\_ITR

The interior solution.

MSK\_SOL\_ITG

The integer solution.

### 11.5.49 Solve primal or dual form

MSK\_SOLVE\_FREE

The optimizer is free to solve either the primal or the dual problem.

MSK\_SOLVE\_PRIMAL

The optimizer should solve the primal problem.

MSK\_SOLVE\_DUAL

The optimizer should solve the dual problem.

### 11.5.50 Status keys

MSK\_SK\_UNK

The status for the constraint or variable is unknown.

MSK\_SK\_BAS

The constraint or variable is in the basis.

MSK\_SK\_SUPBAS

The constraint or variable is super basic.

MSK\_SK\_LOW

The constraint or variable is at its lower bound.

MSK\_SK\_UPR

The constraint or variable is at its upper bound.

MSK\_SK\_FIX

The constraint or variable is fixed.

MSK\_SK\_INF

The constraint or variable is infeasible in the bounds.

### 11.5.51 Starting point types

MSK\_STARTING\_POINT\_FREE

The starting point is chosen automatically.

**MSK\_STARTING\_POINT\_GUESS**

The optimizer guesses a starting point.

**MSK\_STARTING\_POINT\_CONSTANT**

The optimizer constructs a starting point by assigning a constant value to all primal and dual variables. This starting point is normally robust.

**MSK\_STARTING\_POINT\_SATISFY\_BOUNDS**

The starting point is chosen to satisfy all the simple bounds on nonlinear variables. If this starting point is employed, then more care than usual should be employed when choosing the bounds on the nonlinear variables. In particular very tight bounds should be avoided.

### 11.5.52 Stream types

**MSK\_STREAM\_LOG**

Log stream. Contains the aggregated contents of all other streams. This means that a message written to any other stream will also be written to this stream.

**MSK\_STREAM\_MSG**

Message stream. Log information relating to performance and progress of the optimization is written to this stream.

**MSK\_STREAM\_ERR**

Error stream. Error messages are written to this stream.

**MSK\_STREAM\_WRN**

Warning stream. Warning messages are written to this stream.

### 11.5.53 Integer values

**MSK\_MAX\_STR\_LEN**

Maximum string length allowed in **MOSEK**.

**MSK\_LICENSE\_BUFFER\_LENGTH**

The length of a license key buffer.

### 11.5.54 Variable types

**MSK\_VAR\_TYPE\_CONT**

Is a continuous variable.

**MSK\_VAR\_TYPE\_INT**

Is an integer variable.



## SUPPORTED FILE FORMATS

**MOSEK** supports a range of problem and solution formats listed in [Table 12.1](#) and [Table 12.2](#). The **Task format** is **MOSEK**'s native binary format and it supports all features that **MOSEK** supports. The **OPF format** is **MOSEK**'s human-readable alternative that supports nearly all features (everything except semidefinite problems). In general, text formats are significantly slower to read, but can be examined and edited directly in any text editor.

### Problem formats

See [Table 12.1](#).

Table 12.1: List of supported file formats for optimization problems.

| Format Type         | Ext.  | Binary/Text | LP | QO | CQO | SDP |
|---------------------|-------|-------------|----|----|-----|-----|
| <i>LP</i>           | lp    | plain text  | X  | X  |     |     |
| <i>MPS</i>          | mps   | plain text  | X  | X  |     |     |
| <i>OPF</i>          | opf   | plain text  | X  | X  | X   |     |
| <i>CBF</i>          | cbf   | plain text  | X  |    | X   | X   |
| <i>OSiL</i>         | xml   | xml text    | X  | X  |     |     |
| <i>Task format</i>  | task  | binary      | X  | X  | X   | X   |
| <i>Jtask format</i> | jtask | text        | X  | X  | X   | X   |

### Solution formats

See [Table 12.2](#).

Table 12.2: List of supported solution formats.

| Format Type        | Ext. | Binary/Text | Description       |
|--------------------|------|-------------|-------------------|
| <i>SOL</i>         | sol  | plain text  | Interior Solution |
|                    | bas  | plain text  | Basic Solution    |
|                    | int  | plain text  | Integer           |
| <i>Jsol format</i> | jsol | text        | Solution          |

### Compression

**MOSEK** supports GZIP compression of files. Problem files with an additional `.gz` extension are assumed to be compressed when read, and are automatically compressed when written. For example, a file called

problem.mps.gz

will be considered as a GZIP compressed MPS file.

## 12.1 The LP File Format

**MOSEK** supports the LP file format with some extensions. The LP format is not a completely well-defined standard and hence different optimization packages may interpret the same LP file in slightly different ways. **MOSEK** tries to emulate as closely as possible CPLEX's behavior, but tries to stay backward compatible.

The LP file format can specify problems on the form

$$\begin{array}{ll} \text{minimize/maximize} & c^T x + \frac{1}{2} q^o(x) \\ \text{subject to} & \begin{array}{lll} l^c \leq & Ax + \frac{1}{2} q(x) & \leq u^c, \\ l^x \leq & x & \leq u^x, \\ & x_{\mathcal{J}} \text{ integer,} \end{array} \end{array}$$

where

- $x \in \mathbb{R}^n$  is the vector of decision variables.
- $c \in \mathbb{R}^n$  is the linear term in the objective.
- $q^o : \mathbb{R}^n \rightarrow \mathbb{R}$  is the quadratic term in the objective where

$$q^o(x) = x^T Q^o x$$

and it is assumed that

$$Q^o = (Q^o)^T.$$

- $A \in \mathbb{R}^{m \times n}$  is the constraint matrix.
- $l^c \in \mathbb{R}^m$  is the lower limit on the activity for the constraints.
- $u^c \in \mathbb{R}^m$  is the upper limit on the activity for the constraints.
- $l^x \in \mathbb{R}^n$  is the lower limit on the activity for the variables.
- $u^x \in \mathbb{R}^n$  is the upper limit on the activity for the variables.
- $q : \mathbb{R}^n \rightarrow \mathbb{R}$  is a vector of quadratic functions. Hence,

$$q_i(x) = x^T Q^i x$$

where it is assumed that

$$Q^i = (Q^i)^T.$$

- $\mathcal{J} \subseteq \{1, 2, \dots, n\}$  is an index set of the integer constrained variables.

### 12.1.1 File Sections

An LP formatted file contains a number of sections specifying the objective, constraints, variable bounds, and variable types. The section keywords may be any mix of upper and lower case letters.

#### Objective Function

The first section beginning with one of the keywords

```
max
maximum
maximize
min
minimum
minimize
```

defines the objective sense and the objective function, i.e.

$$c^T x + \frac{1}{2} x^T Q^o x.$$

The objective may be given a name by writing

```
myname:
```

before the expressions. If no name is given, then the objective is named `obj`.

The objective function contains linear and quadratic terms. The linear terms are written as:

```
4 x1 + x2 - 0.1 x3
```

and so forth. The quadratic terms are written in square brackets ( `[ ]` ) and are either squared or multiplied as in the examples

```
x1^2
```

and

```
x1 * x2
```

There may be zero or more pairs of brackets containing quadratic expressions.

An example of an objective section is

```
minimize
myobj: 4 x1 + x2 - 0.1 x3 + [ x1^2 + 2.1 x1 * x2 ]/2
```

Please note that the quadratic expressions are multiplied with  $\frac{1}{2}$ , so that the above expression means

$$\text{minimize } 4x_1 + x_2 - 0.1 \cdot x_3 + \frac{1}{2}(x_1^2 + 2.1 \cdot x_1 \cdot x_2)$$

If the same variable occurs more than once in the linear part, the coefficients are added, so that `4 x1 + 2 x1` is equivalent to `6 x1`. In the quadratic expressions `x1 * x2` is equivalent to `x2 * x1` and, as in the linear part, if the same variables multiplied or squared occur several times their coefficients are added.

## Constraints

The second section beginning with one of the keywords

```
subj to
subject to
s.t.
st
```

defines the linear constraint matrix  $A$  and the quadratic matrices  $Q^i$ .

A constraint contains a name (optional), expressions adhering to the same rules as in the objective and a bound:

```
subject to
con1: x1 + x2 + [ x3^2 ]/2 <= 5.1
```

The bound type (here  $\leq$ ) may be any of  $<$ ,  $\leq$ ,  $=$ ,  $>$ ,  $\geq$  ( $<$  and  $\leq$  mean the same), and the bound may be any number.

In the standard LP format it is not possible to define more than one bound, but **MOSEK** supports defining ranged constraints by using double-colon ( $::$ ) instead of a single-colon ( $:$ ) after the constraint name, i.e.

$$-5 \leq x_1 + x_2 \leq 5 \quad (12.1)$$

may be written as

```
con:: -5 < x_1 + x_2 < 5
```

By default **MOSEK** writes ranged constraints this way.

If the files must adhere to the LP standard, ranged constraints must either be split into upper bounded and lower bounded constraints or be written as an equality with a slack variable. For example the expression (12.1) may be written as

$$x_1 + x_2 - sl_1 = 0, \quad -5 \leq sl_1 \leq 5.$$

## Bounds

Bounds on the variables can be specified in the bound section beginning with one of the keywords

```
bound
bounds
```

The bounds section is optional but should, if present, follow the **subject to** section. All variables listed in the bounds section must occur in either the objective or a constraint.

The default lower and upper bounds are 0 and  $+\infty$ . A variable may be declared free with the keyword **free**, which means that the lower bound is  $-\infty$  and the upper bound is  $+\infty$ . Furthermore it may be assigned a finite lower and upper bound. The bound definitions for a given variable may be written in one or two lines, and bounds can be any number or  $\pm\infty$  (written as **+inf/-inf/+infinity/-infinity**) as in the example

```
bounds
x1 free
x2 <= 5
0.1 <= x2
x3 = 42
2 <= x4 < +inf
```

## Variable Types

The final two sections are optional and must begin with one of the keywords

```
bin
binaries
binary
```

and

```
gen
general
```

Under **general** all integer variables are listed, and under **binary** all binary (integer variables with bounds 0 and 1) are listed:

```

general
x1 x2
binary
x3 x4

```

Again, all variables listed in the binary or general sections must occur in either the objective or a constraint.

### Terminating Section

Finally, an LP formatted file must be terminated with the keyword

```
end
```

## 12.1.2 LP File Examples

### Linear example lo1.lp

```

\ File: lo1.lp
maximize
obj: 3 x1 + x2 + 5 x3 + x4
subject to
c1: 3 x1 + x2 + 2 x3 = 30
c2: 2 x1 + x2 + 3 x3 + x4 >= 15
c3: 2 x2 + 3 x4 <= 25
bounds
0 <= x1 <= +infinity
0 <= x2 <= 10
0 <= x3 <= +infinity
0 <= x4 <= +infinity
end

```

### Mixed integer example milo1.lp

```

maximize
obj: x1 + 6.4e-01 x2
subject to
c1: 5e+01 x1 + 3.1e+01 x2 <= 2.5e+02
c2: 3e+00 x1 - 2e+00 x2 >= -4e+00
bounds
0 <= x1 <= +infinity
0 <= x2 <= +infinity
general
x1 x2
end

```

## 12.1.3 LP Format peculiarities

### Comments

Anything on a line after a \ is ignored and is treated as a comment.

## Names

A name for an objective, a constraint or a variable may contain the letters *a-z*, *A-Z*, the digits *0-9* and the characters

|                      |
|----------------------|
| !"#\$%&()/,.;?@_`' ~ |
|----------------------|

The first character in a name must not be a number, a period or the letter *e* or *E*. Keywords must not be used as names.

**MOSEK** accepts any character as valid for names, except `\0`. A name that is not allowed in LP file will be changed and a warning will be issued.

The algorithm for making names LP valid works as follows: The name is interpreted as an `utf-8` string. For a unicode character *c*:

- If *c*==`_` (underscore), the output is `__` (two underscores).
- If *c* is a valid LP name character, the output is just *c*.
- If *c* is another character in the ASCII range, the output is `_XX`, where *XX* is the hexadecimal code for the character.
- If *c* is a character in the range *127-65535*, the output is `_uXXXX`, where *XXXX* is the hexadecimal code for the character.
- If *c* is a character above 65535, the output is `_UXXXXXXXX`, where *XXXXXXXX* is the hexadecimal code for the character.

Invalid `utf-8` substrings are escaped as `_XX'`, and if a name starts with a period, *e* or *E*, that character is escaped as `_XX`.

## Variable Bounds

Specifying several upper or lower bounds on one variable is possible but **MOSEK** uses only the tightest bounds. If a variable is fixed (with `=`), then it is considered the tightest bound.

## MOSEK Extensions to the LP Format

Some optimization software packages employ a more strict definition of the LP format than the one used by **MOSEK**. The limitations imposed by the strict LP format are the following:

- Quadratic terms in the constraints are not allowed.
- Names can be only 16 characters long.
- Lines must not exceed 255 characters in length.

If an LP formatted file created by **MOSEK** should satisfy the strict definition, then the parameter

- `MSK_IPAR_WRITE_LP_STRICT_FORMAT`

should be set; note, however, that some problems cannot be written correctly as a strict LP formatted file. For instance, all names are truncated to 16 characters and hence they may lose their uniqueness and change the problem.

To get around some of the inconveniences converting from other problem formats, **MOSEK** allows lines to contain 1024 characters and names may have any length (shorter than the 1024 characters).

Internally in **MOSEK** names may contain any (printable) character, many of which cannot be used in LP names. Setting the parameters

- `MSK_IPAR_READ_LP_QUOTED_NAMES` and
- `MSK_IPAR_WRITE_LP_QUOTED_NAMES`

allows **MOSEK** to use quoted names. The first parameter tells **MOSEK** to remove quotes from quoted names e.g, "x1", when reading LP formatted files. The second parameter tells **MOSEK** to put quotes around any semi-illegal name (names beginning with a number or a period) and fully illegal name (containing illegal characters). As double quote is a legal character in the LP format, quoting semi-illegal names makes them legal in the pure LP format as long as they are still shorter than 16 characters. Fully illegal names are still illegal in a pure LP file.

### 12.1.4 The strict LP format

The LP format is not a formal standard and different vendors have slightly different interpretations of the LP format. To make **MOSEK**'s definition of the LP format more compatible with the definitions of other vendors, use the parameter setting

- `MSK_IPAR_WRITE_LP_STRICT_FORMAT = MSK_ON`

This setting may lead to truncation of some names and hence to an invalid LP file. The simple solution to this problem is to use the parameter setting

- `MSK_IPAR_WRITE_GENERIC_NAMES = MSK_ON`

which will cause all names to be renamed systematically in the output file.

### 12.1.5 Formatting of an LP File

A few parameters control the visual formatting of LP files written by **MOSEK** in order to make it easier to read the files. These parameters are

- `MSK_IPAR_WRITE_LP_LINE_WIDTH`
- `MSK_IPAR_WRITE_LP_TERMS_PER_LINE`

The first parameter sets the maximum number of characters on a single line. The default value is 80 corresponding roughly to the width of a standard text document.

The second parameter sets the maximum number of terms per line; a term means a sign, a coefficient, and a name (for example + 42 elephants). The default value is 0, meaning that there is no maximum.

### Unnamed Constraints

Reading and writing an LP file with **MOSEK** may change it superficially. If an LP file contains unnamed constraints or objective these are given their generic names when the file is read (however unnamed constraints in **MOSEK** are written without names).

## 12.2 The MPS File Format

**MOSEK** supports the standard MPS format with some extensions. For a detailed description of the MPS format see the book by Nazareth [Naz87].

### 12.2.1 MPS File Structure

The version of the MPS format supported by **MOSEK** allows specification of an optimization problem of the form

$$\begin{aligned} l^c &\leq Ax + q(x) &\leq u^c, \\ l^x &\leq x &\leq u^x, \\ &x \in \mathcal{K}, \\ &x_{\mathcal{J}} \text{ integer}, \end{aligned} \tag{12.2}$$

where

- $x \in \mathbb{R}^n$  is the vector of decision variables.
- $A \in \mathbb{R}^{m \times n}$  is the constraint matrix.
- $l^c \in \mathbb{R}^m$  is the lower limit on the activity for the constraints.
- $u^c \in \mathbb{R}^m$  is the upper limit on the activity for the constraints.
- $l^x \in \mathbb{R}^n$  is the lower limit on the activity for the variables.
- $u^x \in \mathbb{R}^n$  is the upper limit on the activity for the variables.
- $q : \mathbb{R}^n \rightarrow \mathbb{R}$  is a vector of quadratic functions. Hence,

$$q_i(x) = \frac{1}{2} x^T Q^i x$$

where it is assumed that

$$Q^i = (Q^i)^T.$$

Please note the explicit  $\frac{1}{2}$  in the quadratic term and that  $Q^i$  is required to be symmetric.

- $\mathcal{K}$  is a convex cone.
- $\mathcal{J} \subseteq \{1, 2, \dots, n\}$  is an index set of the integer-constrained variables.

An MPS file with one row and one column can be illustrated like this:

```
*          1          2          3          4          5          6
*23456789012345678901234567890123456789012345678901234567890
NAME          [name]
OBJSENSE
[objsense]
OBJNAME
[objname]
ROWS
? [cname1]
COLUMNS
[vname1] [cname1] [value1] [vname3] [value2]
RHS
[name] [cname1] [value1] [cname2] [value2]
RANGES
[name] [cname1] [value1] [cname2] [value2]
QSECTION      [cname1]
[vname1] [vname2] [value1] [vname3] [value2]
QMATRIX
[vname1] [vname2] [value1]
QUADOBJ
[vname1] [vname2] [value1]
QCMATRIX      [cname1]
[vname1] [vname2] [value1]
BOUNDS
?? [name] [vname1] [value1]
CSECTION      [kname1] [value1] [ktype]
[vname1]
ENDATA
```

Here the names in capitals are keywords of the MPS format and names in brackets are custom defined names or values. A couple of notes on the structure:

- Fields: All items surrounded by brackets appear in *fields*. The fields named “valueN” are numerical values. Hence, they must have the format

```
[+|-]XXXXXXXX.XXXXXX[[e|E][+|-]XXX]
```

where

```
.. code-block:: text
```

```
X = [0|1|2|3|4|5|6|7|8|9].
```

- Sections: The MPS file consists of several sections where the names in capitals indicate the beginning of a new section. For example, COLUMNS denotes the beginning of the columns section.
- Comments: Lines starting with an \* are comment lines and are ignored by **MOSEK**.
- Keys: The question marks represent keys to be specified later.
- Extensions: The sections QSECTION and CSECTION are specific **MOSEK** extensions of the MPS format. The sections QMATRIX, QUADOBJ and QCMATRIX are included for sake of compatibility with other vendors extensions to the MPS format.

The standard MPS format is a fixed format, i.e. everything in the MPS file must be within certain fixed positions. **MOSEK** also supports a *free format*. See [Sec. 12.2.9](#) for details.

### Linear example lo1.mps

A concrete example of a MPS file is presented below:

```
* File: lo1.mps
NAME          lo1
OBJSENSE
    MAX
ROWS
N  obj
E  c1
G  c2
L  c3
COLUMNS
    x1      obj      3
    x1      c1       3
    x1      c2       2
    x2      obj      1
    x2      c1       1
    x2      c2       1
    x2      c3       2
    x3      obj      5
    x3      c1       2
    x3      c2       3
    x4      obj      1
    x4      c2       1
    x4      c3       3
RHS
    rhs     c1      30
    rhs     c2      15
    rhs     c3      25
RANGES
BOUNDS
UP bound    x2      10
ENDATA
```

Subsequently each individual section in the MPS format is discussed.

### Section NAME

In this section a name ([name]) is assigned to the problem.

**OBJSENSE (optional)**

This is an optional section that can be used to specify the sense of the objective function. The **OBJSENSE** section contains one line at most which can be one of the following

```
MIN
MINIMIZE
MAX
MAXIMIZE
```

It should be obvious what the implication is of each of these four lines.

**OBJNAME (optional)**

This is an optional section that can be used to specify the name of the row that is used as objective function. The **OBJNAME** section contains one line at most which has the form

```
objname
```

`objname` should be a valid row name.

**ROWS**

A record in the **ROWS** section has the form

```
? [cname1]
```

where the requirements for the fields are as follows:

| Field    | Starting Position | Max Width | required | Description     |
|----------|-------------------|-----------|----------|-----------------|
| ?        | 2                 | 1         | Yes      | Constraint key  |
| [cname1] | 5                 | 8         | Yes      | Constraint name |

Hence, in this section each constraint is assigned an unique name denoted by `[cname1]`. Please note that `[cname1]` starts in position 5 and the field can be at most 8 characters wide. An initial key `?` must be present to specify the type of the constraint. The key can have the values **E**, **G**, **L**, or **N** with the following interpretation:

| Constraint type | $l_i^c$   | $u_i^c$  |
|-----------------|-----------|----------|
| <b>E</b>        | finite    | $l_i^c$  |
| <b>G</b>        | finite    | $\infty$ |
| <b>L</b>        | $-\infty$ | finite   |
| <b>N</b>        | $-\infty$ | $\infty$ |

In the MPS format an objective vector is not specified explicitly, but one of the constraints having the key **N** will be used as the objective vector  $c$ . In general, if multiple **N** type constraints are specified, then the first will be used as the objective vector  $c$ .

**COLUMNS**

In this section the elements of  $A$  are specified using one or more records having the form:

```
[vname1] [cname1] [value1] [cname2] [value2]
```

where the requirements for each field are as follows:

| Field    | Starting Position | Max Width | required | Description     |
|----------|-------------------|-----------|----------|-----------------|
| [vname1] | 5                 | 8         | Yes      | Variable name   |
| [cname1] | 15                | 8         | Yes      | Constraint name |
| [value1] | 25                | 12        | Yes      | Numerical value |
| [cname2] | 40                | 8         | No       | Constraint name |
| [value2] | 50                | 12        | No       | Numerical value |

Hence, a record specifies one or two elements  $a_{ij}$  of  $A$  using the principle that [vname1] and [cname1] determines  $j$  and  $i$  respectively. Please note that [cname1] must be a constraint name specified in the ROWS section. Finally, [value1] denotes the numerical value of  $a_{ij}$ . Another optional element is specified by [cname2], and [value2] for the variable specified by [vname1]. Some important comments are:

- All elements belonging to one variable must be grouped together.
- Zero elements of  $A$  should not be specified.
- At least one element for each variable should be specified.

### RHS (optional)

A record in this section has the format

|        |          |          |          |          |
|--------|----------|----------|----------|----------|
| [name] | [cname1] | [value1] | [cname2] | [value2] |
|--------|----------|----------|----------|----------|

where the requirements for each field are as follows:

| Field    | Starting Position | Max Width | required | Description            |
|----------|-------------------|-----------|----------|------------------------|
| [name]   | 5                 | 8         | Yes      | Name of the RHS vector |
| [cname1] | 15                | 8         | Yes      | Constraint name        |
| [value1] | 25                | 12        | Yes      | Numerical value        |
| [cname2] | 40                | 8         | No       | Constraint name        |
| [value2] | 50                | 12        | No       | Numerical value        |

The interpretation of a record is that [name] is the name of the RHS vector to be specified. In general, several vectors can be specified. [cname1] denotes a constraint name previously specified in the ROWS section. Now, assume that this name has been assigned to the  $i$  th constraint and  $v_1$  denotes the value specified by [value1], then the interpretation of  $v_1$  is:

| Constraint | $l_i^c$ | $u_i^c$ |
|------------|---------|---------|
| type       |         |         |
| E          | $v_1$   | $v_1$   |
| G          | $v_1$   |         |
| L          |         | $v_1$   |
| N          |         |         |

An optional second element is specified by [cname2] and [value2] and is interpreted in the same way. Please note that it is not necessary to specify zero elements, because elements are assumed to be zero.

### RANGES (optional)

A record in this section has the form

|        |          |          |          |          |
|--------|----------|----------|----------|----------|
| [name] | [cname1] | [value1] | [cname2] | [value2] |
|--------|----------|----------|----------|----------|

where the requirements for each fields are as follows:

| Field    | Starting Position | Max Width | required | Description              |
|----------|-------------------|-----------|----------|--------------------------|
| [name]   | 5                 | 8         | Yes      | Name of the RANGE vector |
| [cname1] | 15                | 8         | Yes      | Constraint name          |
| [value1] | 25                | 12        | Yes      | Numerical value          |
| [cname2] | 40                | 8         | No       | Constraint name          |
| [value2] | 50                | 12        | No       | Numerical value          |

The records in this section are used to modify the bound vectors for the constraints, i.e. the values in  $l^c$  and  $u^c$ . A record has the following interpretation: [name] is the name of the RANGE vector and [cname1] is a valid constraint name. Assume that [cname1] is assigned to the  $i$  th constraint and let  $v_1$  be the value specified by [value1], then a record has the interpretation:

| Constraint type | Sign of $v_1$ | $l_i^c$         | $u_i^c$       |
|-----------------|---------------|-----------------|---------------|
| E               | —             | $u_i^c + v_1$   |               |
| E               | +             |                 | $l_i^c + v_1$ |
| G               | — or +        | $l_i^c +  v_1 $ |               |
| L               | — or +        | $u_i^c -  v_1 $ |               |
| N               |               |                 |               |

### QSECTION (optional)

Within the QSECTION the label [cname1] must be a constraint name previously specified in the ROWS section. The label [cname1] denotes the constraint to which the quadratic term belongs. A record in the QSECTION has the form

|          |          |          |          |          |
|----------|----------|----------|----------|----------|
| [vname1] | [vname2] | [value1] | [vname3] | [value2] |
|----------|----------|----------|----------|----------|

where the requirements for each field are:

| Field    | Starting Position | Max Width | required | Description     |
|----------|-------------------|-----------|----------|-----------------|
| [vname1] | 5                 | 8         | Yes      | Variable name   |
| [vname2] | 15                | 8         | Yes      | Variable name   |
| [value1] | 25                | 12        | Yes      | Numerical value |
| [vname3] | 40                | 8         | No       | Variable name   |
| [value2] | 50                | 12        | No       | Numerical value |

A record specifies one or two elements in the lower triangular part of the  $Q^i$  matrix where [cname1] specifies the  $i$ . Hence, if the names [vname1] and [vname2] have been assigned to the  $k$  th and  $j$  th variable, then  $Q_{kj}^i$  is assigned the value given by [value1]. An optional second element is specified in the same way by the fields [vname1], [vname3], and [value2].

The example

$$\begin{aligned}
 &\text{minimize} && -x_2 + \frac{1}{2}(2x_1^2 - 2x_1x_3 + 0.2x_2^2 + 2x_3^2) \\
 &\text{subject to} && x_1 + x_2 + x_3 \geq 1, \\
 &&& x \geq 0
 \end{aligned}$$

has the following MPS file representation

```

* File: qo1.mps
NAME          qo1
ROWS
N  obj
G  c1
COLUMNS

```

```

x1      c1      1.0
x2      obj     -1.0
x2      c1      1.0
x3      c1      1.0
RHS
rhs     c1      1.0
QSECTION      obj
x1      x1      2.0
x1      x3     -1.0
x2      x2      0.2
x3      x3      2.0
ENDATA

```

Regarding the QSECTIONs please note that:

- Only one QSECTION is allowed for each constraint.
- The QSECTIONs can appear in an arbitrary order after the COLUMNS section.
- All variable names occurring in the QSECTION must already be specified in the COLUMNS section.
- All entries specified in a QSECTION are assumed to belong to the lower triangular part of the quadratic term of  $Q$ .

#### QMATRIX/QUADOBJ (optional)

The QMATRIX and QUADOBJ sections allow to define the quadratic term of the objective function. They differ in how the quadratic term of the objective function is stored:

- QMATRIX It stores all the nonzeros coefficients, without taking advantage of the symmetry of the  $Q$  matrix.
- QUADOBJ It only store the upper diagonal nonzero elements of the  $Q$  matrix.

A record in both sections has the form:

```
[vname1] [vname2] [value1]
```

where the requirements for each field are:

| Field    | Starting Position | Max Width | required | Description     |
|----------|-------------------|-----------|----------|-----------------|
| [vname1] | 5                 | 8         | Yes      | Variable name   |
| [vname2] | 15                | 8         | Yes      | Variable name   |
| [value1] | 25                | 12        | Yes      | Numerical value |

A record specifies one elements of the  $Q$  matrix in the objective function. Hence, if the names [vname1] and [vname2] have been assigned to the  $k$ th and  $j$ th variable, then  $Q_{kj}$  is assigned the value given by [value1]. Note that a line must appear for each off-diagonal coefficient if using a QMATRIX section, while only one entry is required in a QUADOBJ section. The quadratic part of the objective function will be evaluated as  $1/2x^T Qx$ .

The example

$$\begin{aligned}
 &\text{minimize} && -x_2 + \frac{1}{2}(2x_1^2 - 2x_1x_3 + 0.2x_2^2 + 2x_3^2) \\
 &\text{subject to} && x_1 + x_2 + x_3 \geq 1, \\
 &&& x \geq 0
 \end{aligned}$$

has the following MPS file representation using QMATRIX

```

* File: qo1_matrix.mps
NAME      qo1_qmatrix
ROWS

```

```

N  obj
G  c1
COLUMNS
    x1      c1      1.0
    x2      obj     -1.0
    x2      c1      1.0
    x3      c1      1.0
RHS
    rhs      c1      1.0
QMATRIX
    x1      x1      2.0
    x1      x3     -1.0
    x3      x1     -1.0
    x2      x2      0.2
    x3      x3      2.0
ENDATA

```

or the following using QUADOBJ

```

* File: qo1_quadobj.mps
NAME          qo1_quadobj
ROWS
  N  obj
  G  c1
COLUMNS
    x1      c1      1.0
    x2      obj     -1.0
    x2      c1      1.0
    x3      c1      1.0
RHS
    rhs      c1      1.0
QUADOBJ
    x1      x1      2.0
    x1      x3     -1.0
    x2      x2      0.2
    x3      x3      2.0
ENDATA

```

Please also note that:

- A QMATRIX/QUADOBJ section can appear in an arbitrary order after the COLUMNS section.
- All variable names occurring in the QMATRIX/QUADOBJ section must already be specified in the COLUMNS section.

### 12.2.2 QCMATRIX (optional)

A QCMATRIX section allows to specify the quadratic part of a given constraints. Within the QCMATRIX the label [cname1] must be a constraint name previously specified in the ROWS section. The label [cname1] denotes the constraint to which the quadratic term belongs. A record in the QSECTION has the form

|          |          |          |
|----------|----------|----------|
| [vname1] | [vname2] | [value1] |
|----------|----------|----------|

where the requirements for each field are:

| Field    | Starting Position | Max Width | required | Description     |
|----------|-------------------|-----------|----------|-----------------|
| [vname1] | 5                 | 8         | Yes      | Variable name   |
| [vname2] | 15                | 8         | Yes      | Variable name   |
| [value1] | 25                | 12        | Yes      | Numerical value |

A record specifies an entry of the  $Q^i$  matrix where [cname1] specifies the  $i$ . Hence, if the names [vname1] and [vname2] have been assigned to the  $k$  th and  $j$  th variable, then  $Q_{kj}^i$  is assigned the value given by [value1]. Moreover, the quadratic term is represented as  $1/2x^T Qx$ .

The example

$$\begin{array}{ll} \text{minimize} & x_2 \\ \text{subject to} & x_1 + x_2 + x_3 \geq 1, \\ & \frac{1}{2}(-2x_1x_3 + 0.2x_2^2 + 2x_3^2) \leq 10, \\ & x \geq 0 \end{array}$$

has the following MPS file representation

```
* File: qo1.mps
NAME          qo1
ROWS
 N  obj
 G  c1
 L  q1
COLUMNS
  x1      c1      1.0
  x2      obj     -1.0
  x2      c1      1.0
  x3      c1      1.0
RHS
  rhs     c1      1.0
  rhs     q1     10.0
QCMATRIX   q1
  x1      x1      2.0
  x1      x3     -1.0
  x3      x1     -1.0
  x2      x2      0.2
  x3      x3      2.0
ENDATA
```

Regarding the QCMATRIXs please note that:

- Only one QCMATRIX is allowed for each constraint.
- The QCMATRIXs can appear in an arbitrary order after the COLUMNS section.
- All variable names occurring in the QSECTION must already be specified in the COLUMNS section.
- A QCMATRIX does not exploit the symmetry of  $Q$ : an off-diagonal entry  $(i, j)$  should appear twice.

### 12.2.3 BOUNDS (optional)

In the BOUNDS section changes to the default bounds vectors  $l^x$  and  $u^x$  are specified. The default bounds vectors are  $l^x = 0$  and  $u^x = \infty$ . Moreover, it is possible to specify several sets of bound vectors. A record in this section has the form

```
?? [name]    [vname1]    [value1]
```

where the requirements for each field are:

| Field    | Starting Position | Max Width | Required | Description               |
|----------|-------------------|-----------|----------|---------------------------|
| ??       | 2                 | 2         | Yes      | Bound key                 |
| [name]   | 5                 | 8         | Yes      | Name of the BOUNDS vector |
| [vname1] | 15                | 8         | Yes      | Variable name             |
| [value1] | 25                | 12        | No       | Numerical value           |

Hence, a record in the BOUNDS section has the following interpretation: **[name]** is the name of the bound vector and **[vname1]** is the name of the variable which bounds are modified by the record. **??** and **[value1]** are used to modify the bound vectors according to the following table:

| ?? | $l_j^x$             | $u_j^x$               | Made integer (added to $\mathcal{J}$ ) |
|----|---------------------|-----------------------|--|
| FR | $-\infty$           | $\infty$              | No                                     |
| FX | $v_1$               | $v_1$                 | No                                     |
| LO | $v_1$               | unchanged             | No                                     |
| MI | $-\infty$           | unchanged             | No                                     |
| PL | unchanged           | $\infty$              | No                                     |
| UP | unchanged           | $v_1$                 | No                                     |
| BV | 0                   | 1                     | Yes                                    |
| LI | $\lceil v_1 \rceil$ | unchanged             | Yes                                    |
| UI | unchanged           | $\lfloor v_1 \rfloor$ | Yes                                    |

$v\_1$  is the value specified by **[value1]**.

#### 12.2.4 CSECTION (optional)

The purpose of the CSECTION is to specify the constraint

$$x \in \mathcal{K}.$$

in (12.2). It is assumed that  $\mathcal{K}$  satisfies the following requirements. Let

$$x^t \in \mathbb{R}^{n^t}, \quad t = 1, \dots, k$$

be vectors comprised of parts of the decision variables  $x$  so that each decision variable is a member of exactly **one** vector  $x^t$ , for example

$$x^1 = \begin{bmatrix} x_1 \\ x_4 \\ x_7 \end{bmatrix} \quad \text{and} \quad x^2 = \begin{bmatrix} x_6 \\ x_5 \\ x_3 \\ x_2 \end{bmatrix}.$$

Next define

$$\mathcal{K} := \{x \in \mathbb{R}^n : x^t \in \mathcal{K}_t, \quad t = 1, \dots, k\}$$

where  $\mathcal{K}_t$  must have one of the following forms

- $\mathbb{R}$  set:

$$\mathcal{K}_t = \{x \in \mathbb{R}^{n^t}\}.$$

- Quadratic cone:

$$\mathcal{K}_t = \left\{ x \in \mathbb{R}^{n^t} : x_1 \geq \sqrt{\sum_{j=2}^{n^t} x_j^2} \right\}. \quad (12.3)$$

- Rotated quadratic cone:

$$\mathcal{K}_t = \left\{ x \in \mathbb{R}^{n^t} : 2x_1x_2 \geq \sum_{j=3}^{n^t} x_j^2, \quad x_1, x_2 \geq 0 \right\}. \quad (12.4)$$

In general, only quadratic and rotated quadratic cones are specified in the MPS file whereas membership of the  $\mathbb{R}$  set is not. If a variable is not a member of any other cone then it is assumed to be a member of an  $\mathbb{R}$  cone.

Next, let us study an example. Assume that the quadratic cone

$$x_4 \geq \sqrt{x_5^2 + x_8^2}$$

and the rotated quadratic cone

$$x_3 x_7 \geq x_1^2 + x_0^2, \quad x_3, x_7 \geq 0,$$

should be specified in the MPS file. One CSECTION is required for each cone and they are specified as follows:

```
*      1      2      3      4      5      6
*2345678901234567890123456789012345678901234567890
CSECTION      konea      0.0      QUAD
x4
x5
x8
CSECTION      koneb      0.0      RQUAD
x7
x3
x1
x0
```

This first CSECTION specifies the cone (12.3) which is given the name **konea**. This is a quadratic cone which is specified by the keyword **QUAD** in the CSECTION header. The 0.0 value in the CSECTION header is not used by the QUAD cone.

The second CSECTION specifies the rotated quadratic cone (12.4). Please note the keyword **RQUAD** in the CSECTION which is used to specify that the cone is a rotated quadratic cone instead of a quadratic cone. The 0.0 value in the CSECTION header is not used by the RQUAD cone.

In general, a CSECTION header has the format

|          |          |          |         |
|----------|----------|----------|---------|
| CSECTION | [kname1] | [value1] | [ktype] |
|----------|----------|----------|---------|

where the requirement for each field are as follows:

| Field    | Starting Position | Max Width | Required | Description       |
|----------|-------------------|-----------|----------|-------------------|
| [kname1] | 5                 | 8         | Yes      | Name of the cone  |
| [value1] | 15                | 12        | No       | Cone parameter    |
| [ktype]  | 25                |           | Yes      | Type of the cone. |

The possible cone type keys are:

| Cone type key | Members  | Interpretation.                     |
|---------------|----------|-------------------------------------|
| QUAD          | $\leq 1$ | Quadratic cone i.e. (12.3).         |
| RQUAD         | $\leq 2$ | Rotated quadratic cone i.e. (12.4). |

Please note that a quadratic cone must have at least one member whereas a rotated quadratic cone must have at least two members. A record in the CSECTION has the format

|          |
|----------|
| [vname1] |
|----------|

where the requirements for each field are

| Field    | Starting Position | Max Width | required | Description           |
|----------|-------------------|-----------|----------|-----------------------|
| [vname1] | 2                 | 8         | Yes      | A valid variable name |

The most important restriction with respect to the CSECTION is that a variable must occur in only one CSECTION.

### 12.2.5 ENDATA

This keyword denotes the end of the MPS file.

### 12.2.6 Integer Variables

Using special bound keys in the BOUNDS section it is possible to specify that some or all of the variables should be integer-constrained i.e. be members of  $\mathcal{J}$ . However, an alternative method is available.

This method is available only for backward compatibility and we recommend that it is not used. This method requires that markers are placed in the COLUMNS section as in the example:

|   |          |              |          |            |
|---|----------|--------------|----------|------------|
| COLUMNS                                   |          |              |          |            |
| x1  | obj      | -10.0        | c1       | 0.7        |
| x1  | c2       | 0.5          | c3       | 1.0        |
| x1  | c4       | 0.1          |          |            |
| * Start of integer-constrained variables. |          |              |          |            |
| MARK000                                   | 'MARKER' |              | 'INTORG' |            |
| x2  | obj      | -9.0         | c1       | 1.0        |
| x2  | c2       | 0.8333333333 | c3       | 0.66666667 |
| x2  | c4       | 0.25         |          |            |
| x3  | obj      | 1.0          | c6       | 2.0        |
| MARK001                                   | 'MARKER' |              | 'INTEND' |            |

- End of integer-constrained variables.

Please note that special marker lines are used to indicate the start and the end of the integer variables. Furthermore be aware of the following

- **IMPORTANT:** All variables between the markers are assigned a default lower bound of 0 and a default upper bound of 1. **This may not be what is intended.** If it is not intended, the correct bounds should be defined in the BOUNDS section of the MPS formatted file.
- **MOSEK** ignores field 1, i.e. MARK0001 and MARK001, however, other optimization systems require them.
- Field 2, i.e. **MARKER**, must be specified including the single quotes. This implies that no row can be assigned the name **MARKER**.
- Field 3 is ignored and should be left blank.
- Field 4, i.e. **INTORG** and **INTEND**, must be specified.
- It is possible to specify several such integer marker sections within the COLUMNS section.

### 12.2.7 General Limitations

- An MPS file should be an ASCII file.

### 12.2.8 Interpretation of the MPS Format

Several issues related to the MPS format are not well-defined by the industry standard. However, **MOSEK** uses the following interpretation:

- If a matrix element in the COLUMNS section is specified multiple times, then the multiple entries are added together.

- If a matrix element in a QSECTION section is specified multiple times, then the multiple entries are added together.

### 12.2.9 The Free MPS Format

MOSEK supports a free format variation of the MPS format. The free format is similar to the MPS file format but less restrictive, e.g. it allows longer names. However, it also presents two main limitations:

- A name must not contain any blanks.
- By default a line in the MPS file must not contain more than 1024 characters. However, by modifying the parameter `MSK_IPAR_READ_MPS_WIDTH` an arbitrary large line width will be accepted.

To use the free MPS format instead of the default MPS format the MOSEK parameter `MSK_IPAR_READ_MPS_FORMAT` should be changed.

## 12.3 The OPF Format

The *Optimization Problem Format (OPF)* is an alternative to LP and MPS files for specifying optimization problems. It is row-oriented, inspired by the CPLEX LP format.

Apart from containing objective, constraints, bounds etc. it may contain complete or partial solutions, comments and extra information relevant for solving the problem. It is designed to be easily read and modified by hand and to be forward compatible with possible future extensions.

### Intended use

The OPF file format is meant to replace several other files:

- The LP file format: Any problem that can be written as an LP file can be written as an OPF file too; furthermore it naturally accommodates ranged constraints and variables as well as arbitrary characters in names, fixed expressions in the objective, empty constraints, and conic constraints.
- Parameter files: It is possible to specify integer, double and string parameters along with the problem (or in a separate OPF file).
- Solution files: It is possible to store a full or a partial solution in an OPF file and later reload it.

### 12.3.1 The File Format

The format uses tags to structure data. A simple example with the basic sections may look like this:

```
[comment]
This is a comment. You may write almost anything here...
[/comment]

# This is a single-line comment.

[objective min 'myobj']
x + 3 y + x^2 + 3 y^2 + z + 1
[/objective]

[constraints]
[con 'con01'] 4 <= x + y  [/con]
[/constraints]

[bounds]
[b] -10 <= x,y <= 10  [/b]
```

```
[cone quad] x,y,z [/cone]
[/bounds]
```

A scope is opened by a tag of the form `[tag]` and closed by a tag of the form `[/tag]`. An opening tag may accept a list of unnamed and named arguments, for examples:

```
[tag value] tag with one unnamed argument [/tag]
[tag arg=value] tag with one named argument in quotes [/tag]
```

Unnamed arguments are identified by their order, while named arguments may appear in any order, but never before an unnamed argument. The `value` can be a quoted, single-quoted or double-quoted text string, i.e.

```
[tag 'value']      single-quoted value [/tag]
[tag arg='value']  single-quoted value [/tag]
[tag "value"]     double-quoted value [/tag]
[tag arg="value"] double-quoted value [/tag]
```

## Sections

The recognized tags are

`[comment]`

A comment section. This can contain *almost* any text: Between single quotes (') or double quotes (") any text may appear. Outside quotes the markup characters ([ and ]) must be prefixed by backslashes. Both single and double quotes may appear alone or inside a pair of quotes if it is prefixed by a backslash.

`[objective]`

The objective function: This accepts one or two parameters, where the first one (in the above example `min`) is either `min` or `max` (regardless of case) and defines the objective sense, and the second one (above `myobj`), if present, is the objective name. The section may contain linear and quadratic expressions. If several objectives are specified, all but the last are ignored.

`[constraints]`

This does not directly contain any data, but may contain the subsection `con` defining a linear constraint.

`[con]` defines a single constraint; if an argument is present (`[con NAME]`) this is used as the name of the constraint, otherwise it is given a null-name. The section contains a constraint definition written as linear and quadratic expressions with a lower bound, an upper bound, with both or with an equality. Examples:

```
[constraints]
[con 'con1'] 0 <= x + y      [/con]
[con 'con2'] 0 >= x + y      [/con]
[con 'con3'] 0 <= x + y <= 10 [/con]
[con 'con4']      x + y  = 10 [/con]
[/constraints]
```

Constraint names are unique. If a constraint is specified which has the same name as a previously defined constraint, the new constraint replaces the existing one.

### [bounds]

This does not directly contain any data, but may contain the subsections **b** (linear bounds on variables) and **cone** (quadratic cone).

[b]. Bound definition on one or several variables separated by comma (,). An upper or lower bound on a variable replaces any earlier defined bound on that variable. If only one bound (upper or lower) is given only this bound is replaced. This means that upper and lower bounds can be specified separately. So the OPF bound definition:

```
[b]  x,y >= -10  [/b]
[b]  x,y <= 10   [/b]
```

results in the bound  $-10 \leq x, y \leq 10$ .

[cone]. currently supports the *quadratic cone* and the *rotated quadratic cone*.

A conic constraint is defined as a set of variables which belong to a single unique cone.

- A quadratic cone of  $n$  variables  $x_1, \dots, x_n$  defines a constraint of the form

$$x_1^2 \geq \sum_{i=2}^n x_i^2, \quad x_1 \geq 0.$$

- A rotated quadratic cone of  $n$  variables  $x_1, \dots, x_n$  defines a constraint of the form

$$2x_1x_2 \geq \sum_{i=3}^n x_i^2, \quad x_1, x_2 \geq 0.$$

A [bounds]-section example:

```
[bounds]
[b]  0 <= x,y <= 10  [/b] # ranged bound
[b]  10 >= x,y >= 0  [/b] # ranged bound
[b]  0 <= x,y <= inf [/b] # using inf
[b]      x,y free    [/b] # free variables
# Let (x,y,z,w) belong to the cone K
[cone quad] x,y,z,w [/cone] # quadratic cone
[cone rquad] x,y,z,w [/cone] # rotated quadratic cone
[/bounds]
```

By default all variables are free.

### [variables]

This defines an ordering of variables as they should appear in the problem. This is simply a space-separated list of variable names. Optionally, an attribute can be added [variables disallow\_new\_variables] indicating that if any variable not listed here occurs later in the file it is an error.

### [integer]

This contains a space-separated list of variables and defines the constraint that the listed variables must be integer values.

### [hints]

This may contain only non-essential data; for example estimates of the number of variables, constraints and non-zeros. Placed before all other sections containing data this may reduce the time spent reading the file.

In the `hints` section, any subsection which is not recognized by **MOSEK** is simply ignored. In this section a hint in a subsection is defined as follows:

```
[hint ITEM] value [/hint]
```

where `ITEM` may be replaced by `numvar` (number of variables), `numcon` (number of linear/quadratic constraints), `numanz` (number of linear non-zeros in constraints) and `numqnz` (number of quadratic non-zeros in constraints).

### [solutions]

This section can contain a set of full or partial solutions to a problem. Each solution must be specified using a `[solution]`-section, i.e.

```
[solutions]
[solution]...[/solution] #solution 1
[solution]...[/solution] #solution 2
#other solutions....
[solution]...[/solution] #solution n
[/solutions]
```

Note that a `[solution]`-section must be always specified inside a `[solutions]`-section. The syntax of a `[solution]`-section is the following:

```
[solution SOLTYPE status=STATUS]...[/solution]
```

where `SOLTYPE` is one of the strings

- `interior`, a non-basic solution,
- `basic`, a basic solution,
- `integer`, an integer solution,

and `STATUS` is one of the strings

- `UNKNOWN`,
- `OPTIMAL`,
- `INTEGER_OPTIMAL`,
- `PRIM_FEAS`,
- `DUAL_FEAS`,
- `PRIM_AND_DUAL_FEAS`,
- `NEAR_OPTIMAL`,
- `NEAR_PRIM_FEAS`,
- `NEAR_DUAL_FEAS`,
- `NEAR_PRIM_AND_DUAL_FEAS`,
- `PRIM_INFEAS_CER`,
- `DUAL_INFEAS_CER`,
- `NEAR_PRIM_INFEAS_CER`,

- NEAR\_DUAL\_INFEAS\_CER,
- NEAR\_INTEGER\_OPTIMAL.

Most of these values are irrelevant for input solutions; when constructing a solution for simplex hot-start or an initial solution for a mixed integer problem the safe setting is UNKNOWN.

A [solution]-section contains [con] and [var] sections. Each [con] and [var] section defines solution information for a single variable or constraint, specified as list of KEYWORD/value pairs, in any order, written as

```
KEYWORD=value
```

Allowed keywords are as follows:

- **sk**. The status of the item, where the **value** is one of the following strings:
  - **LOW**, the item is on its lower bound.
  - **UPR**, the item is on its upper bound.
  - **FIX**, it is a fixed item.
  - **BAS**, the item is in the basis.
  - **SUPBAS**, the item is super basic.
  - **UNK**, the status is unknown.
  - **INF**, the item is outside its bounds (infeasible).
- **lvl** Defines the level of the item.
- **s1** Defines the level of the dual variable associated with its lower bound.
- **su** Defines the level of the dual variable associated with its upper bound.
- **sn** Defines the level of the variable associated with its cone.
- **y** Defines the level of the corresponding dual variable (for constraints only).

A [var] section should always contain the items **sk**, **lvl**, **s1** and **su**. Items **s1** and **su** are not required for **integer** solutions.

A [con] section should always contain **sk**, **lvl**, **s1**, **su** and **y**.

An example of a solution section

```
[solution basic status=UNKNOWN]
[var x0] sk=LOW    lvl=5.0    [/var]
[var x1] sk=UPR    lvl=10.0   [/var]
[var x2] sk=SUPBAS lvl=2.0    s1=1.5 su=0.0 [/var]

[con c0] sk=LOW    lvl=3.0 y=0.0 [/con]
[con c0] sk=UPR    lvl=0.0 y=5.0 [/con]
[/solution]
```

- **[vendor]** This contains solver/vendor specific data. It accepts one argument, which is a vendor ID – for **MOSEK** the ID is simply **mosek** – and the section contains the subsection **parameters** defining solver parameters. When reading a vendor section, any unknown vendor can be safely ignored. This is described later.

Comments using the # may appear anywhere in the file. Between the # and the following line-break any text may be written, including markup characters.

## Numbers

Numbers, when used for parameter values or coefficients, are written in the usual way by the `printf` function. That is, they may be prefixed by a sign (+ or -) and may contain an integer part, decimal part and an exponent. The decimal point is always `.` (a dot). Some examples are

```
1
1.0
.0
1.
1e10
1e+10
1e-10
```

Some *invalid* examples are

```
e10    # invalid, must contain either integer or decimal part
.       # invalid
.e10   # invalid
```

More formally, the following standard regular expression describes numbers as used:

```
[+|-]?([0-9]+[.][0-9]*|.[0-9]+)([eE][+|-]?[0-9]+)?
```

## Names

Variable names, constraint names and objective name may contain arbitrary characters, which in some cases must be enclosed by quotes (single or double) that in turn must be preceded by a backslash. Unquoted names must begin with a letter (`a-z` or `A-Z`) and contain only the following characters: the letters `a-z` and `A-Z`, the digits `0-9`, braces (`{` and `}`) and underscore (`_`).

Some examples of legal names:

```
an_unquoted_name
another_name{123}
'single quoted name'
"double quoted name"
"name with \"quote\" in it"
"name with []s in it"
```

### 12.3.2 Parameters Section

In the `vendor` section solver parameters are defined inside the `parameters` subsection. Each parameter is written as

```
[p PARAMETER_NAME] value [/p]
```

where `PARAMETER_NAME` is replaced by a **MOSEK** parameter name, usually of the form `MSK_IPAR_...`, `MSK_DPAR_...` or `MSK_SPAR_...`, and the `value` is replaced by the value of that parameter; both integer values and named values may be used. Some simple examples are

```
[vendor mosek]
[parameters]
[p MSK_IPAR_OPF_MAX_TERMS_PER_LINE] 10      [/p]
[p MSK_IPAR_OPF_WRITE_PARAMETERS]    MSK_ON [/p]
[p MSK_DPAR_DATA_TOL_BOUND_INF]      1.0e18 [/p]
[/parameters]
[/vendor]
```

### 12.3.3 Writing OPF Files from MOSEK

To write an OPF file set the parameter `MSK_IPAR_WRITE_DATA_FORMAT` to `MSK_DATA_FORMAT_OP` as this ensures that OPF format is used.

Then modify the following parameters to define what the file should contain:

|  |   |
|--|---|
| <code>MSK_IPAR_OPF_WRITE_SOL_BAS</code>    | Include basic solution, if defined.   |
| <code>MSK_IPAR_OPF_WRITE_SOL_ITG</code>    | Include integer solution, if defined.   |
| <code>MSK_IPAR_OPF_WRITE_SOL_ITR</code>    | Include interior solution, if defined.  |
| <code>MSK_IPAR_OPF_WRITE_SOLUTIONS</code>  | Include solutions if they are defined. If this is off, no solutions are included. |
| <code>MSK_IPAR_OPF_WRITE_HEADER</code>     | Include a small header with comments.   |
| <code>MSK_IPAR_OPF_WRITE_PROBLEM</code>    | Include the problem itself — objective, constraints and bounds.                   |
| <code>MSK_IPAR_OPF_WRITE_PARAMETERS</code> | Include all parameter settings.   |
| <code>MSK_IPAR_OPF_WRITE_HINTS</code>      | Include hints about the size of the problem.                                      |

### 12.3.4 Examples

This section contains a set of small examples written in OPF and describing how to formulate linear, quadratic and conic problems.

#### Linear Example `lo1.opf`

Consider the example:

$$\begin{array}{ll}
 \text{maximize} & 3x_0 + 1x_1 + 5x_2 + 1x_3 \\
 \text{subject to} & 3x_0 + 1x_1 + 2x_2 = 30, \\
 & 2x_0 + 1x_1 + 3x_2 + 1x_3 \geq 15, \\
 & 2x_1 + 3x_3 \leq 25,
 \end{array}$$

having the bounds

$$\begin{array}{ll}
 0 \leq x_0 \leq \infty, \\
 0 \leq x_1 \leq 10, \\
 0 \leq x_2 \leq \infty, \\
 0 \leq x_3 \leq \infty.
 \end{array}$$

In the OPF format the example is displayed as shown in [Listing 12.1](#).

Listing 12.1: Example of an OPF file for a linear problem.

```

[comment]
  The lo1 example in OPF format
[/comment]

[hints]
  [hint NUMVAR] 4 [/hint]
  [hint NUMCON] 3 [/hint]
  [hint NUMANZ] 9 [/hint]
[/hints]

[variables disallow_new_variables]
  x1 x2 x3 x4
[/variables]

[objective maximize 'obj']
  3 x1 + x2 + 5 x3 + x4
[/objective]
```

```
[constraints]
[con 'c1'] 3 x1 +   x2 + 2 x3           = 30 [/con]
[con 'c2'] 2 x1 +   x2 + 3 x3 +   x4 >= 15 [/con]
[con 'c3']           2 x2           + 3 x4 <= 25 [/con]
[/constraints]

[bounds]
[b] 0 <= * [/b]
[b] 0 <= x2 <= 10 [/b]
[/bounds]
```

### Quadratic Example qo1.opf

An example of a quadratic optimization problem is

$$\begin{array}{ll}\text{minimize} & x_1^2 + 0.1x_2^2 + x_3^2 - x_1x_3 - x_2 \\ \text{subject to} & 1 \leq x_1 + x_2 + x_3, \\ & x \geq 0.\end{array}$$

This can be formulated in **opf** as shown below.

Listing 12.2: Example of an OPF file for a quadratic problem.

```
[comment]
  The qo1 example in OPF format
[/comment]

[hints]
[hint NUMVAR] 3 [/hint]
[hint NUMCON] 1 [/hint]
[hint NUMANZ] 3 [/hint]
[hint NUMQNZ] 4 [/hint]
[/hints]

[variables disallow_new_variables]
  x1 x2 x3
[/variables]

[objective minimize 'obj']
  # The quadratic terms are often written with a factor of 1/2 as here,
  # but this is not required.

  - x2 + 0.5 ( 2.0 x1 ^ 2 - 2.0 x3 * x1 + 0.2 x2 ^ 2 + 2.0 x3 ^ 2 )
[/objective]

[constraints]
[con 'c1'] 1.0 <= x1 + x2 + x3 [/con]
[/constraints]

[bounds]
[b] 0 <= * [/b]
[/bounds]
```

**Conic Quadratic Example** `cqo1.opf`

Consider the example:

$$\begin{aligned}
 &\text{minimize} && x_3 + x_4 + x_5 \\
 &\text{subject to} && x_0 + x_1 + 2x_2 = 1, \\
 & && x_0, x_1, x_2 \geq 0, \\
 & && x_3 \geq \sqrt{x_0^2 + x_1^2}, \\
 & && 2x_4x_5 \geq x_2^2.
 \end{aligned}$$

Please note that the type of the cones is defined by the parameter to `[cone ...]`; the content of the `cone`-section is the names of variables that belong to the cone. The resulting OPF file is in [Listing 12.3](#).

Listing 12.3: Example of an OPF file for a conic quadratic problem.

```

[comment]
  The cqo1 example in OPF format.
[/comment]

[hints]
  [hint NUMVAR] 6 [/hint]
  [hint NUMCON] 1 [/hint]
  [hint NUMANZ] 3 [/hint]
[/hints]

[variables disallow_new_variables]
  x1 x2 x3 x4 x5 x6
[/variables]

[objective minimize 'obj']
  x4 + x5 + x6
[/objective]

[constraints]
  [con 'c1'] x1 + x2 + 2e+00 x3 = 1e+00 [/con]
[/constraints]

[bounds]
  # We let all variables default to the positive orthant
  [b] 0 <= * [/b]

  # ...and change those that differ from the default
  [b] x4,x5,x6 free [/b]

  # Define quadratic cone: x4 >= sqrt( x1^2 + x2^2 )
  [cone quad 'k1'] x4, x1, x2 [/cone]

  # Define rotated quadratic cone: 2 x5 x6 >= x3^2
  [cone rquad 'k2'] x5, x6, x3 [/cone]
[/bounds]

```

**Mixed Integer Example** `mil01.opf`

Consider the mixed integer problem:

$$\begin{aligned}
 &\text{maximize} && x_0 + 0.64x_1 \\
 &\text{subject to} && 50x_0 + 31x_1 \leq 250, \\
 & && 3x_0 - 2x_1 \geq -4, \\
 & && x_0, x_1 \geq 0 \quad \text{and integer}
 \end{aligned}$$

This can be implemented in OPF with the file in [Listing 12.4](#).

Listing 12.4: Example of an OPF file for a mixed-integer linear problem.

```

[comment]
  The milo1 example in OPF format
[/comment]

[hints]
  [hint NUMVAR] 2 [/hint]
  [hint NUMCON] 2 [/hint]
  [hint NUMANZ] 4 [/hint]
[/hints]

[variables disallow_new_variables]
  x1 x2
[/variables]

[objective maximize 'obj']
  x1 + 6.4e-1 x2
[/objective]

[constraints]
  [con 'c1'] 5e+1 x1 + 3.1e+1 x2 <= 2.5e+2 [/con]
  [con 'c2'] -4 <= 3 x1 - 2 x2 [/con]
[/constraints]

[bounds]
  [b] 0 <= * [/b]
[/bounds]

[integer]
  x1 x2
[/integer]

```

## 12.4 The CBF Format

This document constitutes the technical reference manual of the *Conic Benchmark Format* with file extension: `.cbf` or `.CBF`. It unifies linear, second-order cone (also known as conic quadratic) and semidefinite optimization with mixed-integer variables. The format has been designed with benchmark libraries in mind, and therefore focuses on compact and easily parsable representations. The problem structure is separated from the problem data, and the format moreover facilitates benchmarking of hotstart capability through sequences of changes.

### 12.4.1 How Instances Are Specified

This section defines the spectrum of conic optimization problems that can be formulated in terms of the keywords of the CBF format.

In the CBF format, conic optimization problems are considered in the following form:

$$\begin{aligned}
 & \min / \max && g^{obj} \\
 \text{s.t.} &&& g_i \in \mathcal{K}_i, \quad i \in \mathcal{I}, \\
 &&& G_i \in \mathcal{K}_i, \quad i \in \mathcal{I}^{PSD}, \\
 &&& x_j \in \mathcal{K}_j, \quad j \in \mathcal{J}, \\
 &&& \overline{X}_j \in \mathcal{K}_j, \quad j \in \mathcal{J}^{PSD}.
 \end{aligned} \tag{12.5}$$

- **Variables** are either scalar variables,  $x_j$  for  $j \in \mathcal{J}$ , or variables,  $\overline{X}_j$  for  $j \in \mathcal{J}^{PSD}$ . Scalar variables can also be declared as integer.

- **Constraints** are affine expressions of the variables, either scalar-valued  $g_i$  for  $i \in \mathcal{I}$ , or matrix-valued  $G_i$  for  $i \in \mathcal{I}^{PSD}$

$$g_i = \sum_{j \in \mathcal{J}^{PSD}} \langle F_{ij}, X_j \rangle + \sum_{j \in \mathcal{J}} a_{ij} x_j + b_i,$$

$$G_i = \sum_{j \in \mathcal{J}} x_j H_{ij} + D_i.$$

- The **objective function** is a scalar-valued affine expression of the variables, either to be minimized or maximized. We refer to this expression as  $g^{obj}$

$$g^{obj} = \sum_{j \in \mathcal{J}^{PSD}} \langle F_j^{obj}, X_j \rangle + \sum_{j \in \mathcal{J}} a_j^{obj} x_j + b^{obj}.$$

CBF format can represent the following cones  $\mathcal{K}$ :

- **Free domain** - A cone in the linear family defined by

$$\{x \in \mathbb{R}^n\}, \text{ for } n \geq 1.$$

- **Positive orthant** - A cone in the linear family defined by

$$\{x \in \mathbb{R}^n \mid x_j \geq 0 \text{ for } j = 1, \dots, n\}, \text{ for } n \geq 1.$$

- **Negative orthant** - A cone in the linear family defined by

$$\{x \in \mathbb{R}^n \mid x_j \leq 0 \text{ for } j = 1, \dots, n\}, \text{ for } n \geq 1.$$

- **Fixpoint zero** - A cone in the linear family defined by

$$\{x \in \mathbb{R}^n \mid x_j = 0 \text{ for } j = 1, \dots, n\}, \text{ for } n \geq 1.$$

- **Quadratic cone** - A cone in the second-order cone family defined by

$$\left\{ \begin{pmatrix} p \\ x \end{pmatrix} \in \mathbb{R} \times \mathbb{R}^{n-1}, p^2 \geq x^T x, p \geq 0 \right\}, \text{ for } n \geq 2.$$

- **Rotated quadratic cone** - A cone in the second-order cone family defined by

$$\left\{ \begin{pmatrix} p \\ q \\ x \end{pmatrix} \in \mathbb{R} \times \mathbb{R} \times \mathbb{R}^{n-2}, 2pq \geq x^T x, p \geq 0, q \geq 0 \right\}, \text{ for } n \geq 3.$$

## 12.4.2 The Structure of CBF Files

This section defines how information is written in the CBF format, without being specific about the type of information being communicated.

All information items belong to exactly one of the three groups of information. These information groups, and the order they must appear in, are:

1. File format.
2. Problem structure.
3. Problem data.

The first group, file format, provides information on how to interpret the file. The second group, problem structure, provides the information needed to deduce the type and size of the problem instance. Finally, the third group, problem data, specifies the coefficients and constants of the problem instance.

### Information items

The format is composed as a list of information items. The first line of an information item is the **KEYWORD**, revealing the type of information provided. The second line - of some keywords only - is the **HEADER**, typically revealing the size of information that follows. The remaining lines are the **BODY** holding the actual information to be specified.

|         |
|---------|
| KEYWORD |
| BODY    |
| KEYWORD |
| HEADER  |
| BODY    |

The **KEYWORD** determines how each line in the **HEADER** and **BODY** is structured. Moreover, the number of lines in the **BODY** follows either from the **KEYWORD**, the **HEADER**, or from another information item required to precede it.

### Embedded hotstart-sequences

A sequence of problem instances, based on the same problem structure, is within a single file. This is facilitated via the **CHANGE** within the problem data information group, as a separator between the information items of each instance. The information items following a **CHANGE** keyword are appending to, or changing (e.g., setting coefficients back to their default value of zero), the problem data of the preceding instance.

The sequence is intended for benchmarking of hotstart capability, where the solvers can reuse their internal state and solution (subject to the achieved accuracy) as warmpoint for the succeeding instance. Whenever this feature is unsupported or undesired, the keyword **CHANGE** should be interpreted as the end of file.

### File encoding and line width restrictions

The format is based on the US-ASCII printable character set with two extensions as listed below. Note, by definition, that none of these extensions can be misinterpreted as printable US-ASCII characters:

- A line feed marks the end of a line, carriage returns are ignored.
- Comment-lines may contain unicode characters in UTF-8 encoding.

The line width is restricted to 512 bytes, with 3 bytes reserved for the potential carriage return, line feed and null-terminator.

Integers and floating point numbers must follow the ISO C decimal string representation in the standard C locale. The format does not impose restrictions on the magnitude of, or number of significant digits in numeric data, but the use of 64-bit integers and 64-bit IEEE 754 floating point numbers should be sufficient to avoid loss of precision.

### Comment-line and whitespace rules

The format allows single-line comments respecting the following rule:

- Lines having first byte equal to '#' (US-ASCII 35) are comments, and should be ignored. Comments are only allowed between information items.

Given that a line is not a comment-line, whitespace characters should be handled according to the following rules:

- Leading and trailing whitespace characters should be ignored.
  - The separator between multiple pieces of information on one line, is either one or more whitespace characters.
- Lines containing only whitespace characters are empty, and should be ignored. Empty lines are only allowed between information items.

## 12.4.3 Problem Specification

### The problem structure

The problem structure defines the objective sense, whether it is minimization and maximization. It also defines the index sets,  $\mathcal{J}$ ,  $\mathcal{J}^{PSD}$ ,  $\mathcal{I}$  and  $\mathcal{I}^{PSD}$ , which are all numbered from zero,  $\{0, 1, \dots\}$ , and empty until explicitly constructed.

- **Scalar variables** are constructed in vectors restricted to a conic domain, such as  $(x_0, x_1) \in \mathbb{R}_+^2$ ,  $(x_2, x_3, x_4) \in \mathcal{Q}^3$ , etc. In terms of the Cartesian product, this generalizes to

$$x \in \mathcal{K}_1^{n_1} \times \mathcal{K}_2^{n_2} \times \dots \times \mathcal{K}_k^{n_k}$$

which in the CBF format becomes:

```
VAR
n k
K1 n1
K2 n2
...
Kk nk
```

where  $\sum_i n_i = n$  is the total number of scalar variables. The list of supported cones is found in [Table 12.3](#). Integrality of scalar variables can be specified afterwards.

- **PSD variables** are constructed one-by-one. That is,  $X_j \succeq \mathbf{0}^{n_j \times n_j}$  for  $j \in \mathcal{J}^{PSD}$ , constructs a matrix-valued variable of size  $n_j \times n_j$  restricted to be symmetric positive semidefinite. In the CBF format, this list of constructions becomes:

```
PSDVAR
N
n1
n2
...
nN
```

where  $N$  is the total number of PSD variables.

- **Scalar constraints** are constructed in vectors restricted to a conic domain, such as  $(g_0, g_1) \in \mathbb{R}_+^2$ ,  $(g_2, g_3, g_4) \in \mathcal{Q}^3$ , etc. In terms of the Cartesian product, this generalizes to

$$g \in \mathcal{K}_1^{m_1} \times \mathcal{K}_2^{m_2} \times \dots \times \mathcal{K}_k^{m_k}$$

which in the CBF format becomes:

```

CON
m k
K1 m1
K2 m2
. .
Kk mk

```

where  $\sum_i m_i = m$  is the total number of scalar constraints. The list of supported cones is found in Table 12.3.

- **PSD constraints** are constructed one-by-one. That is,  $G_i \succeq \mathbf{0}^{m_i \times m_i}$  for  $i \in \mathcal{I}^{PSD}$ , constructs a matrix-valued affine expressions of size  $m_i \times m_i$  restricted to be symmetric positive semidefinite. In the CBF format, this list of constructions becomes

```

PSDCON
M
m1
m2
. .
mM

```

where  $M$  is the total number of PSD constraints.

With the objective sense, variables (with integer indications) and constraints, the definitions of the many affine expressions follow in problem data.

### Problem data

The problem data defines the coefficients and constants of the affine expressions of the problem instance. These are considered zero until explicitly defined, implying that instances with no keywords from this information group are, in fact, valid. Duplicating or conflicting information is a failure to comply with the standard. Consequently, two coefficients written to the same position in a matrix (or to transposed positions in a symmetric matrix) is an error.

The affine expressions of the objective,  $g^{obj}$ , of the scalar constraints,  $g_i$ , and of the PSD constraints,  $G_i$ , are defined separately. The following notation uses the standard trace inner product for matrices,  $\langle X, Y \rangle = \sum_{i,j} X_{ij} Y_{ij}$ .

- The affine expression of the objective is defined as

$$g^{obj} = \sum_{j \in \mathcal{J}^{PSD}} \langle F_j^{obj}, X_j \rangle + \sum_{j \in \mathcal{J}} a_j^{obj} x_j + b^{obj},$$

in terms of the symmetric matrices,  $F_j^{obj}$ , and scalars,  $a_j^{obj}$  and  $b^{obj}$ .

- The affine expressions of the scalar constraints are defined, for  $i \in \mathcal{I}$ , as

$$g_i = \sum_{j \in \mathcal{J}^{PSD}} \langle F_{ij}, X_j \rangle + \sum_{j \in \mathcal{J}} a_{ij} x_j + b_i,$$

in terms of the symmetric matrices,  $F_{ij}$ , and scalars,  $a_{ij}$  and  $b_i$ .

- The affine expressions of the PSD constraints are defined, for  $i \in \mathcal{I}^{PSD}$ , as

$$G_i = \sum_{j \in \mathcal{J}} x_j H_{ij} + D_i,$$

in terms of the symmetric matrices,  $H_{ij}$  and  $D_i$ .

## List of cones

The format uses an explicit syntax for symmetric positive semidefinite cones as shown above. For scalar variables and constraints, constructed in vectors, the supported conic domains and their minimum sizes are given as follows.

Table 12.3: Cones available in the CBF format

| Name                   | CBF keyword | Cone family  |
|------------------------|-------------|--------------|
| Free domain            | F           | linear       |
| Positive orthant       | L+          | linear       |
| Negative orthant       | L-          | linear       |
| Fixpoint zero          | L=          | linear       |
| Quadratic cone         | Q           | second-order |
| Rotated quadratic cone | QR          | second-order |

### 12.4.4 File Format Keywords

#### VER

*Description:* The version of the Conic Benchmark Format used to write the file.

HEADER: None

BODY: One line formatted as:

|     |
|-----|
| INT |
|-----|

This is the version number.

Must appear exactly once in a file, as the first keyword.

#### OBJSENSE

*Description:* Define the objective sense.

HEADER: None

BODY: One line formatted as:

|     |
|-----|
| STR |
|-----|

having MIN indicates minimize, and MAX indicates maximize. Capital letters are required.

Must appear exactly once in a file.

#### PSDVAR

*Description:* Construct the PSD variables.

HEADER: One line formatted as:

|     |
|-----|
| INT |
|-----|

This is the number of PSD variables in the problem.

BODY: A list of lines formatted as:

|     |
|-----|
| INT |
|-----|

This indicates the number of rows (equal to the number of columns) in the matrix-valued PSD variable. The number of lines should match the number stated in the header.

## VAR

*Description:* Construct the scalar variables.

**HEADER:** One line formatted as:

|         |
|---------|
| INT INT |
|---------|

This is the number of scalar variables, followed by the number of conic domains they are restricted to.

**BODY:** A list of lines formatted as:

|         |
|---------|
| STR INT |
|---------|

This indicates the cone name (see [Table 12.3](#)), and the number of scalar variables restricted to this cone. These numbers should add up to the number of scalar variables stated first in the header. The number of lines should match the second number stated in the header.

## INT

*Description:* Declare integer requirements on a selected subset of scalar variables.

**HEADER:** one line formatted as:

|     |
|-----|
| INT |
|-----|

This is the number of integer scalar variables in the problem.

**BODY:** a list of lines formatted as:

|     |
|-----|
| INT |
|-----|

This indicates the scalar variable index  $j \in \mathcal{J}$ . The number of lines should match the number stated in the header.

Can only be used after the keyword **VAR**.

## PSDCON

*Description:* Construct the PSD constraints.

**HEADER:** One line formatted as:

|     |
|-----|
| INT |
|-----|

This is the number of PSD constraints in the problem.

**BODY:** A list of lines formatted as:

|     |
|-----|
| INT |
|-----|

This indicates the number of rows (equal to the number of columns) in the matrix-valued affine expression of the PSD constraint. The number of lines should match the number stated in the header.

Can only be used after these keywords: **PSDVAR**, **VAR**.

## CON

*Description:* Construct the scalar constraints.

**HEADER:** One line formatted as:

|         |
|---------|
| INT INT |
|---------|

This is the number of scalar constraints, followed by the number of conic domains they restrict to.

**BODY:** A list of lines formatted as:

|         |
|---------|
| STR INT |
|---------|

This indicates the cone name (see [Table 12.3](#)), and the number of affine expressions restricted to this cone. These numbers should add up to the number of scalar constraints stated first in the header. The number of lines should match the second number stated in the header.

Can only be used after these keywords: PSDVAR, VAR

## OBJFCOORD

*Description:* Input sparse coordinates (quadruplets) to define the symmetric matrices  $F_j^{obj}$ , as used in the objective.

**HEADER:** One line formatted as:

|     |
|-----|
| INT |
|-----|

This is the number of coordinates to be specified.

**BODY:** A list of lines formatted as:

|                  |
|------------------|
| INT INT INT REAL |
|------------------|

This indicates the PSD variable index  $j \in \mathcal{J}^{PSD}$ , the row index, the column index and the coefficient value. The number of lines should match the number stated in the header.

## OBJACOORD

*Description:* Input sparse coordinates (pairs) to define the scalars,  $a_j^{obj}$ , as used in the objective.

**HEADER:** One line formatted as:

|     |
|-----|
| INT |
|-----|

This is the number of coordinates to be specified.

**BODY:** A list of lines formatted as:

|          |
|----------|
| INT REAL |
|----------|

This indicates the scalar variable index  $j \in \mathcal{J}$  and the coefficient value. The number of lines should match the number stated in the header.

## OBJBCOORD

*Description:* Input the scalar,  $b^{obj}$ , as used in the objective.

**HEADER:** None.

**BODY:** One line formatted as:

|      |
|------|
| REAL |
|------|

This indicates the coefficient value.

## FCOORD

*Description:* Input sparse coordinates (quintuplets) to define the symmetric matrices,  $F_{ij}$ , as used in the scalar constraints.

HEADER: One line formatted as:

|     |
|-----|
| INT |
|-----|

This is the number of coordinates to be specified.

BODY: A list of lines formatted as:

|                      |
|----------------------|
| INT INT INT INT REAL |
|----------------------|

This indicates the scalar constraint index  $i \in \mathcal{I}$ , the PSD variable index  $j \in \mathcal{J}^{PSD}$ , the row index, the column index and the coefficient value. The number of lines should match the number stated in the header.

## ACOORD

*Description:* Input sparse coordinates (triplets) to define the scalars,  $a_{ij}$ , as used in the scalar constraints.

HEADER: One line formatted as:

|     |
|-----|
| INT |
|-----|

This is the number of coordinates to be specified.

BODY: A list of lines formatted as:

|              |
|--------------|
| INT INT REAL |
|--------------|

This indicates the scalar constraint index  $i \in \mathcal{I}$ , the scalar variable index  $j \in \mathcal{J}$  and the coefficient value. The number of lines should match the number stated in the header.

## BCOORD

*Description:* Input sparse coordinates (pairs) to define the scalars,  $b_i$ , as used in the scalar constraints.

HEADER: One line formatted as:

|     |
|-----|
| INT |
|-----|

This is the number of coordinates to be specified.

BODY: A list of lines formatted as:

|          |
|----------|
| INT REAL |
|----------|

This indicates the scalar constraint index  $i \in \mathcal{I}$  and the coefficient value. The number of lines should match the number stated in the header.

## HCOORD

*Description:* Input sparse coordinates (quintuplets) to define the symmetric matrices,  $H_{ij}$ , as used in the PSD constraints.

**HEADER:** One line formatted as:

|     |
|-----|
| INT |
|-----|

This is the number of coordinates to be specified.

**BODY:** A list of lines formatted as

|                      |
|----------------------|
| INT INT INT INT REAL |
|----------------------|

This indicates the PSD constraint index  $i \in \mathcal{I}^{PSD}$ , the scalar variable index  $j \in \mathcal{J}$ , the row index, the column index and the coefficient value. The number of lines should match the number stated in the header.

## DCOORD

*Description:* Input sparse coordinates (quadruplets) to define the symmetric matrices,  $D_i$ , as used in the PSD constraints.

**HEADER:** One line formatted as

|     |
|-----|
| INT |
|-----|

This is the number of coordinates to be specified.

**BODY:** A list of lines formatted as:

|                  |
|------------------|
| INT INT INT REAL |
|------------------|

This indicates the PSD constraint index  $i \in \mathcal{I}^{PSD}$ , the row index, the column index and the coefficient value. The number of lines should match the number stated in the header.

## CHANGE

Start of a new instance specification based on changes to the previous. Can be interpreted as the end of file when the hotstart-sequence is unsupported or undesired.

**BODY:** None

**Header:** None

## 12.4.5 CBF Format Examples

### Minimal Working Example

The conic optimization problem (12.6), has three variables in a quadratic cone - first one is integer - and an affine expression in domain 0 (equality constraint).

$$\begin{aligned} &\text{minimize} && 5.1 x_0 \\ &\text{subject to} && 6.2 x_1 + 7.3 x_2 - 8.4 \in \{0\} \\ &&& x \in \mathcal{Q}^3, x_0 \in \mathbb{Z}. \end{aligned} \tag{12.6}$$

Its formulation in the Conic Benchmark Format begins with the version of the CBF format used, to safeguard against later revisions.

```

VER
1

```

Next follows the problem structure, consisting of the objective sense, the number and domain of variables, the indices of integer variables, and the number and domain of scalar-valued affine expressions (i.e., the equality constraint).

```

OBJSENSE
MIN

VAR
3 1
Q 3

INT
1
0

CON
1 1
L= 1

```

Finally follows the problem data, consisting of the coefficients of the objective, the coefficients of the constraints, and the constant terms of the constraints. All data is specified on a sparse coordinate form.

```

OBJCOORD
1
0 5.1

ACCOORD
2
0 1 6.2
0 2 7.3

BCCOORD
1
0 -8.4

```

This concludes the example.

### Mixing Linear, Second-order and Semidefinite Cones

The conic optimization problem (12.7), has a semidefinite cone, a quadratic cone over unordered subindices, and two equality constraints.

$$\begin{aligned}
 & \text{minimize} && \left\langle \begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix}, X_1 \right\rangle + x_1 \\
 & \text{subject to} && \left\langle \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, X_1 \right\rangle + x_1 &= 1.0, \\
 & && \left\langle \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}, X_1 \right\rangle + x_0 + x_2 &= 0.5, \\
 & && x_1 \geq \sqrt{x_0^2 + x_2^2}, \\
 & && X_1 \succeq \mathbf{0}.
 \end{aligned} \tag{12.7}$$

The equality constraints are easily rewritten to the conic form,  $(g_0, g_1) \in \{0\}^2$ , by moving constants such that the right-hand-side becomes zero. The quadratic cone does not fit under the **VAR** keyword in this variable permutation. Instead, it takes a scalar constraint  $(g_2, g_3, g_4) = (x_1, x_0, x_2) \in \mathcal{Q}^3$ , with scalar

variables constructed as  $(x_0, x_1, x_2) \in \mathbb{R}^3$ . Its formulation in the CBF format is reported in the following list

```
# File written using this version of the Conic Benchmark Format:
#   | Version 1.
VER
1

# The sense of the objective is:
#   | Minimize.
OBJSENSE
MIN

# One PSD variable of this size:
#   | Three times three.
PSDVAR
1
3

# Three scalar variables in this one conic domain:
#   | Three are free.
VAR
3 1
F 3

# Five scalar constraints with affine expressions in two conic domains:
#   | Two are fixed to zero.
#   | Three are in conic quadratic domain.
CON
5 2
L= 2
Q 3

# Five coordinates in F^{obj}_j coefficients:
#   | F^{obj}[0][0,0] = 2.0
#   | F^{obj}[0][1,0] = 1.0
#   | and more...
OBJFCOORD
5
0 0 0 2.0
0 1 0 1.0
0 1 1 2.0
0 2 1 1.0
0 2 2 2.0

# One coordinate in a^{obj}_j coefficients:
#   | a^{obj}[1] = 1.0
OBJACOORD
1
1 1.0

# Nine coordinates in F_{ij} coefficients:
#   | F[0,0][0,0] = 1.0
#   | F[0,0][1,1] = 1.0
#   | and more...
FCOORD
9
0 0 0 0 1.0
0 0 1 1 1.0
0 0 2 2 1.0
1 0 0 0 1.0
1 0 1 0 1.0
1 0 2 0 1.0
```

```

1 0 1 1 1.0
1 0 2 1 1.0
1 0 2 2 1.0

# Six coordinates in a_ij coefficients:
#   | a[0,1] = 1.0
#   | a[1,0] = 1.0
#   | and more...
ACCOORD
6
0 1 1.0
1 0 1.0
1 2 1.0
2 1 1.0
3 0 1.0
4 2 1.0

# Two coordinates in b_i coefficients:
#   | b[0] = -1.0
#   | b[1] = -0.5
BCCOORD
2
0 -1.0
1 -0.5

```

### Mixing Semidefinite Variables and Linear Matrix Inequalities

The standard forms in semidefinite optimization are usually based either on semidefinite variables or linear matrix inequalities. In the CBF format, both forms are supported and can even be mixed as shown in.

$$\begin{aligned}
 & \text{minimize} && \left\langle \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, X_1 \right\rangle + x_1 + x_2 + 1 \\
 & \text{subject to} && \left\langle \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, X_1 \right\rangle - x_1 - x_2 \geq 0.0, \\
 & && x_1 \begin{bmatrix} 0 & 1 \\ 1 & 3 \end{bmatrix} + x_2 \begin{bmatrix} 3 & 1 \\ 1 & 0 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \succeq \mathbf{0}, \\
 & && X_1 \succeq \mathbf{0}.
 \end{aligned} \tag{12.8}$$

Its formulation in the CBF format is written in what follows

```

# File written using this version of the Conic Benchmark Format:
#   | Version 1.
VER
1

# The sense of the objective is:
#   | Minimize.
OBJSENSE
MIN

# One PSD variable of this size:
#   | Two times two.
PSDVAR
1
2

# Two scalar variables in this one conic domain:
#   | Two are free.
VAR
2 1

```

```

F 2

# One PSD constraint of this size:
#   | Two times two.
PSDCON
1
2

# One scalar constraint with an affine expression in this one conic domain:
#   | One is greater than or equal to zero.
CON
1 1
L+ 1

# Two coordinates in  $F^{\text{obj}}_j$  coefficients:
#   |  $F^{\text{obj}}_j[0][0,0] = 1.0$ 
#   |  $F^{\text{obj}}_j[0][1,1] = 1.0$ 
OBJFCOORD
2
0 0 0 1.0
0 1 1 1.0

# Two coordinates in  $a^{\text{obj}}_j$  coefficients:
#   |  $a^{\text{obj}}_j[0] = 1.0$ 
#   |  $a^{\text{obj}}_j[1] = 1.0$ 
OBJACOORD
2
0 1.0
1 1.0

# One coordinate in  $b^{\text{obj}}$  coefficient:
#   |  $b^{\text{obj}} = 1.0$ 
OBJBCOORD
1.0

# One coordinate in  $F_{ij}$  coefficients:
#   |  $F_{0,0}[1,0] = 1.0$ 
FCOORD
1
0 0 1 0 1.0

# Two coordinates in  $a_{ij}$  coefficients:
#   |  $a_{0,0} = -1.0$ 
#   |  $a_{0,1} = -1.0$ 
ACCOORD
2
0 0 -1.0
0 1 -1.0

# Four coordinates in  $H_{ij}$  coefficients:
#   |  $H_{0,0}[1,0] = 1.0$ 
#   |  $H_{0,0}[1,1] = 3.0$ 
#   | and more...
HCOORD
4
0 0 1 0 1.0
0 0 1 1 3.0
0 1 0 0 3.0
0 1 1 0 1.0

# Two coordinates in  $D_i$  coefficients:
#   |  $D_0[0,0] = -1.0$ 
#   |  $D_0[1,1] = -1.0$ 

```

```
DCOORD
2
0 0 0 -1.0
0 1 1 -1.0
```

### Optimization Over a Sequence of Objectives

The linear optimization problem (12.9), is defined for a sequence of objectives such that hotstarting from one to the next might be advantages.

$$\begin{aligned} & \text{maximize}_k && g_k^{obj} \\ & \text{subject to} && 50x_0 + 31 \leq 250, \\ & && 3x_0 - 2x_1 \geq -4, \\ & && x \in \mathbb{R}_+^2, \end{aligned} \tag{12.9}$$

given,

1.  $g_0^{obj} = x_0 + 0.64x_1$ .
2.  $g_1^{obj} = 1.11x_0 + 0.76x_1$ .
3.  $g_2^{obj} = 1.11x_0 + 0.85x_1$ .

Its formulation in the CBF format is reported in [Listing 12.5](#).

Listing 12.5: Problem (12.9) in CBF format.

```
# File written using this version of the Conic Benchmark Format:
#   | Version 1.
VER
1

# The sense of the objective is:
#   | Maximize.
OBJSENSE
MAX

# Two scalar variables in this one conic domain:
#   | Two are nonnegative.
VAR
2 1
L+ 2

# Two scalar constraints with affine expressions in these two conic domains:
#   | One is in the nonpositive domain.
#   | One is in the nonnegative domain.
CON
2 2
L- 1
L+ 1

# Two coordinates in a^{obj}_j coefficients:
#   | a^{obj}[0] = 1.0
#   | a^{obj}[1] = 0.64
OBJCOORD
2
0 1.0
1 0.64

# Four coordinates in a_ij coefficients:
#   | a[0,0] = 50.0
#   | a[1,0] = 3.0
```

```

#      | and more...
ACCOORD
4
0 0 50.0
1 0 3.0
0 1 31.0
1 1 -2.0

# Two coordinates in b_i coefficients:
#      | b[0] = -250.0
#      | b[1] = 4.0
BCCOORD
2
0 -250.0
1 4.0

# New problem instance defined in terms of changes.
CHANGE

# Two coordinate changes in a^{obj}_j coefficients. Now it is:
#      | a^{obj}[0] = 1.11
#      | a^{obj}[1] = 0.76
OBJACCOORD
2
0 1.11
1 0.76

# New problem instance defined in terms of changes.
CHANGE

# One coordinate change in a^{obj}_j coefficients. Now it is:
#      | a^{obj}[0] = 1.11
#      | a^{obj}[1] = 0.85
OBJACCOORD
1
1 0.85

```

## 12.5 The XML (OSiL) Format

**MOSEK** can write data in the standard OSiL xml format. For a definition of the OSiL format please see <http://www.optimizationservices.org/>.

Only linear constraints (possibly with integer variables) are supported. By default output files with the extension `.xml` are written in the OSiL format.

The parameter `MSK_IPAR_WRITE_XML_MODE` controls if the linear coefficients in the  $A$  matrix are written in row or column order.

## 12.6 The Task Format

The Task format is **MOSEK**'s native binary format. It contains a complete image of a **MOSEK** task, i.e.

- Problem data: Linear, conic quadratic, semidefinite and quadratic data
- Problem item names: Variable names, constraints names, cone names etc.
- Parameter settings
- Solutions

There are a few things to be aware of:

- The task format *does not* support General Convex problems since these are defined by arbitrary user-defined functions.
- Status of a solution read from a file will *always* be unknown.
- Parameter settings in a task file *always override* any parameters set on the command line or in a parameter file.

The format is based on the *TAR* (USTar) file format. This means that the individual pieces of data in a `.task` file can be examined by unpacking it as a *TAR* file. Please note that the inverse may not work: Creating a file using *TAR* will most probably not create a valid **MOSEK** Task file since the order of the entries is important.

## 12.7 The JSON Format

**MOSEK** provides the possibility to read/write problems in valid JSON format.

JSON (JavaScript Object Notation) is a lightweight data-interchange format. It is easy for humans to read and write. It is easy for machines to parse and generate. It is based on a subset of the JavaScript Programming Language, Standard ECMA-262 3rd Edition - December 1999. JSON is a text format that is completely language independent but uses conventions that are familiar to programmers of the C-family of languages, including C, C++, C#, Java, JavaScript, Perl, Python, and many others. These properties make JSON an ideal data-interchange language.

The official JSON website <http://www.json.org> provides plenty of information along with the format definition.

**MOSEK** defines two JSON-like formats:

- *jtask*
- *jsol*

**Warning:** Despite being text-based human-readable formats, *jtask* and *jsol* files will include no indentation and no new-lines, in order to keep the files as compact as possible. We therefore strongly advise to use JSON viewer tools to inspect *jtask* and *jsol* files.

### 12.7.1 *jtask* format

It stores a problem instance. The *jtask* format contains the same information as a *task format*.

Even though a *jtask* file is human-readable, we do not recommend users to create it by hand, but to rely on **MOSEK**.

### 12.7.2 *jsol* format

It stores a problem solution. The *jsol* format contains all solutions and information items.

### 12.7.3 A *jtask* example

In [Listing 12.6](#) we present a file in the *jtask* format that corresponds to the sample problem from `1o1.1p`. The listing has been formatted for readability.

Listing 12.6: A formatted *jtask* file for the `lo1.lp` example.

```

{
  "$schema": "http://mosek.com/json/schema#",
  "Task/INFO": {
    "taskname": "lo1",
    "numvar": 4,
    "numcon": 3,
    "numcone": 0,
    "numbarvar": 0,
    "numanz": 9,
    "numsymmat": 0,
    "mosekver": [
      8,
      0,
      0,
      9
    ]
  },
  "Task/data": {
    "var": {
      "name": [
        "x1",
        "x2",
        "x3",
        "x4"
      ],
      "bk": [
        "lo",
        "ra",
        "lo",
        "lo"
      ],
      "b1": [
        0.0,
        0.0,
        0.0,
        0.0
      ],
      "bu": [
        1e+30,
        1e+1,
        1e+30,
        1e+30
      ],
      "type": [
        "cont",
        "cont",
        "cont",
        "cont"
      ]
    },
    "con": {
      "name": [
        "c1",
        "c2",
        "c3"
      ],
      "bk": [
        "fx",
        "lo",
        "up"
      ]
    }
  }
}

```

```
    ],
    "bl": [
        3e+1,
        1.5e+1,
        -1e+30
    ],
    "bu": [
        3e+1,
        1e+30,
        2.5e+1
    ]
},
"objective": {
    "sense": "max",
    "name": "obj",
    "c": {
        "subj": [
            0,
            1,
            2,
            3
        ],
        "val": [
            3e+0,
            1e+0,
            5e+0,
            1e+0
        ]
    },
    "cfix": 0.0
},
"A": {
    "subi": [
        0,
        0,
        0,
        1,
        1,
        1,
        1,
        2,
        2
    ],
    "subj": [
        0,
        1,
        2,
        0,
        1,
        2,
        3,
        1,
        3
    ],
    "val": [
        3e+0,
        1e+0,
        2e+0,
        2e+0,
        1e+0,
        3e+0,
        1e+0,
        2e+0,
```

```

        3e+0
    ]
}
},
"Task/parameters":{
  "iparam":{
    "ANA_SOL_BASIS":"ON",
    "ANA_SOL_PRINT_VIOLATED":"OFF",
    "AUTO_SORT_A_BEFORE_OPT":"OFF",
    "AUTO_UPDATE_SOL_INFO":"OFF",
    "BASIS_SOLVE_USE_PLUS_ONE":"OFF",
    "BI_CLEAN_OPTIMIZER":"OPTIMIZER_FREE",
    "BI_IGNORE_MAX_ITER":"OFF",
    "BI_IGNORE_NUM_ERROR":"OFF",
    "BI_MAX_ITERATIONS":1000000,
    "CACHE_LICENSE":"ON",
    "CHECK_CONVEXITY":"CHECK_CONVEXITY_FULL",
    "COMPRESS_STATFILE":"ON",
    "CONCURRENT_NUM_OPTIMIZERS":2,
    "CONCURRENT_PRIORITY_DUAL_SIMPLEX":2,
    "CONCURRENT_PRIORITY_FREE_SIMPLEX":3,
    "CONCURRENT_PRIORITY_INTPNT":4,
    "CONCURRENT_PRIORITY_PRIMAL_SIMPLEX":1,
    "FEASREPAIR_OPTIMIZE":"FEASREPAIR_OPTIMIZE_NONE",
    "INFEAS_GENERIC_NAMES":"OFF",
    "INFEAS_PREFER_PRIMAL":"ON",
    "INFEAS_REPORT_AUTO":"OFF",
    "INFEAS_REPORT_LEVEL":1,
    "INTPNT_BASIS":"BI_ALWAYS",
    "INTPNT_DIFF_STEP":"ON",
    "INTPNT_FACTOR_DEBUG_LVL":0,
    "INTPNT_FACTOR_METHOD":0,
    "INTPNT_HOTSTART":"INTPNT_HOTSTART_NONE",
    "INTPNT_MAX_ITERATIONS":400,
    "INTPNT_MAX_NUM_COR":-1,
    "INTPNT_MAX_NUM_REFINEMENT_STEPS":-1,
    "INTPNT_OFF_COL_TRH":40,
    "INTPNT_ORDER_METHOD":"ORDER_METHOD_FREE",
    "INTPNT_REGULARIZATION_USE":"ON",
    "INTPNT_SCALING":"SCALING_FREE",
    "INTPNT_SOLVE_FORM":"SOLVE_FREE",
    "INTPNT_STARTING_POINT":"STARTING_POINT_FREE",
    "LIC_TRH_EXPIRY_WRN":7,
    "LICENSE_DEBUG":"OFF",
    "LICENSE_PAUSE_TIME":0,
    "LICENSE_SUPPRESS_EXPIRE_WRNS":"OFF",
    "LICENSE_WAIT":"OFF",
    "LOG":10,
    "LOG_ANA_PRO":1,
    "LOG_BI":4,
    "LOG_BI_FREQ":2500,
    "LOG_CHECK_CONVEXITY":0,
    "LOG_CONCURRENT":1,
    "LOG_CUT_SECOND_OPT":1,
    "LOG_EXPAND":0,
    "LOG_FACTOR":1,
    "LOG_FEAS_REPAIR":1,
    "LOG_FILE":1,
    "LOG_HEAD":1,
    "LOG_INFEAS_ANA":1,
    "LOG_INTPNT":4,
    "LOG_MIO":4,
    "LOG_MIO_FREQ":1000,

```

```

"LOG_OPTIMIZER":1,
"LOG_ORDER":1,
"LOG_PRESOLVE":1,
"LOG_RESPONSE":0,
"LOG_SENSITIVITY":1,
"LOG_SENSITIVITY_OPT":0,
"LOG_SIM":4,
"LOG_SIM_FREQ":1000,
"LOG_SIM_MINOR":1,
"LOG_STORAGE":1,
"MAX_NUM_WARNINGS":10,
"MIO_BRANCH_DIR":"BRANCH_DIR_FREE",
"MIO_CONSTRUCT_SOL":"OFF",
"MIO_CUT_CLIQUE":"ON",
"MIO_CUT_CMIR":"ON",
"MIO_CUT_GMI":"ON",
"MIO_CUT_KNAPSACK_COVER":"OFF",
"MIO_HEURISTIC_LEVEL":-1,
"MIO_MAX_NUM_BRANCHES":-1,
"MIO_MAX_NUM_RELAXS":-1,
"MIO_MAX_NUM_SOLUTIONS":-1,
"MIO_MODE":"MIO_MODE_SATISFIED",
"MIO_MT_USER_CB":"ON",
"MIO_NODE_OPTIMIZER":"OPTIMIZER_FREE",
"MIO_NODE_SELECTION":"MIO_NODE_SELECTION_FREE",
"MIO_PERSPECTIVE_REFORMULATE":"ON",
"MIO_PROBING_LEVEL":-1,
"MIO_RINS_MAX_NODES":-1,
"MIO_ROOT_OPTIMIZER":"OPTIMIZER_FREE",
"MIO_ROOT_REPEAT_PRESOLVE_LEVEL":-1,
"MT_SPINCOUNT":0,
"NUM_THREADS":0,
"OPF_MAX_TERMS_PER_LINE":5,
"OPF_WRITE_HEADER":"ON",
"OPF_WRITE_HINTS":"ON",
"OPF_WRITE_PARAMETERS":"OFF",
"OPF_WRITE_PROBLEM":"ON",
"OPF_WRITE_SOL_BAS":"ON",
"OPF_WRITE_SOL_ITG":"ON",
"OPF_WRITE_SOL_ITR":"ON",
"OPF_WRITE_SOLUTIONS":"OFF",
"OPTIMIZER":"OPTIMIZER_FREE",
"PARAM_READ_CASE_NAME":"ON",
"PARAM_READ_IGN_ERROR":"OFF",
"PRESOLVE_ELIMINATOR_MAX_FILL":-1,
"PRESOLVE_ELIMINATOR_MAX_NUM_TRIES":-1,
"PRESOLVE_LEVEL":-1,
"PRESOLVE_LINDEP_ABS_WORK_TRH":100,
"PRESOLVE_LINDEP_REL_WORK_TRH":100,
"PRESOLVE_LINDEP_USE":"ON",
"PRESOLVE_MAX_NUM_REDUCATIONS":-1,
"PRESOLVE_USE":"PRESOLVE_MODE_FREE",
"PRIMAL_REPAIR_OPTIMIZER":"OPTIMIZER_FREE",
"QO_SEPARABLE_REFORMULATION":"OFF",
"READ_DATA_COMPRESSED":"COMPRESS_FREE",
"READ_DATA_FORMAT":"DATA_FORMAT_EXTENSION",
"READ_DEBUG":"OFF",
"READ_KEEP_FREE_CON":"OFF",
"READ_LP_DROP_NEW_VARS_IN_BOU":"OFF",
"READ_LP_QUOTED_NAMES":"ON",
"READ_MPS_FORMAT":"MPS_FORMAT_FREE",
"READ_MPS_WIDTH":1024,
"READ_TASK_IGNORE_PARAM":"OFF",

```

```

"SENSITIVITY_ALL": "OFF",
"SENSITIVITY_OPTIMIZER": "OPTIMIZER_FREE_SIMPLEX",
"SENSITIVITY_TYPE": "SENSITIVITY_TYPE_BASIS",
"SIM_BASIS_FACTOR_USE": "ON",
"SIM_DEGEN": "SIM_DEGEN_FREE",
"SIM_DUAL_CRASH": 90,
"SIM_DUAL_PHASEONE_METHOD": 0,
"SIM_DUAL_RESTRICT_SELECTION": 50,
"SIM_DUAL_SELECTION": "SIM_SELECTION_FREE",
"SIM_EXPLOIT_DUPVEC": "SIM_EXPLOIT_DUPVEC_OFF",
"SIM_HOTSTART": "SIM_HOTSTART_FREE",
"SIM_HOTSTART_LU": "ON",
"SIM_INTEGER": 0,
"SIM_MAX_ITERATIONS": 10000000,
"SIM_MAX_NUM_SETBACKS": 250,
"SIM_NON_SINGULAR": "ON",
"SIM_PRIMAL_CRASH": 90,
"SIM_PRIMAL_PHASEONE_METHOD": 0,
"SIM_PRIMAL_RESTRICT_SELECTION": 50,
"SIM_PRIMAL_SELECTION": "SIM_SELECTION_FREE",
"SIM_REFACTOR_FREQ": 0,
"SIM_REFORMULATION": "SIM_REFORMULATION_OFF",
"SIM_SAVE_LU": "OFF",
"SIM_SCALING": "SCALING_FREE",
"SIM_SCALING_METHOD": "SCALING_METHOD_POW2",
"SIM_SOLVE_FORM": "SOLVE_FREE",
"SIM_STABILITY_PRIORITY": 50,
"SIM_SWITCH_OPTIMIZER": "OFF",
"SOL_FILTER_KEEP_BASIC": "OFF",
"SOL_FILTER_KEEP_RANGED": "OFF",
"SOL_READ_NAME_WIDTH": -1,
"SOL_READ_WIDTH": 1024,
"SOLUTION_CALLBACK": "OFF",
"TIMING_LEVEL": 1,
"WRITE_BAS_CONSTRAINTS": "ON",
"WRITE_BAS_HEAD": "ON",
"WRITE_BAS_VARIABLES": "ON",
"WRITE_DATA_COMPRESSED": 0,
"WRITE_DATA_FORMAT": "DATA_FORMAT_EXTENSION",
"WRITE_DATA_PARAM": "OFF",
"WRITE_FREE_CON": "OFF",
"WRITE_GENERIC_NAMES": "OFF",
"WRITE_GENERIC_NAMES_IO": 1,
"WRITE_IGNORE_INCOMPATIBLE_CONIC_ITEMS": "OFF",
"WRITE_IGNORE_INCOMPATIBLE_ITEMS": "OFF",
"WRITE_IGNORE_INCOMPATIBLE_NL_ITEMS": "OFF",
"WRITE_IGNORE_INCOMPATIBLE_PSD_ITEMS": "OFF",
"WRITE_INT_CONSTRAINTS": "ON",
"WRITE_INT_HEAD": "ON",
"WRITE_INT_VARIABLES": "ON",
"WRITE_LP_FULL_OBJ": "ON",
"WRITE_LP_LINE_WIDTH": 80,
"WRITE_LP_QUOTED_NAMES": "ON",
"WRITE_LP_STRICT_FORMAT": "OFF",
"WRITE_LP_TERMS_PER_LINE": 10,
"WRITE_MPS_FORMAT": "MPS_FORMAT_FREE",
"WRITE_MPS_INT": "ON",
"WRITE_PRECISION": 15,
"WRITE_SOL_BARVARIABLES": "ON",
"WRITE_SOL_CONSTRAINTS": "ON",
"WRITE_SOL_HEAD": "ON",
"WRITE_SOL_IGNORE_INVALID_NAMES": "OFF",
"WRITE_SOL_VARIABLES": "ON",

```

```

    "WRITE_TASK_INC_SOL": "ON",
    "WRITE_XML_MODE": "WRITE_XML_MODE_ROW"
},
"dparam": {
    "ANA_SOL_INFEAS_TOL": 1e-6,
    "BASIS_REL_TOL_S": 1e-12,
    "BASIS_TOL_S": 1e-6,
    "BASIS_TOL_X": 1e-6,
    "CHECK_CONVEXITY_REL_TOL": 1e-10,
    "DATA_TOL_AIJ": 1e-12,
    "DATA_TOL_AIJ_HUGE": 1e+20,
    "DATA_TOL_AIJ_LARGE": 1e+10,
    "DATA_TOL_BOUND_INF": 1e+16,
    "DATA_TOL_BOUND_WRN": 1e+8,
    "DATA_TOL_C_HUGE": 1e+16,
    "DATA_TOL_CJ_LARGE": 1e+8,
    "DATA_TOL_QIJ": 1e-16,
    "DATA_TOL_X": 1e-8,
    "FEASREPAIR_TOL": 1e-10,
    "INTPNT_CO_TOL_DFEAS": 1e-8,
    "INTPNT_CO_TOL_INFEAS": 1e-10,
    "INTPNT_CO_TOL_MU_RED": 1e-8,
    "INTPNT_CO_TOL_NEAR_REL": 1e+3,
    "INTPNT_CO_TOL_PFEAS": 1e-8,
    "INTPNT_CO_TOL_REL_GAP": 1e-7,
    "INTPNT_NL_MERIT_BAL": 1e-4,
    "INTPNT_NL_TOL_DFEAS": 1e-8,
    "INTPNT_NL_TOL_MU_RED": 1e-12,
    "INTPNT_NL_TOL_NEAR_REL": 1e+3,
    "INTPNT_NL_TOL_PFEAS": 1e-8,
    "INTPNT_NL_TOL_REL_GAP": 1e-6,
    "INTPNT_NL_TOL_REL_STEP": 9.95e-1,
    "INTPNT_QO_TOL_DFEAS": 1e-8,
    "INTPNT_QO_TOL_INFEAS": 1e-10,
    "INTPNT_QO_TOL_MU_RED": 1e-8,
    "INTPNT_QO_TOL_NEAR_REL": 1e+3,
    "INTPNT_QO_TOL_PFEAS": 1e-8,
    "INTPNT_QO_TOL_REL_GAP": 1e-8,
    "INTPNT_TOL_DFEAS": 1e-8,
    "INTPNT_TOL_DSAFE": 1e+0,
    "INTPNT_TOL_INFEAS": 1e-10,
    "INTPNT_TOL_MU_RED": 1e-16,
    "INTPNT_TOL_PATH": 1e-8,
    "INTPNT_TOL_PFEAS": 1e-8,
    "INTPNT_TOL_PSAFE": 1e+0,
    "INTPNT_TOL_REL_GAP": 1e-8,
    "INTPNT_TOL_REL_STEP": 9.999e-1,
    "INTPNT_TOL_STEP_SIZE": 1e-6,
    "LOWER_OBJ_CUT": -1e+30,
    "LOWER_OBJ_CUT_FINITE_TRH": -5e+29,
    "MIO_DISABLE_TERM_TIME": -1e+0,
    "MIO_MAX_TIME": -1e+0,
    "MIO_MAX_TIME_APRX_OPT": 6e+1,
    "MIO_NEAR_TOL_ABS_GAP": 0.0,
    "MIO_NEAR_TOL_REL_GAP": 1e-3,
    "MIO_REL_GAP_CONST": 1e-10,
    "MIO_TOL_ABS_GAP": 0.0,
    "MIO_TOL_ABS_RELAX_INT": 1e-5,
    "MIO_TOL_FEAS": 1e-6,
    "MIO_TOL_REL_DUAL_BOUND_IMPROVEMENT": 0.0,
    "MIO_TOL_REL_GAP": 1e-4,
    "MIO_TOL_X": 1e-6,
    "OPTIMIZER_MAX_TIME": -1e+0,

```

```

    "PRESOLVE_TOL_ABS_LINDEP":1e-6,
    "PRESOLVE_TOL_AIJ":1e-12,
    "PRESOLVE_TOL_REL_LINDEP":1e-10,
    "PRESOLVE_TOL_S":1e-8,
    "PRESOLVE_TOL_X":1e-8,
    "QCQO_REFORMULATE_REL_DROP_TOL":1e-15,
    "SEMIDEFINITE_TOL_APPROX":1e-10,
    "SIM_LU_TOL_REL_PIV":1e-2,
    "SIMPLEX_ABS_TOL_PIV":1e-7,
    "UPPER_OBJ_CUT":1e+30,
    "UPPER_OBJ_CUT_FINITE_TRH":5e+29
  },
  "sparam":{
    "BAS_SOL_FILE_NAME": "",
    "DATA_FILE_NAME": "examples/tools/data/lo1.mps",
    "DEBUG_FILE_NAME": "",
    "INT_SOL_FILE_NAME": "",
    "ITR_SOL_FILE_NAME": "",
    "MIO_DEBUG_STRING": "",
    "PARAM_COMMENT_SIGN": "%%",
    "PARAM_READ_FILE_NAME": "",
    "PARAM_WRITE_FILE_NAME": "",
    "READ_MPS_BOU_NAME": "",
    "READ_MPS_OBJ_NAME": "",
    "READ_MPS_RAN_NAME": "",
    "READ_MPS_RHS_NAME": "",
    "SENSITIVITY_FILE_NAME": "",
    "SENSITIVITY_RES_FILE_NAME": "",
    "SOL_FILTER_XC_LOW": "",
    "SOL_FILTER_XC_UPR": "",
    "SOL_FILTER_XX_LOW": "",
    "SOL_FILTER_XX_UPR": "",
    "STAT_FILE_NAME": "",
    "STAT_KEY": "",
    "STAT_NAME": "",
    "WRITE_LP_GEN_VAR_NAME": "XMSKGEN"
  }
}

```

## 12.8 The Solution File Format

MOSEK provides several solution files depending on the problem type and the optimizer used:

- *basis solution file* (extension `.bas`) if the problem is optimized using the simplex optimizer or basis identification is performed,
- *interior solution file* (extension `.sol`) if a problem is optimized using the interior-point optimizer and no basis identification is required,
- *integer solution file* (extension `.int`) if the problem contains integer constrained variables.

All solution files have the format:

|                  |  |
|------------------|--|
| NAME             | : <problem name>   |
| PROBLEM STATUS   | : <status of the problem>                                |
| SOLUTION STATUS  | : <status of the solution>                               |
| OBJECTIVE NAME   | : <name of the objective function>                       |
| PRIMAL OBJECTIVE | : <primal objective value corresponding to the solution> |
| DUAL OBJECTIVE   | : <dual objective value corresponding to the solution>   |
| CONSTRAINTS      |  |

| INDEX     | NAME   | AT | ACTIVITY  | LOWER LIMIT | UPPER LIMIT | DUAL LOWER | DUAL UPPER |
|-----------|--------|----|-----------|-------------|-------------|------------|------------|
| ?         | <name> | ?? | <a value> | <a value>   | <a value>   | <a value>  | <a value>  |
| VARIABLES |        |    |           |             |             |            |            |
| INDEX     | NAME   | AT | ACTIVITY  | LOWER LIMIT | UPPER LIMIT | DUAL LOWER | DUAL UPPER |
| ↔DUAL     |        |    |           |             |             |            |            |
| ?         | <name> | ?? | <a value> | <a value>   | <a value>   | <a value>  | <a value>  |

In the example the fields ? and <> will be filled with problem and solution specific information. As can be observed a solution report consists of three sections, i.e.

- **HEADER** In this section, first the name of the problem is listed and afterwards the problem and solution status are shown. Next the primal and dual objective values are displayed.
- **CONSTRAINTS** For each constraint  $i$  of the form

$$l_i^c \leq \sum_{j=1}^n a_{ij}x_j \leq u_i^c, \quad (12.10)$$

the following information is listed:

- **INDEX:** A sequential index assigned to the constraint by **MOSEK**
- **NAME:** The name of the constraint assigned by the user.
- **AT:** The status of the constraint. In Table 12.4 the possible values of the status keys and their interpretation are shown.

Table 12.4: Status keys.

| Status key | Interpretation  |
|------------|---|
| UN         | Unknown status  |
| BS         | Is basic  |
| SB         | Is superbasic   |
| LL         | Is at the lower limit (bound)                                       |
| UL         | Is at the upper limit (bound)                                       |
| EQ         | Lower limit is identical to upper limit                             |
| **         | Is infeasible i.e. the lower limit is greater than the upper limit. |

- **ACTIVITY:** the quantity  $\sum_{j=1}^n a_{ij}x_j^*$ , where  $x^*$  is the value of the primal solution.
- **LOWER LIMIT:** the quantity  $l_i^c$  (see (12.10).)
- **UPPER LIMIT:** the quantity  $u_i^c$  (see (12.10).)
- **DUAL LOWER:** the dual multiplier corresponding to the lower limit on the constraint.
- **DUAL UPPER:** the dual multiplier corresponding to the upper limit on the constraint.
- **VARIABLES** The last section of the solution report lists information about the variables. This information has a similar interpretation as for the constraints. However, the column with the header **CONIC DUAL** is included for problems having one or more conic constraints. This column shows the dual variables corresponding to the conic constraints.

**Example:** lo1.sol

In Listing 12.7 we show the solution file for the lo1.opf problem.

Listing 12.7: An example of .sol file.

|                 |                            |
|-----------------|----------------------------|
| NAME            | :                          |
| PROBLEM STATUS  | : PRIMAL_AND_DUAL_FEASIBLE |
| SOLUTION STATUS | : OPTIMAL                  |
| OBJECTIVE NAME  | : obj                      |

```

PRIMAL OBJECTIVE      : 8.33333333e+01
DUAL OBJECTIVE        : 8.33333332e+01

CONSTRAINTS
INDEX      NAME          AT ACTIVITY          LOWER LIMIT      UPPER LIMIT      U
↪DUAL LOWER          DUAL UPPER
0          c1            EQ 3.00000000000000e+01  3.00000000e+01   3.00000000e+01   -0.
↪00000000000000e+00  -2.49999999741654e+00
1          c2            SB 5.33333333049188e+01  1.50000000e+01   NONE              2.
↪09157603759397e-10  -0.00000000000000e+00
2          c3            UL 2.49999999842049e+01  NONE              2.50000000e+01   -0.
↪00000000000000e+00  -3.33333332895110e-01

VARIABLES
INDEX      NAME          AT ACTIVITY          LOWER LIMIT      UPPER LIMIT      U
↪DUAL LOWER          DUAL UPPER
0          x1            LL 1.67020427073508e-09  0.00000000e+00   NONE              -4.
↪49999999528055e+00  -0.00000000000000e+00
1          x2            LL 2.93510446280504e-09  0.00000000e+00   1.00000000e+01   -2.
↪16666666494916e+00  6.20863861687316e-10
2          x3            SB 1.49999999899425e+01  0.00000000e+00   NONE              -8.
↪79123177454657e-10  -0.00000000000000e+00
3          x4            SB 8.33333332273116e+00  0.00000000e+00   NONE              -1.
↪69795978899185e-09  -0.00000000000000e+00

```



## BIBLIOGRAPHY

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- certdir=/etc/Mosek/server/cert
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